# The solution to a second order linear ordinary differential equation with a non-homogeneous term that is a measure ${ }^{\dagger}$ 

Timothy C. Johnson ${ }^{\ddagger}$ and Mihail Zervos ${ }^{\S}$<br>(???)

We consider the solvability of the ordinary differential equation (ODE)

$$
\begin{equation*}
\frac{1}{2} \sigma^{2} w^{\prime \prime}+b w^{\prime}-r w+h=0 \tag{1}
\end{equation*}
$$

inside an interval $\mathcal{J} \equiv] \alpha, \beta[$, where $\sigma, b, r$ are given functions and $h$ is a locally finite measure. This ODE is associated with the Hamilton-Jacobi-Bellman equations arising in the study of a wide range of stochastic optimisation problems. These problems are motivated by numerous applications and include optimal stopping, singular stochastic control and impulse stochastic control models in which the state process is given by a one-dimensional Itô diffusion. Under general conditions, we derive both analytic and probabilistic expressions for the solution to (1) that is required by the analysis of the relevant stochastic control models. We also establish a number of properties that are important for applications.

Keywords: second-order linear ordinary differential equations, measure-valued inhomogeneity, additive functionals, local time, optimal stopping, singular control, impulse control

2000 Mathematics Subject Classifications: 34A30, 60J55, 49J15, 34H05, 62L15

## 1 Introduction

Let $\mathcal{J}$ be an open interval with left endpoint $\alpha \geq-\infty$ and right endpoint $\beta \leq \infty$, and let $\mathcal{B}(\mathcal{J})$ denote the Borel $\sigma$-algebra on $\mathcal{J}$. It is well known that a function $g: \mathcal{J} \rightarrow \mathbb{R}$ is the difference of two convex functions if and only if its second distributional derivative is a locally integrable measure on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$. Given such a function $g$, we denote by $g_{-}^{\prime}$ its left-hand first derivative, which

[^0]is a function of finite variation, and we let
\[

$$
\begin{equation*}
g^{\prime \prime}(d x)=g_{\mathrm{ac}}^{\prime \prime}(x) d x+g_{\mathrm{s}}^{\prime \prime}(d x) \tag{2}
\end{equation*}
$$

\]

be the Lebesgue decomposition of the second distributional derivative $g^{\prime \prime}(d x)$ into the measure $g_{\mathrm{ac}}^{\prime \prime}(x) d x$ that is absolutely continuous with respect to the Lebesgue measure and the measure $g_{\mathrm{s}}^{\prime \prime}(d x)$ that is mutually singular with the Lebesgue measure. Similarly, given a locally integrable measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$, we denote by

$$
\begin{equation*}
h(d x)=h_{\mathrm{ac}}(x) d x+h_{\mathrm{s}}(d x) \tag{3}
\end{equation*}
$$

its Lebesgue decomposition.
Now, let $\sigma, b, r: \mathcal{J} \rightarrow \mathbb{R}$ be given Borel-measurable functions with $\sigma>0$, and let $h$ be a measure on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$. We aim at establishing general conditions on this data, under which there exists a solution $w$ to the ODE (1) in the sense of distributions. In particular, we consider the solvability of (1) in the following sense.

Definition 1.1 A function $w: \mathcal{J} \rightarrow \mathbb{R}$ is a solution to the $\operatorname{ODE}(1)$ if it is the difference of two convex functions and $\mathcal{L} w=-h$, where $\mathcal{L} w$ is the measure on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ defined by

$$
\begin{equation*}
\mathcal{L} w(d x)=\frac{1}{2} \sigma^{2}(x) w^{\prime \prime}(d x)+b(x) w_{-}^{\prime}(x) d x-r(x) w(x) d x \tag{4}
\end{equation*}
$$

Equivalently, a function $w: \mathcal{J} \rightarrow \mathbb{R}$ is a solution to the ODE (1) if it is the difference of two convex functions,

$$
\begin{equation*}
\frac{1}{2} \sigma^{2}(x) w_{\mathrm{ac}}^{\prime \prime}(x)+b(x) w_{-}^{\prime}(x)-r(x) w(x)+h_{\mathrm{ac}}(x)=0 \tag{5}
\end{equation*}
$$

Lebesgue-a.e. in $\mathcal{J}$, and

$$
\begin{equation*}
w_{\mathrm{s}}^{\prime \prime}(d x)=-\frac{2}{\sigma^{2}(x)} h_{\mathrm{s}}(d x) \tag{6}
\end{equation*}
$$

The ODE (1) arises in the study of several stochastic optimisation models with an expected discounted performance criterion over an infinite time horizon and with state process dynamics related to the one-dimensional Itô diffusion

$$
\begin{equation*}
d X_{t}=b\left(X_{t}\right) d t+\sigma\left(X_{t}\right) d W_{t}, \quad X_{0}=x \in \mathcal{J} \tag{7}
\end{equation*}
$$

where $W$ is a standard one-dimensional Brownian motion. Such models have been motivated by numerous applications and arise in optimal stopping, singular stochastic control and impulse stochastic control; Alvarez [1-4], Beibel and Lerche [5], Beneš, Shepp and Witsenhausen [6], Davis and Zervos [9], Dayanik and Karatzas [10], Duckworth and Zervos [11], Guo and Shepp [13], Harrison and Taksar [14], Harrison and Taylor [15], Jacka [17, 18], Karatzas [19], Karatzas and Ocone [20], Karatzas, Ocone, Wang and Zervos [21], Karatzas and Sudderth [23], Ma [25], Øksendal [27,28], Salminen [31], Shreve, Lehoczky and Gavers [34], Shiryayev [32], Shiryaev and Peskir [33], and the references therein provide a highly incomplete list of such stochastic control problems. In the models studied in these references by means of dynamic programming and variational inequalities, special cases of the ODE (1) are considered. In these cases, the measure $h$, which is closely related to the associated payoff functionals, is assumed to be absolutely continuous with respect to the Lebesgue measure.

Apart from their independent theoretical interest, the results that we establish here are important for addressing stochastic control problems in which $h$ is not absolutely continuous. Such a situation arises in the optimal stopping problem that aims at maximising the performance criterion

$$
\begin{equation*}
\mathbb{E}_{x}\left[\exp \left(-\int_{0}^{\tau} r\left(X_{s}\right) d s\right) g\left(X_{\tau}\right) \mathbf{1}_{\{\tau<\infty\}}\right] \tag{8}
\end{equation*}
$$

over all stopping times $\tau$. If $g$ is $C^{1}$ with absolutely continuous first derivative and satisfies appropriate technical conditions, then an application of Itô's formula implies that this performance criterion is equal to

$$
\begin{equation*}
g(x)+\mathbb{E}_{x}\left[\int_{0}^{\tau} \exp \left(-\int_{0}^{t} r\left(X_{s}\right) d s\right) \tilde{\mathcal{L}} g\left(X_{t}\right) d t\right] \tag{9}
\end{equation*}
$$

where

$$
\tilde{\mathcal{L}} g=\frac{1}{2} \sigma^{2} g^{\prime \prime}+b g^{\prime}-r g .
$$

It follows that the problem of maximising (8) over $\tau$ is equivalent to maximising (9) over all stopping times $\tau$. With regard to standard theory of optimal stopping, the Hamilton-Jacobi-Bellman (HJB) equation of this problem takes the form of the variational inequality

$$
\max \left\{\frac{1}{2} \sigma^{2} w^{\prime \prime}+b w^{\prime}-r w+\tilde{\mathcal{L}} g,-w\right\}=0
$$

Thus, one is faced with the solvability of (1).
This reformulation is not intended solely for providing a justification for this paper. Indeed, it turns out that deriving explicit solutions to special cases of this optimal stopping problem depends crucially on the properties of $\tilde{\mathcal{L}} g$ (see Alvarez [4, Corollary 4.2]). This situation is not confined to optimal stopping: $\emptyset$ ksendal [27,28] used similar ideas to reformulate a number of singular control models to equivalent ones involving the function $\tilde{\mathcal{L}} g$ that he then solved. At this point, we are faced with the issue of extending these analyses to the cases that arise when $g$ does not possess the regularity assumed above and $\tilde{\mathcal{L}} g$ is a measure as in (4) rather than a function. An example where such a generalisation becomes relevant is provided by the perpetual American butterfly spread option, the payoff function $g$ of which is given by

$$
g(x)=\left(x-K_{1}\right)^{+}-2\left(x-K_{2}\right)^{+}+\left(x-K_{3}\right)^{+},
$$

for some constants $K_{1}<K_{2}<K_{3}$.
The solvability of the ODE (1) when $h$ is a function satisfying appropriate integrability conditions has been extensively studied under general assumptions, and has been documented in several references, including Feller [12], Breiman [8], Mandl [26], Itô and McKean [16], Karlin and Taylor [24], Rogers and Williams [30], and Borodin and Salminen [7]. Our analysis here relies on the use of Itô calculus. For this reason, we restrict our attention to Itô diffusions such as the one given by (7) rather than more general diffusions, which may not be semimartingales. Also, we assume that the underlying diffusion $X$ is non-explosive. Our results can be generalised with little effort to account for the cases that arise if the boundary points $\alpha, \beta$ are attainable (whether absorbing or reflecting), provided that we stay within a semimartingale framework. We have decided against addressing such a generalisation, partly because this would significantly complicate the exposition of our results and partly because most applications assume that the underlying state process is non-explosive.
At this point, it is of interest to make a comment on the relation of our results with the theory of additive functionals of Markov processes. To fix ideas, suppose that $X$ is a Brownian motion and that $r(x) \equiv \lambda$, for some constant $\lambda>0$. In this case, if $D$ is a continuous additive functional of $X$, then $D=A^{h}$ for some measure $h$, where $A^{h}$ is the process defined by (54) in Section 4 (see Revuz and Yor [29, Theorem X.2.9]). Furthermore, the $\lambda$ potential $U_{D}^{\lambda}$ of $D$ admits the expression

$$
\begin{equation*}
U_{D}^{\lambda}(x):=\mathbb{E}_{x}\left[\int_{0}^{\infty} e^{-\lambda t} d D_{t}\right]=\int_{\mathcal{J}} u^{\lambda}(x, s) \nu_{D}(d s), \tag{10}
\end{equation*}
$$

where $u^{\lambda}$ is the Green function defined by $u^{\lambda}(x, s)=(\sqrt{2 \lambda})^{-1} \exp (-\sqrt{2 \lambda}|x-s|)$
and $\nu_{D}$ is the Revuz measure of $D$ (see Revuz and Yor [29, Theorem X.2.8]). Such representations can be extended to more general linear Markov processes including the ones that we consider here. One contribution of this paper is to provide an explicit expression for the right-hand side of (10) and to show that this satisfies the ODE (1) when $X$ is an Itô diffusion such as the one given by (7).

