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SETTER
MALHAM

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QUESTION
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SOLUTION
1

$$(a) \delta J(\gamma(x), \eta(x)) = \frac{d}{d\varepsilon} J(\underbrace{\gamma(x) + \varepsilon \eta(x)}_{\gamma(x; \varepsilon)}) \Big|_{\varepsilon=0} = 0, \quad \forall \eta$$

$\Rightarrow \gamma(x)$ is the extremising curve.

$$\begin{aligned} \delta J &= \int_a^b \frac{\partial}{\partial \varepsilon} F(x, \gamma(x; \varepsilon), \gamma_x(x; \varepsilon)) dx \Big|_{\varepsilon=0} \\ &= \int_a^b \frac{\partial F}{\partial \gamma(x; \varepsilon)} \cdot \eta(x) + \frac{\partial F}{\partial \gamma_x(x; \varepsilon)} \cdot \eta_x(x) dx \Big|_{\varepsilon=0} \\ &= \int_a^b \left(\frac{\partial F}{\partial \gamma} - \frac{d}{dx} \left(\frac{\partial F}{\partial \gamma_x} \right) \right) \eta(x) dx \end{aligned}$$

using integration by parts & that $\eta(a) = \eta(b) = 0$.

$\delta J = 0$ for all twice continuously differentiable $\eta(x)$

$$\Rightarrow \frac{\partial F}{\partial \gamma} - \frac{d}{dx} \left(\frac{\partial F}{\partial \gamma_x} \right) = 0. \quad \oplus$$

$$\begin{aligned} \frac{d}{dx} \left(\gamma' \frac{\partial F}{\partial \gamma'} - F \right) &= \gamma'' \frac{\partial F}{\partial \gamma'} + \gamma' \frac{d}{dx} \left(\frac{\partial F}{\partial \gamma'} \right) - \frac{dF}{dx} \\ &= \gamma'' F_{\gamma'} + \gamma' \frac{d}{dx} F_{\gamma'} - F_x - F_{\gamma} \gamma' - F_{\gamma'} \gamma'' \\ &= -\gamma' \left(F_{\gamma} - \frac{d}{dx} F_{\gamma'} \right) - F_x \end{aligned}$$

$$\begin{aligned} \text{Hence } \frac{\partial F}{\partial x} + \frac{d}{dx} \left(\gamma' \frac{\partial F}{\partial \gamma'} - F \right) &= -\gamma' \left(\frac{\partial F}{\partial \gamma} - \frac{d}{dx} \left(\frac{\partial F}{\partial \gamma'} \right) \right) \\ &= 0 \quad \text{using } \oplus. \end{aligned}$$

SETTER'S SIGNATURE *Demir Malham*

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24/9/2000

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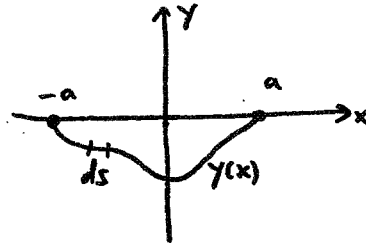
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(b) mass of chain element = $\rho g ds$

potential energy = $\int \rho g ds \cdot y$

Total PE = $J = \int_{-a}^a \rho g y ds$

$= \int_{-a}^a \rho g y \sqrt{1+y'^2} dx.$



Constraint: $\int_{-a}^a ds = \int_{-a}^a \sqrt{1+y'^2} dx = l.$

Method of Lagrange multipliers \Rightarrow minimise $\bar{J} = \int_{-a}^a F(y, y', \lambda) dx$

where $F = (y+\lambda)(1+y'^2)^{1/2}$. Last part of (a) \Rightarrow

$y' F_{y'} - F = \text{const}$ (no explicit x in F).

$\Rightarrow [y'^2(1+y'^2)^{-1/2} - (1+y'^2)^{1/2}](y+\lambda) = \text{const} = A^{-1}$

$\Rightarrow y'^2 = A^2(y+\lambda)^2 - 1$

Sub^{stn} $a(y+\lambda) = \cosh \theta$ and integration \Rightarrow

$y = A^{-1} \cosh[A(x+B)] - \lambda$

Symmetry about origin $\Rightarrow B \equiv 0$

$x = \pm a, y = 0 \Rightarrow A\lambda = \cosh[Aa]$ $\textcircled{\oplus}$

Chain length $l = \int_{-a}^a (1 + \sinh^2(Ax))^{1/2} dx$

$\Rightarrow Al = 2 \sinh[Aa]$ $\textcircled{\oplus}$

$\textcircled{\oplus} \& \textcircled{\oplus}$ determine A & λ .