The paper is organised as follows. In Section 2, we consider the Itô diffusion (7), we develop our assumptions and we review a number of well-known results on which our analysis depends. In Section 3, we establish an analytic expression for a special solution to (1), and we prove several analytic properties that this solution has. In Section 4, we establish a probabilistic expression for this special solution, and we show that it satisfies Dynkin's formula as well as the transversality condition, which are properties that are most important for the analysis of specific applications.

## 2 The associated Itô diffusion, assumptions and spaces of measures

We consider the Itô diffusion given by (7) and we make the following assumption.
Assumption 2.1 The functions $b, \sigma: \mathcal{J} \rightarrow \mathbb{R}$ are Borel-measurable and satisfy the following conditions:

$$
\begin{equation*}
\left.\sigma^{2}(x)>0, \quad \text { for all } x \in \mathcal{J} \equiv\right] \alpha, \beta[, \tag{11}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{\bar{\alpha}}^{\bar{\beta}} \frac{1+|b(s)|}{\sigma^{2}(s)} d s<\infty, \quad \text { for all } \alpha<\bar{\alpha}<\bar{\beta}<\beta . \tag{12}
\end{equation*}
$$

Also, $\sigma^{2}$ is locally bounded, i.e.,

$$
\begin{equation*}
\sup _{s \in[\bar{\alpha}, \bar{\beta}]} \sigma^{2}(s)<\infty, \quad \text { for all } \alpha<\bar{\alpha}<\bar{\beta}<\beta . \tag{13}
\end{equation*}
$$

Assumptions (11) and (12) are the non-degeneracy condition (ND) ${ }^{\prime}$ and the local integrability condition (LI) ${ }^{\prime}$ in Karatzas and Shreve [22, Section 5.5.C], respectively. These conditions are sufficient for the SDE (7) to have a weak solution that is unique in the sense of probability law up to a possible explosion time. In particular, given $c \in \mathcal{J}$, the scale function $p$ and the speed measure
$m$, given by

$$
\begin{gather*}
p(x)=\int_{c}^{x} \exp \left(-2 \int_{c}^{s} \frac{b(u)}{\sigma^{2}(u)} d u\right) d s, \quad \text { for } x \in \mathcal{J},  \tag{14}\\
m(d x)=\frac{2}{\sigma^{2}(x) p^{\prime}(x)} d x \tag{15}
\end{gather*}
$$

are well-defined. For future reference, we note that $p$ satisfies the ODE

$$
\begin{equation*}
\frac{1}{2} \sigma^{2}(x) p^{\prime \prime}(x)+b(x) p^{\prime}(x)=0 \tag{16}
\end{equation*}
$$

We also assume that the solution to (7) is non-explosive, i.e., the hitting time of the boundary $\{\alpha, \beta\}$ of the interval $\mathcal{J}$ is infinite with probability 1 . With reference to the so-called Feller's test for explosions (see Theorem 5.5.29 in Karatzas and Shreve [22]), we therefore make the following assumption.
Assumption 2.2 If we define

$$
l(x)=\int_{c}^{x}[p(x)-p(y)] m(d y), \quad \text { for } x \in \mathcal{J},
$$

then $\lim _{x \downarrow \alpha} l(x)=\lim _{x \uparrow \beta} l(x)=\infty$.
To proceed further, we consider a weak solution $\mathbb{S}_{x}=\left(\Omega, \mathcal{F}, \mathcal{F}_{t}, \mathbb{P}_{x}, W, X\right)$ to the $\operatorname{SDE}(7)$. Given a point $a \in \mathcal{J}$, we denote by $T_{a}$ the first hitting time of the set $\{a\}$, i.e.,

$$
\begin{equation*}
T_{a}=\inf \left\{t \geq 0 \mid X_{t}=a\right\} \tag{17}
\end{equation*}
$$

Our assumptions imply that

$$
\mathbb{P}_{x}\left(T_{a}<\infty\right)>0, \quad \text { for all } x, a \in \mathcal{J}
$$

i.e., the diffusion $X$ is regular. Also, we define

$$
\Lambda_{t}=\int_{0}^{t} r\left(X_{s}\right) d s, \quad \text { for } t \geq 0
$$

The process $\Lambda$ is well-defined thanks to the following assumption that we make.
Assumption 2.3 The function $r: \mathcal{J} \rightarrow] 0, \infty[$ is Borel-measurable and locally bounded. Also, there exists $r_{0}>0$ such that $r(x) \geq r_{0}$, for all $x \in \mathcal{J}$.

In the presence of Assumptions 2.1, 2.2 and 2.3, the general solution to the homogeneous ODE

$$
\begin{equation*}
\frac{1}{2} \sigma^{2}(x) w^{\prime \prime}(x)+b(x) w^{\prime}(x)-r(x) w(x)=0, \quad \text { for } x \in \mathcal{J} \tag{18}
\end{equation*}
$$

exists in the classical sense and is given by

$$
\begin{equation*}
w(x)=A \phi(x)+B \psi(x) \tag{19}
\end{equation*}
$$

for some constants $A, B \in \mathbb{R}$. The functions $\phi$ and $\psi$ are $C^{1}$, their first derivatives are absolutely continuous functions,

$$
\begin{array}{ll}
0<\phi(x) & \text { and } \quad \phi^{\prime}(x)<0, \\
0<\psi(x) & \text { for all } x \in \mathcal{J}  \tag{21}\\
\text { and } \quad \psi^{\prime}(x)>0, & \text { for all } x \in \mathcal{J}
\end{array}
$$

and

$$
\begin{equation*}
\lim _{x \downarrow \alpha} \phi(x)=\lim _{x \uparrow \beta} \psi(x)=\infty . \tag{22}
\end{equation*}
$$

These functions are unique, modulo multiplicative constants. Also, they satisfy

$$
\begin{equation*}
\phi(x)=\phi(y) \mathbb{E}_{x}\left[e^{-\Lambda_{T_{y}}}\right], \text { for all } y<x \tag{23}
\end{equation*}
$$

and

$$
\begin{equation*}
\psi(x)=\psi(y) \mathbb{E}_{x}\left[e^{-\Lambda_{T_{y}}}\right], \text { for all } x<y \tag{24}
\end{equation*}
$$

where $T_{y}$ is the first hitting time of $\{y\}$ defined by (17) above.
Remark 2.4 Note that Assumption 2.3 implies

$$
\lim _{t \rightarrow \infty} e^{-\Lambda_{t}}\left|g\left(X_{t}\right)\right| \mathbf{1}_{\left\{T_{\bar{\alpha}} \wedge T_{\bar{\beta}}=\infty\right\}}=0
$$

for all points $\bar{\alpha}, \bar{\beta} \in \mathcal{J}$ such that $\bar{\alpha}<x<\bar{\beta}$ and all locally bounded functions $g: \mathcal{J} \rightarrow \mathbb{R}$. We can therefore define $e^{-\Lambda_{T_{\bar{\alpha}} \wedge T_{\bar{\beta}}}}\left|g\left(X_{T_{\bar{\alpha}} \wedge T_{\bar{\beta}}}\right)\right|=$ $\lim _{t \rightarrow \infty} e^{-\Lambda_{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge t}}\left|g\left(X_{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge t}\right)\right|$.

The following result, which we will need, is a straightforward consequence of the probabilistic expressions (23)-(23).

Lemma 2 Suppose that Assumptions 2.1-2.3 hold true, and fix any initial condition $x \in \mathcal{J}$ and any weak solution $\mathbb{S}_{x}$ to the $\operatorname{SDE}$ (7). Also, consider any strictly decreasing sequence $\left(\alpha_{m}\right)$ and any strictly increasing sequence $\left(\beta_{n}\right)$ such that

$$
\begin{equation*}
\alpha_{1}<x<\beta_{1}, \quad \lim _{m \rightarrow \infty} \alpha_{m}=\alpha \quad \text { and } \quad \lim _{n \rightarrow \infty} \beta_{n}=\beta \tag{25}
\end{equation*}
$$

If $g: \mathcal{J} \rightarrow \mathbb{R}$ is a locally bounded function satisfying

$$
\lim _{x \downarrow \alpha} \frac{|g(x)|}{\phi(x)}=\lim _{x \uparrow \beta} \frac{|g(x)|}{\psi(x)}=0,
$$

then

$$
\lim _{m, n \rightarrow \infty} \mathbb{E}\left[e^{-\Lambda_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}}\left|g\left(X_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}\right)\right|\right]=0
$$

Proof. Using (20)-(24), we calculate

$$
\begin{aligned}
\lim _{m, n \rightarrow \infty} \mathbb{E} & {\left[e^{-\Lambda_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}}\left|g\left(X_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}\right)\right|\right] } \\
& \leq \lim _{m, n \rightarrow \infty}\left\{| g ( \alpha _ { m } ) | \mathbb { E } _ { x } \left[e^{\left.\left.-\Lambda_{T_{\alpha_{m}}}\right]+\left|g\left(\beta_{n}\right)\right| \mathbb{E}_{x}\left[e^{-\Lambda_{T_{\beta_{n}}}}\right]\right\}}\right.\right. \\
& =\lim _{m \rightarrow \infty} \phi(x) \frac{\left|g\left(\alpha_{m}\right)\right|}{\phi\left(\alpha_{m}\right)}+\lim _{n \rightarrow \infty} \psi(x) \frac{\left|g\left(\beta_{n}\right)\right|}{\psi\left(\beta_{n}\right)} \\
& =0
\end{aligned}
$$

and the result follows.
If $\alpha$ is an entrance boundary point, i.e., if $\lim _{x \downarrow \alpha} \mathbb{P}_{x}\left(T_{a}<\infty\right)>0$, for some $a \in \mathcal{J}$, then $\psi(\alpha):=\lim _{x \downarrow \alpha} \psi(x)>0$, otherwise, if $\alpha$ is a natural boundary point, $\psi(\alpha):=\lim _{x \downarrow \alpha} \psi(x)=0$. Similarly, if $\beta$ is an entrance boundary point, then $\phi(\beta):=\lim _{x \uparrow \beta} \phi(x)>0$, while, if $\beta$ is a natural boundary point, $\phi(\beta):=$ $\lim _{x \uparrow \beta} \phi(x)=0$. Furthermore, the scale function $p$ admits the expression

$$
\begin{equation*}
p^{\prime}(x)=\frac{\phi(x) \psi^{\prime}(x)-\phi^{\prime}(x) \psi(x)}{C}, \quad \text { for all } x \in \mathcal{J}, \tag{26}
\end{equation*}
$$

where

$$
\begin{equation*}
C=\phi(c) \psi^{\prime}(c)-\phi^{\prime}(c) \psi(c)>0 . \tag{27}
\end{equation*}
$$

Apart from Lemma 2, all of these results concerning the functions $\phi$ and $\psi$ can be found in several references, including Borodin and Salminen [7], Itô and McKean [16], and Rogers and Williams [30].

Now, we consider measures $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J})$ ) such that

$$
\begin{equation*}
\int_{[\bar{\alpha}, \bar{\beta}]} \frac{1}{\sigma^{2}(x) p^{\prime}(x)}|h|(d x)<\infty, \quad \text { for all } \alpha<\bar{\alpha}<\bar{\beta}<\beta, \tag{28}
\end{equation*}
$$

where $|h|$ is the total variation measure of $h$, and we fix any point $\gamma \in \mathcal{J}$.
Definition 2.5 The space $\mathcal{I}_{\phi, \psi}$ of $(\phi, \psi)$-integrable measures is defined to be the set of all measures $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ such that

$$
\int_{]_{\alpha, \gamma}} \frac{\psi(s)}{\sigma^{2}(s) p^{\prime}(s)}|h|(d s)+\int_{[\gamma, \beta[ } \frac{\phi(s)}{\sigma^{2}(s) p^{\prime}(s)}|h|(d s)<\infty .
$$

Definition 2.6 The space $\Sigma_{\phi, \psi}$ of $(\phi, \psi)$-sumable measures is defined to be the set of all measures $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ satisfying (28) and such that the limits

$$
\lim _{x \downarrow \alpha} \int_{] x, \gamma[ } \frac{\psi(s)}{\sigma^{2}(s) p^{\prime}(s)} h(d s) \quad \text { and } \quad \lim _{x \uparrow \beta} \int_{[\gamma, x[ } \frac{\phi(s)}{\sigma^{2}(s) p^{\prime}(s)} h(d s)
$$

exist in $\mathbb{R}$.
Remark 2.7 It is worth noting that the definitions of $\mathcal{I}_{\phi, \psi}$ and $\Sigma_{\phi, \psi}$ do not depend on the choice of the point $\gamma \in \mathcal{J}$. Also, we plainly have $\mathcal{I}_{\phi, \psi} \subseteq \Sigma_{\phi, \psi}$. In fact, this inclusion is strict (see Example 2.8 below). However, we should note that, if $h$ is a positive measure, then $h \in \Sigma_{\phi, \psi}$ if and only if $h \in \mathcal{I}_{\phi, \psi}$.

Example 2.8 Suppose that $\mathcal{J}=] 0, \infty[, b \equiv 0$ and $\sigma(x)=\sqrt{2} x$, so that the Itô diffusion $X$ is a geometric Brownian motion, and that $r(x)=2$. In this context, we can see that

$$
\begin{equation*}
\phi(x)=x^{-1}, \quad \psi(x)=x^{2} \quad \text { and } \quad p^{\prime}(x)=1, \tag{29}
\end{equation*}
$$

where we have taken $c=1$ for the definition (14) of the scale function $p$. Also, consider the measure $h$ defined by

$$
\begin{equation*}
h(\Gamma)=\sum_{k=0}^{\infty} \frac{1}{2 k+1} \mathbf{1}_{\Gamma}\left(\frac{1}{2 k+1}\right)-\sum_{k=1}^{\infty} \frac{1}{2 k} \mathbf{1}_{\Gamma}\left(\frac{1}{2 k}\right), \tag{30}
\end{equation*}
$$

for $\Gamma \in \mathcal{B}(] 0, \infty[)$. In view of (29), we calculate

$$
\left.\int_{[0,1]} \frac{2 \psi(s)}{\sigma^{2}(s) p^{\prime}(s)}|h|(d s)=|h|(00,1]\right)=\sum_{k=0}^{\infty} \frac{1}{k}=\infty,
$$

and

$$
\lim _{x \downarrow 0} \int_{\mid x, 1]} \frac{2 \psi(s)}{\sigma^{2}(s) p^{\prime}(s)} h(d s)=1-\frac{1}{2}+\frac{1}{3}-\frac{1}{4}+\frac{1}{5}-\cdots=\ln 2 .
$$

However, combining these calculations with the fact that the support of the measure $h$ is included in the interval $] 0,1]$, we can see that $h \in \Sigma_{\phi, \psi}$ and that $h \notin \mathcal{I}_{\phi, \psi}$.

## 3 Analytic characterisation of a special solution to the ODE (1)

The purpose of this section is to study analytic properties of an appropriate special solution to the ODE (1). To this end, we consider a measure $h \in \Sigma_{\phi, \psi}$, and we define the function $Q_{h}: \mathcal{J} \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
Q_{h}(x)=\phi(x) \int_{] \alpha, x[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)+\psi(x) \int_{[x, \beta[ } \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s) . \tag{31}
\end{equation*}
$$

The next result is concerned with showing that this function is a special solution to the ODE (1).

Proposition 3 Suppose that Assumptions 2.1-2.3 are satisfied. Given a measure $h \in \Sigma_{\phi, \psi} \supset \mathcal{I}_{\phi, \psi}$, the function $Q_{h}$ defined by (31) is the difference of two convex functions,

$$
\begin{equation*}
\left(Q_{h}\right)_{-}^{\prime}(x)=\phi^{\prime}(x) \int_{] \alpha, x[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)+\psi^{\prime}(x) \int_{[x, \beta]} \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s) \tag{32}
\end{equation*}
$$

and $Q_{h}$ is a special solution to the ODE (1) in the sense of Definition 1.1. Furthermore, the operator $h \mapsto Q_{h}$ mapping $\Sigma_{\phi, \psi}$ into the set of all realvalued functions on $\mathcal{J}$ that are differences of two convex functions is positive, i.e.,

$$
\begin{equation*}
Q_{h} \geq 0, \quad \text { for all positive } h \in \Sigma_{\phi, \psi} \tag{33}
\end{equation*}
$$

and linear, i.e.,

$$
\begin{equation*}
Q_{a_{1} h_{1}+a_{2} h_{2}}=a_{1} Q_{h_{1}}+a_{2} Q_{h_{2}}, \quad \text { for all } a_{1}, a_{2} \in \mathbb{R} \text { and } h_{1}, h_{2} \in \Sigma_{\phi, \psi} . \tag{34}
\end{equation*}
$$

Proof. Recalling that $h$ satisfies (28), we define the left-continuous function $H: \mathcal{J} \rightarrow \mathbb{R}$ by $H(\gamma)=0$,

$$
\begin{equation*}
\left.H(x)=-\int_{] x, \gamma[ } \frac{2}{C \sigma^{2}(s) p^{\prime}(s)} h(d s), \quad \text { if } x \in\right] \alpha, \gamma[, \tag{35}
\end{equation*}
$$

and

$$
\begin{equation*}
\left.H(x)=\int_{[\gamma, x[ } \frac{2}{C \sigma^{2}(s) p^{\prime}(s)} h(d s), \quad \text { if } x \in\right] \gamma, \beta[, \tag{36}
\end{equation*}
$$

where the constant $C>0$ is as in (27). Now consider any points $\bar{\alpha}, \bar{\beta} \in \mathcal{J}$ such that $\bar{\alpha}<\bar{\beta}$. Using the integration by parts formula, we calculate

$$
\begin{align*}
& -H(\bar{\alpha}) \psi(\bar{\alpha})-\int_{\bar{\alpha}}^{x} \psi^{\prime}(s) H(s) d s=-H(x) \psi(x)+\int_{[\bar{\alpha}, x[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s),  \tag{37}\\
& H(\bar{\beta}) \phi(\bar{\beta})-\int_{x}^{\bar{\beta}} \phi^{\prime}(s) H(s) d s=H(x) \phi(x)+\int_{[x, \bar{\beta}]} \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s) . \tag{38}
\end{align*}
$$

If we define the function $\Theta_{h}^{\bar{\alpha}, \bar{\beta}}:[\bar{\alpha}, \bar{\beta}] \rightarrow \mathbb{R}$ by

$$
\begin{align*}
\Theta_{h}^{\bar{\alpha}, \bar{\beta}}(x)= & {\left[\int_{] \alpha, \bar{\alpha}[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)-H(\bar{\alpha}) \psi(\bar{\alpha})\right] \phi(x) } \\
& +\left[\int_{[\bar{\beta}, \beta[ } \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)+H(\bar{\beta}) \phi(\bar{\beta})\right] \psi(x) \\
& -\phi(x) \int_{\bar{\alpha}}^{x} \psi^{\prime}(s) H(s) d s-\psi(x) \int_{x}^{\bar{\beta}} \phi^{\prime}(s) H(s) d s, \tag{39}
\end{align*}
$$

then these expressions imply

$$
\begin{equation*}
Q_{h}(x)=\Theta_{h}^{\bar{\alpha}, \bar{\beta}}(x), \quad \text { for all } x \in[\bar{\alpha}, \bar{\beta}] \tag{40}
\end{equation*}
$$

In view of (26) and the fact that $H$ is left-continuous, we can see that the left-hand side first derivative of $\Theta_{h}^{\bar{\alpha}, \bar{\beta}}$ is given by

$$
\begin{align*}
\left(\Theta_{h}^{\bar{\alpha}, \bar{\beta}}\right)_{-}^{\prime}(x)= & {\left[\int_{] \alpha, \bar{\alpha}[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)-H(\bar{\alpha}) \psi(\bar{\alpha})\right] \phi^{\prime}(x) } \\
& +\left[\int_{[\bar{\beta}, \beta[ } \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)+H(\bar{\beta}) \phi(\bar{\beta})\right] \psi^{\prime}(x)-C p^{\prime}(x) H(x) \\
& -\phi^{\prime}(x) \int_{\bar{\alpha}}^{x} \psi^{\prime}(s) H(s) d s-\psi^{\prime}(x) \int_{x}^{\bar{\beta}} \phi^{\prime}(s) H(s) d s . \tag{41}
\end{align*}
$$

This calculation, (26), the integration by parts formulae (37)-(38) and the identity (40) imply (32). From this expression, we can also see that $\left(\Theta_{h}^{\bar{\alpha}, \bar{\beta}}\right)_{-}^{\prime}$ is locally bounded and that the second distributional derivative of $\Theta_{h}^{\bar{\alpha}, \beta}$ is a measure. Furthermore, if

$$
\begin{equation*}
\left(\Theta_{h}^{\bar{\alpha}, \bar{\beta}}\right)^{\prime \prime}(d x)=\left(\Theta_{h}^{\bar{\alpha}, \bar{\beta}}\right)_{\mathrm{ac}}^{\prime \prime}(x) d x+\left(\Theta_{h}^{\bar{\alpha}, \bar{\beta}}\right)_{\mathrm{s}}^{\prime \prime}(d x) \tag{42}
\end{equation*}
$$

is the Lebesgue decomposition of the second distributional derivative $\left(\Theta_{h}^{\bar{\alpha}, \bar{\beta}}\right)^{\prime \prime}(d x)$ (see (2)), then we can calculate

$$
\begin{aligned}
\left(\Theta_{h}^{\bar{\alpha}, \bar{\beta}}\right)_{\mathrm{ac}}^{\prime \prime}(x)= & {\left[\int_{] \alpha, \bar{\alpha}[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)-H(\bar{\alpha}) \psi(\bar{\alpha})\right] \phi^{\prime \prime}(x) } \\
& +\left[\int_{[\bar{\beta}, \beta]} \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)+H(\bar{\beta}) \phi(\bar{\beta})\right] \psi^{\prime \prime}(x) \\
& -C p^{\prime \prime}(x) H(x)-\frac{2 h_{\mathrm{ac}}(x)}{\sigma^{2}(x)} \\
& -\phi^{\prime \prime}(x) \int_{\bar{\alpha}}^{x} \psi^{\prime}(s) H(s) d s-\psi^{\prime \prime}(x) \int_{x}^{\bar{\beta}} \phi^{\prime}(s) H(s) d s .
\end{aligned}
$$

and

$$
\left(\Theta_{h}^{\bar{\alpha}, \bar{\beta}}\right)_{\mathrm{s}}^{\prime \prime}(d x)=-\frac{2}{\sigma^{2}(x)} h_{\mathrm{s}}(d x)
$$

Now, it is straightforward to combine these expressions, (39) and (41) with the fact that the scale function $p$ satisfies the ODE (16) and the fact that the functions $\phi, \psi$ are classical solutions to the homogeneous ODE (18) to see that $\Theta_{h}^{\bar{\alpha}, \bar{\beta}}$ satisfies the ODE (1) inside the interval $] \bar{\alpha}, \bar{\beta}[$. However, this observation (40) and the fact that $\bar{\alpha}, \bar{\beta}$ are arbitrary points in $\mathcal{J}$ imply that $Q_{h}$ satisfies the ODE (1) inside $\mathcal{J}$ in the sense of Definition 1.1. Finally, (33) and (34) follow immediately from the definition of $Q_{h}$.

Establishing conditions under which the solution to the ODE (1) that we have derived above is a monotone or a bounded function is an issue that is most important for applications. To this end, we define the positive measure $r_{\mathrm{m}}$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ by

$$
\begin{equation*}
r_{\mathrm{m}}(d x)=r(x) d x \tag{43}
\end{equation*}
$$

and we consider the following definitions.
Definition 3.1 A measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ is $r$-increasing if, given any $x \in \mathcal{J}$, there exists a constant $K_{x}$ such that the restriction of the measure $-h+$ $K_{x} r_{\mathrm{m}}$ in (]$\left.\left.\left.\left.\alpha, x\right], \mathcal{B}(] \alpha, x\right]\right)\right)$ and the restriction of the measure $h-K_{x} r_{m}$ in ( $[x, \beta[, \mathcal{B}([x, \beta[))$ both are positive measures.

The measure $h$ is $r$-decreasing if $-h$ is $r$-increasing.
Definition 3.2 The $r$-supremum and the $r$-infimum of a measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ over a set $\Gamma \in \mathcal{B}(\mathcal{J})$ are defined by

$$
\begin{aligned}
r-\sup _{\Gamma} h=\inf \{K \in \mathbb{R} \mid & \text { the restriction of }-h+K r_{\mathrm{m}} \\
& \text { in }(\Gamma, \mathcal{B}(\Gamma)) \text { is a positive measure }\}, \\
r-\inf _{\Gamma} h=\sup \{K \in \mathbb{R} \mid & \text { the restriction of } h-K r_{\mathrm{m}} \\
& \text { in }(\Gamma, \mathcal{B}(\Gamma)) \text { is a positive measure }\},
\end{aligned}
$$

with the usual conventions $\inf \emptyset=\infty$ and $\sup \emptyset=-\infty$.
Definition 3.3 A measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ is $r$-convergent in $\mathbb{R}$ at $\alpha$ if there exists a constant $r-\lim _{\alpha} h \in \mathbb{R}$ such that, for all $\varepsilon>0$, there exists $\alpha_{\varepsilon} \in \mathcal{J}$ such that the restrictions of the measures $h-\left(r-\lim _{\alpha} h-\varepsilon\right) r_{\mathrm{m}}$ and $-h+$ $\left(r-\lim _{\alpha} h+\varepsilon\right) r_{\mathrm{m}}$ in (]$\alpha, \alpha_{\varepsilon}\left[\mathcal{B}(] \alpha, \alpha_{\varepsilon}[)\right.$ both are positive measures.
A measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ is $r$-convergent to $\infty$ at $\alpha$, in which case we write $r-\lim _{\alpha} h=\infty$, if, for all $K>0$, there exists $\alpha_{K} \in \mathcal{J}$ such that the restriction of the measure $h-K r_{\mathrm{m}}$ in (]$\alpha, \alpha_{K}\left[, \mathcal{B}(] \alpha, \alpha_{K}[)\right.$ is a positive measure.
A measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ is $r$-convergent to $-\infty$ at $\alpha$, in which case we write $r-\lim _{\alpha} h=-\infty$, if $r-\lim _{\alpha}(-h)=\infty$.

The $r$-limits of a measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ at $\beta$ are defined in a similar way.

Remark 3.4 below provides the intuition behind these definitions.
The following result is concerned with the issues considered above and with several other properties of the solution $Q_{h}$ to the ODE (1) that are of interest in applications.

Proposition 4 Suppose that Assumptions 2.1-2.3 hold true, and consider any measure $h \in \Sigma_{\phi, \psi} \supset \mathcal{I}_{\phi, \psi}$. The function $Q_{h}$ given by (31) satisfies

$$
\begin{equation*}
\lim _{x \downarrow \alpha} \frac{\left|Q_{h}(x)\right|}{\phi(x)}=\lim _{x \uparrow \beta} \frac{\left|Q_{h}(x)\right|}{\psi(x)}=0, \tag{44}
\end{equation*}
$$

and

$$
\begin{gather*}
r-\inf _{\mathcal{J}} h \leq Q_{h}(x) \leq r-\sup _{\mathcal{J}} h,  \tag{45}\\
\phi(x)\left(Q_{h}\right)_{-}^{\prime}(x)-\phi^{\prime}(x) Q_{h}(x)=p^{\prime}(x) \int_{[x, \beta[ } \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s),  \tag{46}\\
\psi(x)\left(Q_{h}\right)_{-}^{\prime}(x)-\psi^{\prime}(x) Q_{h}(x)=-p^{\prime}(x) \int_{] \alpha, x[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s), \tag{47}
\end{gather*}
$$

for all $x \in \mathcal{J}$. If $r_{\mathrm{m}}$ is the measure on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ defined by (43), then

$$
\begin{equation*}
Q_{r_{\mathrm{m}}}(x)=1, \quad \text { for all } x \in \mathcal{J} . \tag{48}
\end{equation*}
$$

If $h$ is $r$-increasing (resp., $r$-decreasing) in the sense of Definition 3.1 and $|h|(\mathcal{J})>0$, then $Q_{h}$ is strictly increasing (resp., strictly decreasing). Furthermore, if $\alpha$ (resp., $\beta$ ) is a natural boundary point and $h$ is $r$-convergent at $\alpha$ (resp., at $\beta$ ) in the sense of Definition 3.3, then

$$
\begin{equation*}
\lim _{x \downarrow \alpha} Q_{h}(x)=r-\lim _{\alpha} h \quad\left(\text { resp., } \lim _{x \uparrow \beta} Q_{h}(x)=r-\lim _{\beta} h\right) . \tag{49}
\end{equation*}
$$

Proof. We can verify (46) and (47) by a straightforward calculation involving the definition (31) of $Q_{h}$ and (26). To prove (48), we first note that (20), (21) and (26) imply

$$
0<\frac{\phi(x) \psi^{\prime}(x)}{C p^{\prime}(x)}<1 \quad \text { and } \quad 0<-\frac{\phi^{\prime}(x) \psi(x)}{C p^{\prime}(x)}<1 .
$$

Combining these inequalities with (22), we can see that

$$
\begin{equation*}
\lim _{x \downarrow \alpha} \frac{\psi^{\prime}(x)}{p^{\prime}(x)}=\lim _{x \uparrow \beta} \frac{\phi^{\prime}(x)}{p^{\prime}(x)}=0 . \tag{50}
\end{equation*}
$$

Now, the fact that $p^{\prime}$ satisfies the ODE (16) and the fact that $\phi$ satisfies the ODE (18) imply

$$
\begin{aligned}
\frac{d}{d x}\left(\frac{\phi^{\prime}(x)}{p^{\prime}(x)}\right) & =\frac{2}{\sigma^{2}(x) p^{\prime}(x)}\left[\frac{1}{2} \sigma^{2}(x) \phi^{\prime \prime}(x)+b(x) \phi^{\prime}(x)\right] \\
& =\frac{2 r(x) \phi(x)}{\sigma^{2}(x) p^{\prime}(x)}
\end{aligned}
$$

Similarly, we can show that

$$
\frac{d}{d x}\left(\frac{\psi^{\prime}(x)}{p^{\prime}(x)}\right)=\frac{2 r(x) \psi(x)}{\sigma^{2}(x) p^{\prime}(x)}
$$

In view of these calculations and the continuity of the functions $\phi^{\prime}, \psi^{\prime}$ and $p^{\prime}$, we can see that

$$
Q_{r_{\mathrm{m}}}(x)=\phi(x) \int_{\alpha}^{x} \frac{1}{C} d\left(\frac{\psi^{\prime}(s)}{p^{\prime}(s)}\right)+\psi(x) \int_{x}^{\beta} \frac{1}{C} d\left(\frac{\phi^{\prime}(s)}{p^{\prime}(s)}\right) .
$$

However, this expression, (50) and (26) imply (48).
To establish (45), suppose, without loss of generality, that $r-\inf _{\mathcal{J}} h>-\infty$, and let any $K \leq r-\inf _{\mathcal{J}} h$. In view of Definition 3.2, $h(d z)-K r(z) d z$ is a positive measure on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$. Combining this observation and (48) with the linearity and positivity of $h \mapsto Q_{h}$ (see (33) and (34) in Proposition 3), we can see that

$$
Q_{h}(x)-K=Q_{h-K r_{m}}(x) \geq 0, \quad \text { for all } x \in \mathcal{J} .
$$

It follows that $\inf _{x \in \mathcal{J}} Q_{h}(x) \geq r-\inf _{\mathcal{J}} h$. Similarly, we can show that $\sup _{x \in \mathcal{J}} Q_{h}(x) \leq r-\sup _{\mathcal{J}} h$, and (45) follows.
Now, let us assume that the measure $h$ is $r$-increasing and $|h|(\mathcal{J})>0$. Given $x \in \mathcal{J}$, let $K_{x}$ be a constant as in Definition 3.1. Using (48), which implies that $\left(Q_{r_{\mathrm{m}}}\right)_{-}^{\prime}(x) \equiv 0$, the linearity of the operator $h \mapsto Q_{h}$ and (32), we can
see that

$$
\begin{aligned}
\left(Q_{h}\right)_{-}^{\prime}(x)= & \left(Q_{h}-Q_{K_{x} r_{\mathrm{m}}}\right)_{-}^{\prime}(x) \\
= & \left(Q_{h-K_{x} r_{\mathrm{m}}}\right)_{-}^{\prime}(x) \\
= & \phi^{\prime}(x) \int_{] \alpha, x[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)}\left(h-K_{x} r_{\mathrm{m}}\right)(d s) \\
& +\psi^{\prime}(x) \int_{[x, \beta[ } \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)}\left(h-K_{x} r_{\mathrm{m}}\right)(d s) \\
> & 0,
\end{aligned}
$$

the inequality following because the restriction of $-h+K_{x} r_{\mathrm{m}}$ in (]$\alpha, x], \mathcal{B}(] \alpha, x]))$ and the restriction of $h-K_{x} r_{\mathrm{m}}$ in $([x, \beta[, \mathcal{B}([x, \beta[))$ both are positive measures (see Definition 3.1), and because $\phi^{\prime}<0<\psi^{\prime}$. However, this calculation implies that $Q_{h}$ is increasing.
To prove (44), we define

$$
\left.H_{\psi}(x)=-\int_{] x, \gamma]} \frac{\psi(s)}{\sigma^{2}(s) p^{\prime}(s)} h(d s), \quad \text { for } x \in\right] \alpha, \gamma[,
$$

and we note that Definition 2.6 implies that

$$
\begin{equation*}
H_{\psi}(\alpha):=\lim _{x \downarrow \alpha} H_{\psi}(x) \quad \text { exists in } \mathbb{R} . \tag{51}
\end{equation*}
$$

Using this definition and the integration by parts formula we calculate

$$
\begin{align*}
& \frac{\psi(x)}{\phi(x)} \int_{] x, \gamma]} \frac{\phi(s)}{\sigma^{2}(s) p^{\prime}(s)} h(d s) \\
& \\
& \quad=\frac{\psi(x)}{\phi(x)} \int_{[x, \gamma]} \frac{\phi(s)}{\psi(s)} d H_{\psi}(s)  \tag{52}\\
& \\
& \quad=\frac{\psi(x)}{\phi(x)} \frac{\phi(\gamma)}{\psi(\gamma)} H_{\psi}(\gamma)-H_{\psi}(x)-\frac{\psi(x)}{\phi(x)} \int_{x}^{\gamma} H_{\psi}(s) d \frac{\phi(s)}{\psi(s)} .
\end{align*}
$$

Now, consider any $y \in] \alpha, \gamma[$, and note that (20) and (21) imply

$$
\frac{d}{d x} \frac{\psi(x)}{\phi(x)}=-\frac{\phi^{\prime}(x) \psi(x)-\phi(x) \psi^{\prime}(x)}{\phi^{2}(x)}<0,
$$

In light of this observation, we calculate

$$
\begin{aligned}
& \limsup _{x \downarrow \alpha}\left[-\frac{\psi(x)}{\phi(x)} \int_{x}^{\gamma} H_{\psi}(s) d \frac{\phi(s)}{\psi(s)}\right] \\
& \leq \limsup _{x \downarrow \alpha}\left[-\left(\frac{\psi(x) \phi(y)}{\phi(x) \psi(y)}-1\right) \sup _{s \in] \alpha, y]} H_{\psi}(s)-\frac{\psi(x)}{\phi(x)} \int_{y}^{\gamma} H_{\psi}(s) d \frac{\phi(s)}{\psi(s)}\right] \\
& =\sup _{s \in\rfloor \alpha, y]} H_{\psi}(s)
\end{aligned}
$$

the equality following because $\lim _{x \downarrow \alpha} \psi(x) / \phi(x)=0$ (see (20)-(22)). By passing to the limit $y \downarrow \alpha$ in this inequality, we can see that

$$
\limsup _{x \downarrow \alpha}\left[-\frac{\psi(x)}{\phi(x)} \int_{x}^{\gamma} H_{\psi}(s) d \frac{\phi(s)}{\psi(s)}\right] \leq \underset{x \downarrow \alpha}{\limsup } H_{\psi}(x)=H_{\psi}(\alpha),
$$

thanks to (51). Using symmetric arguments, we can also see that

$$
\liminf _{x \downarrow \alpha}\left[-\frac{\psi(x)}{\phi(x)} \int_{x}^{\gamma} H_{\psi}(s) d \frac{\phi(s)}{\psi(s)}\right] \geq H_{\psi}(\alpha)
$$

It follows that

$$
\lim _{x \downarrow \alpha}\left[-\frac{\psi(x)}{\phi(x)} \int_{x}^{\gamma} H_{\psi}(s) d \frac{\phi(s)}{\psi(s)}\right]=H_{\psi}(\alpha) \equiv \lim _{x \downarrow \alpha} H_{\psi}(x)
$$

However, this conclusion, (52) and the fact that $\lim _{x \downarrow \alpha} \phi(x) / \psi(x)$ imply

$$
\lim _{x \downarrow \alpha} \frac{\psi(x)}{\phi(x)} \int_{] x, \gamma]} \frac{\phi(s)}{\sigma^{2}(s) p^{\prime}(s)} h(d s)=0
$$

Combining this limit with the fact that

$$
\lim _{x \downarrow \alpha} \int_{] \alpha, x[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)=0
$$

and the definition (31) of $Q_{h}$, we can see that $\lim _{x \downarrow \alpha} Q_{h}(x) / \phi(x)=0$, and (44) follows because $\phi>0$. Showing that $\lim _{x \uparrow \beta}\left|Q_{h}(x)\right| / \psi(x)=0$ involves similar arguments.

Finally, suppose that $\alpha$ is a natural boundary point, so that $\lim _{x \downarrow \alpha} \psi(x)=$ 0 , and that $h$ is $r$-convergent in $\mathbb{R}$ at $\alpha$. Also, fix any $\varepsilon>0$, and let any $\alpha_{\varepsilon} \in \mathcal{J}$ such that the restriction of the measures $h-\left(r-\lim _{\alpha} h-\varepsilon\right) r_{\mathrm{m}}$ and
$-h+\left(r-\lim _{\alpha} h+\varepsilon\right) r_{\mathrm{m}}$ in (]$\alpha, \alpha_{\varepsilon}\left[, \mathcal{B}(] \alpha, \alpha_{\varepsilon}[)\right)$ both are positive measures (see Definition 3.3). In this context, we calculate

$$
\begin{aligned}
\limsup _{x \downarrow \alpha} & Q_{h}(x)-r-\lim _{\alpha} h-\varepsilon \\
= & \limsup _{x \downarrow \alpha} Q_{h-\left(r-\lim _{\alpha} h+\varepsilon\right) r_{\mathrm{m}}}(x) \\
= & \limsup _{x \downarrow \alpha}\left[\phi(x) \int_{] \alpha, x[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)}\left[h-\left(r-\lim _{\alpha} h+\varepsilon\right) r_{\mathrm{m}}\right](d s)\right. \\
& +\psi(x) \int_{\left[x, \alpha_{\varepsilon}[ \right.} \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)}\left[h-\left(r-\lim _{\alpha} h+\varepsilon\right) r_{\mathrm{m}}\right](d s) \\
& \left.\quad+\psi(x) \int_{\left[\alpha_{\varepsilon}, \beta[ \right.} \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)}\left[h-\left(r-\lim _{\alpha} h+\varepsilon\right) r_{\mathrm{m}}\right](d s)\right] \\
\leq & \limsup _{x \downarrow \alpha} \psi(x) \int_{\left[\alpha_{\varepsilon}, \beta[ \right.} \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)}\left[h-\left(r-\lim _{\alpha} h+\varepsilon\right) r_{\mathrm{m}}\right](d s) \\
= & 0 .
\end{aligned}
$$

Since $\varepsilon>0$ is arbitrary, it follows that $\lim _{\sup }^{x \downarrow \alpha} Q_{h}(x) \leq r-\lim _{\alpha} h$. Similarly, we can show that $\lim \inf _{x \downarrow \alpha} Q_{h}(x) \geq r-\lim _{\alpha} h$, and thus establish that $\lim _{x \downarrow \alpha} Q_{h}(x)=r-\lim _{\alpha} h$. Also, we can prove that $\lim _{x \downarrow \alpha} Q_{h}(x)=r-\lim _{\alpha} h$ when $r-\lim _{\alpha} h=\infty$ or $r-\lim _{\alpha} h=-\infty$ using similar arguments.

Remark 3.4 Definitions 3.1, 3.2 and 3.3 take very simple forms if the measure $h$ is absolutely continuous, i.e., if $h_{\mathrm{s}} \equiv 0$ in the Lebesgue decomposition (3) of $h$. Indeed, in this case, $h$ is $r$-increasing (resp., $r$-decreasing) if and only if $h_{\mathrm{ac}} / r$ is an increasing (resp., decreasing) function, and

$$
r-\sup _{\Gamma} h=\sup _{x \in \Gamma} \frac{h_{\mathrm{ac}}(x)}{r(x)} \quad \text { and } \quad r-\inf _{\Gamma} h=\inf _{x \in \Gamma} \frac{h_{\mathrm{ac}}(x)}{r(x)} .
$$

Also, $h$ is $r$-convergent at $\alpha$ (resp., at $\beta$ ) if $h_{\mathrm{ac}} / r$ converges as $x$ tends to $\alpha$ (resp., $\beta$ ), in which case,

$$
r-\lim _{\alpha} h=\lim _{x \downarrow \alpha} \frac{h_{\mathrm{ac}}(x)}{r(x)}, \quad\left(\text { resp., } r-\lim _{\beta} h=\lim _{x \uparrow \beta} \frac{h_{\mathrm{ac}}(x)}{r(x)}\right) .
$$

At this point, it is worth noting that, if $\alpha$ (resp., $\beta$ ) is not a natural boundary point but an entrance one, then (49) is not necessarily true. We substantiate this claim by means of Example 4.2 that we develop in the next section because
it requires the probabilistic representation of the function $Q_{h}$ that we develop there.
Remark 3.5 Given a measure $h$ satisfying (28), the function $Q_{h}^{\bar{\alpha}, \bar{\beta}}: \mathcal{J} \rightarrow \mathbb{R}$ given by

$$
\begin{equation*}
Q_{h}^{\bar{\alpha}, \bar{\beta}}(x)=\phi(x) \int_{] \bar{\alpha}, x[ } \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)+\psi(x) \int_{[x, \bar{\beta}]} \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s), \tag{53}
\end{equation*}
$$

for some $\alpha<\bar{\alpha}<\bar{\beta}<\beta$, is well-defined even when $h \notin \Sigma_{\phi, \psi}$. Furthermore, we can use the same arguments as the ones in the proof of Proposition 3 to show that $Q_{h}^{\bar{\alpha}, \bar{\beta}}$ is the difference of two convex functions and is a special solution to the ODE (1). However, such a solution does not, in general, satisfy (44) in Proposition 4 anymore. To see this claim, it suffices to consider a measure $h \in \Sigma_{\phi, \psi}$ and observe that
$Q_{h}^{\bar{\alpha}, \bar{\beta}}(x)=Q_{h}(x)-\phi(x) \int_{] \alpha, \bar{\alpha}]} \frac{2 \psi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)-\psi(x) \int_{[\bar{\beta}, \beta[ } \frac{2 \phi(s)}{C \sigma^{2}(s) p^{\prime}(s)} h(d s)$.

## 4 Probabilistic characterisation of a special solution to the ODE (1)

Throughout this section, we assume that an initial condition $x \in \mathcal{J}$ and a weak solution $\mathbb{S}_{x}=\left(\Omega, \mathcal{F}, \mathcal{F}_{t}, \mathbb{P}_{x}, W, X\right)$ to the $\operatorname{SDE}(7)$ are fixed, and we make no further reference to this setting. We also assume that the filtered probability space $\left(\Omega, \mathcal{F}, \mathcal{F}_{t}, \mathbb{P}_{x}\right)$ satisfies the usual conditions. In this probabilistic setting, we denote by $L^{z}$ the local time process of $X$ at level $z \in \mathcal{J}$. In particular, we consider a modification of the local time family ( $\left.L_{t}^{z} ; z \in\right] \alpha, \beta[, t \geq 0$ ) such that the mapping $(z, t) \mapsto L_{t}^{z}$ is bicontinuous $\mathbb{P}_{x}$-a.s. (see Revuz and Yor [29, Theorem VI.1.7]).
Given a measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J})$ ) satisfying (28), we define the finite variation process $A^{h}$ by

$$
\begin{equation*}
A_{t}^{h}=\int_{\alpha}^{\beta} \frac{L_{t}^{z}}{\sigma^{2}(z)} h(d z) \tag{54}
\end{equation*}
$$

The assumption that $X$ is non-explosive implies that $\alpha<\inf _{u \leq t} X_{u}<$ $\sup _{u \leq t} X_{u}<\beta$, for all $t \geq 0$. Combining this observation with the fact that the measure $d L_{t}^{z}$ is supported on the set $\left\{X_{t}=z\right\}$ and the continuity of $z \mapsto L_{t}^{z}$,
we can see that

$$
A_{t}^{|h|} \leq \sup _{z \in \mathcal{J}} L_{t}^{z} \int_{\inf _{u \leq t} X_{u}}^{\sup _{u \leq t} X_{u}} \frac{1}{\sigma^{2}(z)}|h|(d z)<\infty,
$$

the second inequality following thanks to (28), and the continuity and strict positivity of $p^{\prime}$. It follows that $A_{t}^{h}$ is well-defined for all $t \geq 0$. Also, we note that $A^{h}$ is continuous, $A_{0}^{h}=0$, and, if $h$ is a positive measure, then $A^{h}$ is an increasing process. These properties follow because $L_{0}^{z}=0$ and the local time process $L^{z}$ is increasing and continuous, for all $z \in \mathcal{J}$. For future reference, we also observe that the mapping $h \mapsto A^{h}$ is linear, i.e.,

$$
\begin{equation*}
A^{a_{1} h_{1}+a_{2} h_{2}}=a_{1} A^{h_{1}}+a_{2} A^{h_{2}} \tag{55}
\end{equation*}
$$

for all $a_{1}, a_{2} \in \mathbb{R}$ and all measures $h_{1}, h_{2}$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ satisfying (28).
Remark 4.1 It is worth noting that, if the measure $h$ is absolutely continuous, i.e., $h_{\mathrm{s}} \equiv 0$ in the Lebesgue decomposition of $h$ in (3), then the occupation times formula (see Revuz and Yor [29, Corollary VI.1.6]) implies that the process $A^{h}$ admits the expression

$$
A_{t}^{h}=\int_{0}^{t} h_{\mathrm{ac}}\left(X_{u}\right) d u
$$

Before addressing the main results in the section, we prove the following preliminary result.
Lemma 5 Suppose that Assumptions 2.1-2.3 hold true. Consider a measure $h$ on $(\mathcal{J}, \mathcal{B}(\mathcal{J}))$ satisfying (28) and let $w: \mathcal{J} \rightarrow \mathbb{R}$ be a function satisfying the ODE (1) in the sense of Definition 1.1. Given any points $\bar{\alpha}, \bar{\beta} \in \mathcal{J}$ such that $\bar{\alpha}<x<\bar{\beta}$, and any $\left(\mathcal{F}_{t}\right)$-stopping time $v$,

$$
\begin{equation*}
\mathbb{E}_{x}\left[e^{-\Lambda_{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v}} w\left(X_{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v}\right)\right]=w(x)-\mathbb{E}_{x}\left[\int_{0}^{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v} e^{-\Lambda_{t}} d A_{t}^{h}\right] \tag{56}
\end{equation*}
$$

where $T_{\bar{\alpha}}$ and $T_{\bar{\beta}}$ are the first hitting times of the sets $\{\bar{\alpha}\}$ and $\{\bar{\beta}\}$, respectively, defined by (17).
Proof. Since the function $w$ is the difference of two convex functions, the Itô-Tanaka formula (e.g., see Revuz and Yor [29, Theorem VI.1.5]) implies
$w\left(X_{t}\right)=w(x)+\int_{0}^{t} b\left(X_{u}\right) w_{-}^{\prime}\left(X_{u}\right) d u+\frac{1}{2} \int_{\alpha}^{\beta} L_{t}^{z} w^{\prime \prime}(d z)+\int_{0}^{t} \sigma\left(X_{u}\right) w_{-}^{\prime}\left(X_{u}\right) d W_{u}$.

In view of the Lebesgue decomposition (42) of the measure $w^{\prime \prime}$ as in (3) and the occupation times formula, we can see that

$$
\int_{\alpha}^{\beta} L_{t}^{z} w_{\mathrm{ac}}^{\prime \prime}(z) d z=\int_{0}^{t} \sigma^{2}\left(X_{u}\right) w_{\mathrm{ac}}^{\prime \prime}\left(X_{u}\right) d u
$$

It follows that

$$
\begin{aligned}
w\left(X_{t}\right)= & w(x)+\int_{0}^{t}\left[\frac{1}{2} \sigma^{2}\left(X_{u}\right) w_{\mathrm{ac}}^{\prime \prime}\left(X_{u}\right)+b\left(X_{u}\right) w_{-}^{\prime}\left(X_{u}\right)\right] d u \\
& +\frac{1}{2} \int_{\alpha}^{\beta} L_{t}^{z} w_{\mathrm{s}}^{\prime \prime}(d z)+\int_{0}^{t} \sigma\left(X_{u}\right) w_{-}^{\prime}\left(X_{u}\right) d W_{u}
\end{aligned}
$$

Now, using the integration by parts formula for semimartingales and the fact that $w$ satisfies the ODE (1) in the sense of Definition 1.1, we obtain

$$
\begin{aligned}
e^{-\Lambda_{t}} w\left(X_{t}\right)= & w(x)+\frac{1}{2} \int_{0}^{t} e^{-\Lambda_{u}} d \int_{\alpha}^{\beta} L_{u}^{z} w_{\mathrm{s}}^{\prime \prime}(d z)+M_{t} \\
& +\int_{0}^{t} e^{-\Lambda_{u}}\left[\frac{1}{2} \sigma^{2}\left(X_{u}\right) w_{\mathrm{ac}}^{\prime \prime}\left(X_{u}\right)+b\left(X_{u}\right) w_{-}^{\prime}\left(X_{u}\right)-r\left(X_{u}\right) w\left(X_{u}\right)\right] d u \\
= & w(x)-\int_{0}^{t} e^{-\Lambda_{u}} h_{\mathrm{ac}}\left(X_{u}\right) d u-\int_{0}^{t} e^{-\Lambda_{u}} d \int_{\alpha}^{\beta} \frac{L_{u}^{z}}{\sigma^{2}(z)} h_{\mathrm{s}}(d z)+M_{t},
\end{aligned}
$$

where $M$ is the stochastic integral defined by

$$
\begin{equation*}
M_{t}=\int_{0}^{t} e^{-\Lambda_{u}} \sigma\left(X_{u}\right) w_{-}^{\prime}\left(X_{u}\right) d W_{u} \tag{57}
\end{equation*}
$$

With regard to the Lebesgue decomposition of the measure $h$ in (3), the occupation times formula and the definition (54) of the process $A^{h}$, we can see that

$$
\begin{equation*}
e^{-\Lambda_{t}} w\left(X_{t}\right)=w(x)-\int_{0}^{t} e^{-\Lambda_{u}} d A_{u}^{h}+M_{t} . \tag{58}
\end{equation*}
$$

In view of Assumption 2.3 and the local boundedness of the functions $w_{-}^{\prime}$ and $\sigma^{2}$ (see also (13) in Assumption 2.1), we can see that the stopped process
$M^{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v}$ has quadratic variation that satisfies

$$
\begin{aligned}
\mathbb{E}_{x}\left[\left\langle M^{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v}\right\rangle_{\infty}\right] & =\mathbb{E}_{x}\left[\int_{0}^{\infty} \mathbf{1}_{\left\{t \leq T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v\right\}}\left[e^{-\Lambda_{t}} \sigma\left(X_{t}\right) w_{-}^{\prime}\left(X_{t}\right)\right]^{2} d t\right] \\
& \leq \frac{1}{2 r_{0}} \sup _{x \in\left[T_{\bar{\alpha}}, T_{\bar{\beta}}\right]}\left[\sigma(x) w_{-}^{\prime}(x)\right]^{2} \\
& <\infty
\end{aligned}
$$

It follows that $M^{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v}$ is a uniformly square integrable martingale, so

$$
M_{\infty}^{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v}:=\lim _{t \rightarrow \infty} M_{t}^{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v} \quad \text { exists, } \mathbb{P}_{x^{-} \text {-a.s. }}
$$

and

$$
\mathbb{E}_{x}\left[M_{\infty}^{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v}\right] \equiv \mathbb{E}_{x}\left[M_{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge v}\right]=0
$$

In light of this observation and Remark 2.4, we can see that (58) implies that

$$
\lim _{t \rightarrow \infty} \int_{0}^{T_{\bar{\alpha}} \wedge T_{\bar{\beta}} \wedge t} e^{-\Lambda_{u}} d A_{u}^{h} \quad \text { exists, } \mathbb{P}_{x} \text {-a.s. }
$$

and that (56) holds true.
The following result provides a probabilistic characterisation of the space $\mathcal{I}_{\phi, \psi}$.
Proposition 6 Suppose that Assumptions 2.1-2.3 hold true. A measure $h \in$ $\Sigma_{\phi, \psi}$ belongs to $\mathcal{I}_{\phi, \psi}$ if and only if

$$
\begin{equation*}
\mathbb{E}_{x}\left[\int_{0}^{\infty} e^{-\Lambda_{t}} d A_{t}^{|h|}\right]<\infty \tag{59}
\end{equation*}
$$

where the increasing process $A^{|h|}$ is defined as in (54). Given any $h \in \mathcal{I}_{\phi, \psi}$,

$$
\begin{equation*}
R_{h}(x):=\mathbb{E}_{x}\left[\int_{0}^{\infty} e^{-\Lambda_{t}} d A_{t}^{h}\right]=Q_{h}(x) \tag{60}
\end{equation*}
$$

Furthermore, given a measure $h \in \mathcal{I}_{\phi, \psi}$, the solution $Q_{h} \equiv R_{h}$ to the ODE (1)
satisfies Dynkin's formula, i.e., given any $\left(\mathcal{F}_{t}\right)$-stopping time $v$,

$$
\begin{align*}
& \mathbb{E}_{x}\left[e^{-\Lambda_{v}} Q_{h}\left(X_{\tau}\right) \mathbf{1}_{\{v<\infty\}}\right]=Q_{h}(x)-\mathbb{E}_{x}\left[\int_{0}^{v} e^{-\Lambda_{t}} d A_{t}^{h}\right]  \tag{61}\\
& \mathbb{E}_{x}\left[e^{-\Lambda_{v}} Q_{h}\left(X_{v}\right) \mathbf{1}_{\{v<\infty\}}\right]=\mathbb{E}_{x}\left[\int_{v}^{\infty} e^{-\Lambda_{t}} d A_{t}^{h}\right] \tag{62}
\end{align*}
$$

as well as the strong transversality condition, i.e., given any sequence $\left(v_{n}\right)$ of $\left(\mathcal{F}_{t}\right)$-stopping times such that $\lim _{n \rightarrow \infty} v_{n}=\infty$,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \mathbb{E}_{x}\left[e^{-\Lambda_{v_{n}}}\left|Q_{h}\left(X_{v_{n}}\right)\right| \mathbf{1}_{\left\{v_{n}<\infty\right\}}\right]=0 \tag{63}
\end{equation*}
$$

Proof. Combining the definition of $\mathcal{I}_{\phi, \psi}$ with the linear dependence of the function $Q_{h}$ on the measure $h$ (see (34)), which implies that $\left|Q_{h}\right| \leq Q_{|h|}$, and the linear dependence of the stochastic process $A^{h}$ on the measure $h$ (see (55)), we can see that the result will follow if we prove it for positive $h$. Therefore, it suffices to develop the proof under the assumptions that $Q_{h} \geq 0$ and that $A^{h}$ is an increasing process.

Consider any sequences $\left(\alpha_{m}\right)$ and $\left(\beta_{n}\right)$ in $\mathcal{J}$ being as in Lemma 2. Given a measure $h \in \Sigma_{\phi, \psi} \supset \mathcal{I}_{\phi, \psi}$, not necessarily positive, we can see that the fact that $Q_{h}$ satisfies the ODE (1) in the sense of Definition 1.1 and Lemma 5 with $v=\infty$ imply

$$
\mathbb{E}_{x}\left[e^{-\Lambda_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}} Q_{h}\left(X_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}\right)\right]=Q_{h}(x)-\mathbb{E}_{x}\left[\int_{0}^{T_{\alpha_{m}} \wedge T_{\beta_{n}}} e^{-\Lambda_{t}} d A_{t}^{h}\right]
$$

In view of (44) and Lemma 2, we can pass to the limits $m, n \rightarrow \infty$ to obtain

$$
\begin{equation*}
Q_{h}(x)=\lim _{m, n \rightarrow \infty} \mathbb{E}_{x}\left[\int_{0}^{T_{\alpha_{m}} \wedge T_{\beta_{n}}} e^{-\Lambda_{t}} d A_{t}^{h}\right] \tag{64}
\end{equation*}
$$

Now, if $h$ is a positive measure satisfying (28), then $A^{h}$ is an increasing process and the monotone convergence theorem implies

$$
\begin{equation*}
\lim _{m, n \rightarrow \infty} \mathbb{E}_{x}\left[\int_{0}^{T_{\alpha_{m}} \wedge T_{\beta_{n}}} e^{-\Lambda_{t}} d A_{t}^{h}\right]=\mathbb{E}_{x}\left[\int_{0}^{\infty} e^{-\Lambda_{t}} d A_{t}^{h}\right] \tag{65}
\end{equation*}
$$

Recalling that every positive measure $h \in \Sigma_{\phi, \psi}$ belongs to $\mathcal{I}_{\phi, \psi}$ (see Remark 2.7), we can see that, if the right hand side of (65) is equal to $\infty$,
then $h \notin \mathcal{I}_{\phi, \psi}$ because, otherwise, (64) and (65) imply $Q_{h}(x)=\infty$, which contradicts the fact that $Q_{h}$ is real-valued for all $h \in \Sigma_{\phi, \psi} \supset \mathcal{I}_{\phi, \psi}$. It follows that a positive measure in $\Sigma_{\phi, \psi}$ belongs to $\mathcal{I}_{\phi, \psi}$ if and only if (59) is true. Furthermore, if $h \in \mathcal{I}_{\phi, \psi}$ is a positive measure, then (64) and (65) imply (60).

To prove (61) and (62), we note that Lemma 5 yields

$$
\begin{equation*}
\mathbb{E}_{x}\left[e^{-\Lambda_{T_{\alpha_{m}} \wedge T_{\beta_{n}} \wedge v}} Q_{h}\left(X_{T_{\alpha_{m}} \wedge T_{\beta_{n}} \wedge v}\right)\right]=Q_{h}(x)-\mathbb{E}_{x}\left[\int_{0}^{T_{\alpha_{m}} \wedge T_{\beta_{n}} \wedge v} e^{-\Lambda_{t}} d A_{t}^{h}\right] \tag{66}
\end{equation*}
$$

where $\left(\alpha_{m}\right)$ and $\left(\beta_{n}\right)$ are any sequences as in Lemma 2. An application of the monotone convergence theorem implies

$$
\lim _{m, n \rightarrow \infty} \mathbb{E}_{x}\left[e^{-\Lambda_{v}} Q_{h}\left(X_{v}\right) \mathbf{1}_{\left\{v \leq T_{\alpha_{m}} \wedge T_{\beta_{n}}\right\}}\right]=\mathbb{E}_{x}\left[e^{-\Lambda_{v}} Q_{h}\left(X_{v}\right) \mathbf{1}_{\{v<\infty\}}\right]
$$

and

$$
\lim _{m, n \rightarrow \infty} \mathbb{E}_{x}\left[\int_{0}^{T_{\alpha_{m}} \wedge T_{\beta_{n}} \wedge v} e^{-\Lambda_{t}} d A_{t}^{h}\right]=\mathbb{E}_{x}\left[\int_{0}^{v} e^{-\Lambda_{t}} d A_{t}^{h}\right]
$$

while Lemma 2 implies

$$
\begin{align*}
\lim _{m, n \rightarrow \infty} \mathbb{E}_{x} & {\left[e^{-\Lambda_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}} Q_{h}\left(X_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}\right) 1_{\left\{T_{\alpha_{m}} \wedge T_{\beta_{n}}<v\right\}}\right] } \\
& \leq \lim _{m, n \rightarrow \infty} \mathbb{E}_{x}\left[e^{-\Lambda_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}} Q_{h}\left(X_{T_{\alpha_{m}} \wedge T_{\beta_{n}}}\right)\right] \\
& =0 . \tag{67}
\end{align*}
$$

In view of these observations, we can pass to the limits $m, n \rightarrow \infty$ in (66) to obtain (61). Finally, (62) follows from (60) and (61), while (63) follows from $(60),(61)$ and the monotone convergence theorem.

When the measure $h$ belongs to $\Sigma_{\phi, \psi}$ but not to $\mathcal{I}_{\phi, \psi}$, we do not have a nice probabilistic characterisation of the solution $Q_{h}$ to the ODE (1) such as the one in the previous proposition. However, we should observe the following result that is a restatement of (64).
Lemma 7 Suppose that Assumptions 2.1-2.3 are satisfied, and consider any measure $h \in \Sigma_{\phi, \psi}$. Given a strictly decreasing sequence $\left(\alpha_{m}\right)$ and a strictly increasing sequence $\left(\beta_{n}\right)$ satisfying (25),

$$
\begin{equation*}
Q_{h}(x)=\lim _{m, n \rightarrow \infty} \mathbb{E}_{x}\left[\int_{0}^{T_{\alpha_{m}} \wedge T_{\beta_{n}}} e^{-\Lambda_{t}} d A_{t}^{h}\right] \tag{68}
\end{equation*}
$$

where $T_{\alpha_{m}}$ and $T_{\beta_{n}}$ are the first hitting times defined as in (17).
Finally, we can consider the following example that highlights the importance of the boundary points $\alpha$ and $\beta$ classification to the validity of (49) in Proposition 4.

Example 4.2 Suppose that $\mathcal{J}=] 0, \infty[$, and that $b(x)=\kappa(\theta-x)$ and $\sigma(x)=$ $\sigma \sqrt{x}$, for some constants $\kappa, \theta, \sigma>0$ such that $\kappa \theta-\frac{1}{2} \sigma^{2}>0$. The associated Itô diffusion $X$ is the square-root mean-reverting process appearing in the Cox-Ingersoll-Ross interest rate model. Also, 0 is an entrance boundary point, and, if we choose $r(x)=r_{0}$, for some constant $r_{0}>0$, then Assumptions 2.1-2.3 are all satisfied. It is a standard exercise to calculate $\mathbb{E}_{x}\left[X_{t}\right]=\theta+(x-\theta) e^{-\kappa t}$. In view of this calculation, we can see that if $h$ is the measure defined by $h(d x)=x d x$, then

$$
\lim _{x \downarrow 0} Q_{h}(x) \equiv \lim _{x \downarrow 0} R_{h}(x)=\frac{\theta \kappa}{r_{0}\left(r_{0}+\kappa\right)}>0=\lim _{x \downarrow 0} \frac{h_{\mathrm{ac}}(x)}{r(x)} \equiv r-\lim _{0} h .
$$

## Acknowledgements

We are grateful to several participants in the Optimal Stopping with Applications Symposium that was held in Manchester on 22-27 January 2006, where part of the results in this paper were presented by the second author, for numerous helpful discussions. We are indebted to Andrew Jack and Damien Lamberton whose critical and detailed comments lead to a significant enhancement of the paper. We also thank an anonymous referee for several useful comments.

## References

[1] Alvarez, L. H. R., 2001, Reward functionals, salvage values, and optimal stopping. Mathematical Methods of Operations Research, 54, 315-337.
[2] Alvarez, L. H. R., 2001, Singular stochastic control, linear diffusions, and optimal stopping: a class of solvable problems. SIAM Journal on Control and Optimization, 39, 1697-1710.
[3] Alvarez, L. H. R., 2003, On the properties of $r$-excessive mappings for a class of diffusions. Annals of Applied Probability 13, 1517-1533.
[4] Alvarez, L. H. R., 2004, A class of solvable impulse control problems. Applied Mathematics and Optimization, 49, 265-295.
[5] Beibel, M. and Lerche, H. R., 2002, A note on optimal stopping of regular diffusions under random discounting. Theory of Probability and its Applications, 45, 547-557.
[6] Beneš, V. E., Shepp, L. A. and Witsenhausen, H. S., 1980, Some solvable stochastic control problems. Stochastics and Stochastics Reports, 4, 39-83.
[7] Borodin, A. N. and Salminen, P., 2002, Handbook of Brownian Motion - Facts and Formulae (Birkhäuser).
[8] Breiman, L., 1968, Probability (Addison-Wesley).
[9] Davis, M. H. A. and Zervos, M., 1998, A pair of explicitly solvable singular stochastic control problems. Applied Mathematics and Optimization, 38, 327-352.
[10] Dayanik, S. and Karatzas, I., 2003, On the optimal stopping problem for one-dimensional diffusions. Stochastic Processes and their Applications, 107, 173-212.
11] Duckworth, K. and Zervos, M., 2001, A model for investment decisions with switching costs. The Annals of Applied Probability, 11, 239-260.
12] Feller, W., 1954, The general diffusion operator and positivity preserving semi-groups in one dimension. Annals of Mathematics, 60, 417-436.
[13] Guo, X. and Shepp, L. A., 2001, Some optimal stopping problems with nontrivial boundaries for pricing exotic options. Journal of Applied Probability, 38, 647-658.
[14] Harrison, J. M. and Taksar, M. I., 1983, Instantaneous control of Brownian motion. Mathematics of Operations research, 8, 439-453.
15] Harrison, J. M. and Taylor, A. J., 1978, Optimal control of a Brownian storage system. Stochastic Processes and Their Applications, 6, 179-194.
[16] Itô, K. and McKean, H. P., 1996, Diffusion Processes and their Sample Paths (Springer-Verlag).
[17] Jacka, S. D., 1983, A finite fuel stochastic control problem. Stochastics, 10, 103-113.
[18] Jacka, S. D., 2002, Avoiding the origin: a finite-fuel stochastic control problem. Annals of Applied Probability, 12, 1378-1389.
[19] Karatzas, I., 1983, A class of singular stochastic control problems. Advances in Applied Probability, 15, 225-254.
[20] Karatzas, I. and Ocone, D., 2002, A leavable bounded-velocity stochastic control problem. Stochastic Processes and their Applications, 99, 31-51.
[21] Karatzas, I., Ocone, D., Wang, H. and Zervos, M., 2000, Finite-fuel singular control with discretionary stopping. Stochastics and Stochastics Reports, 71, 1-50.
[22] Karatzas, I. and Shreve, S. E., 1988, Brownian Motion and Stochastic Calculus (SpringerVerlag).
[23] Karatzas, I. and Sudderth, W. D., 1999, Control and stopping of a diffusion process on an interval. Annals of Applied Probability, 9, 188-196.
24] Karlin, S. and Taylor, H. M., 1981, A Second Course in Stochastic Processes (Academic Press).
[25] Ma, J., 1992, On the principle of smooth fit for a class of singular stochastic control problems for diffusions. SIAM Journal on Control and Optimization, 30, 975-999.
26] Mandl, P., 1968, Analytical Treatment of One-dimensional Markov Processes (Springer-Verlag).
[27] Øksendal, A., 2000, Irreversible investment problems. Finance and Stochastics, 4, 223-250.
[28] Øksendal, A., 2001, Mathematical Models for Investment under Uncertainty (PhD thesis, University of Oslo).
[29] Revuz, D. and Yor, M., 1994, Continuous Martingales and Brownian Motion (2nd edition, Springer-Verlag).
[30] Rogers, L. C. G. and Williams, D., 2000, Diffusions, Markov Processes and Martingales, Volume 2 (Cambridge University Press).
[31] Salminen, P., 1985, Optimal stopping of one-dimensional diffusions. Mathematische Nachrichten, 124, 85-101.
[32] Shiryayev, A. N., 1978, Optimal Stopping Rules (Springer-Verlag).
[33] Shiryaev, A. and Peskir, G., 2006, Optimal Stopping and Free-Boundary Problems (Lectures in Mathematics, ETH Zürich, Birkhäuser).
[34] Shreve, S. E., Lehoczky, J. P. and Gavers, D. P., 1984, Optimal consumption for general diffusions with absorbing and reflecting barriers. SIAM Journal on Control and Optimization, 22, 55-75.


[^0]:    ${ }^{\dagger}$ Research supported by EPSRC grant no. GR/S22998/01
    ${ }^{\ddagger}$ Department of Actuarial Mathematics and Statistics, School of Mathematical and Computer Sciences, Heriot-Watt University, Edinburgh EH14 4AS, UK, e-mail: t.c.johnson@hw.ac.uk
    ${ }^{\S}$ Department of Mathematics, London School of Economics, Houghton Street, London WC2A 2AE, UK, e-mail: m.zervos@lse.ac.uk