$l > 2a$ for solution, otherwise chain not long enough!

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QUESTION
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SOLUTION

Let $x(t), y(t)$ be coordinates of mass m .

$$x(t) = \mu(t) + l \sin \theta(t)$$

$$y(t) = -l \cos \theta(t)$$

$$L = T - V = \frac{1}{2} M \dot{\mu}^2 + \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) - mgy$$

$$\Rightarrow L = \frac{1}{2} M \dot{\mu}^2 + \frac{1}{2} m (\dot{\mu}^2 + l^2 \dot{\theta}^2 + 2l\dot{\mu}\dot{\theta} \cos \theta) + mgl \cos \theta.$$

$$P_{\mu} = \frac{\partial L}{\partial \dot{\mu}} = (M+m)\dot{\mu} + ml\dot{\theta} \cos \theta$$

$$P_{\theta} = \frac{\partial L}{\partial \dot{\theta}} = ml^2\dot{\theta} + 2l\dot{\mu} \cos \theta$$

\hookrightarrow independent of explicit t and $\mu \Rightarrow H$ and P_{μ} are constants of the motion.

$$P_{\mu} \equiv 0 \Rightarrow \text{after integration } (M+m)\mu = -ml \sin \theta + A$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0 \Rightarrow$$

$$ml^2\ddot{\theta} + \frac{d}{dt}(2l\dot{\mu} \cos \theta) + ml\dot{\mu}\dot{\theta} \sin \theta + mgl \sin \theta = 0$$

$$\text{where } \dot{\mu} = \frac{-ml\dot{\theta} \cos \theta}{M+m}.$$

SETTER'S SIGNATURE *Simon Mellor*

CHECKER'S SIGNATURE *Dr. S. L. White*

DATE *8th March 1999*

EXAMINATION QUESTIONS/SOLUTIONS SESSION 1998/99

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COURSE

M2A2

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QUESTION

SOLUTION

$$u = \frac{-ml}{M+m} \sin\theta + \frac{A}{M+m}, \quad \text{Let } \tilde{A} = \frac{A}{M+m}$$

$$\Rightarrow x(t) - \tilde{A} = \left(l - \frac{ml}{M+m} \right) \sin\theta \Rightarrow \text{result.}$$

$$\text{If } \tilde{m} = \frac{Ml}{M+m} \text{ then } \frac{(x - \tilde{A})^2}{\tilde{m}^2} + \frac{y^2}{l^2} = 1,$$

Ellipse. Arc of an Ellipse!

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[Signature]

DATE

8th March 1999

2

2+2

2

Couette flow problem (Chorin & Marsden, pg. 31)

In cylindrical coordinates (r, θ, z) , $\underline{u} = (u_r, u_\theta, u_z)$
the Euler eqns are

$$\frac{\partial u_r}{\partial t} + (\underline{u} \cdot \nabla) u_r - \frac{u_\theta^2}{r} = -\frac{1}{\rho_0} \frac{\partial p}{\partial r} + f_r$$

$$\frac{\partial u_\theta}{\partial t} + (\underline{u} \cdot \nabla) u_\theta + \frac{u_r u_\theta}{r} = -\frac{1}{\rho_0 r} \frac{\partial p}{\partial \theta} + f_\theta$$

$$\frac{\partial u_z}{\partial t} + (\underline{u} \cdot \nabla) u_z = -\frac{1}{\rho_0} \frac{\partial p}{\partial z} + f_z$$

where $p = p(r, \theta, z, t)$ is the pressure, ρ_0 is the uniform density & $\underline{f} = (f_r, f_\theta, f_z)$ is the body force per unit mass.

Here,

$$\underline{u} \cdot \nabla \equiv u_r \frac{\partial}{\partial r} + \frac{u_\theta}{r} \frac{\partial}{\partial \theta} + u_z \frac{\partial}{\partial z}$$

Further, the incompressibility condition is

$$\frac{1}{r} \frac{\partial (r u_r)}{\partial r} + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial u_z}{\partial z} = 0.$$

We will also need the identities:

$$\nabla\phi = \left(\frac{\partial\phi}{\partial r}, \frac{1}{r} \frac{\partial\phi}{\partial\theta}, \frac{\partial\phi}{\partial z} \right)$$

$$\nabla \times \underline{u} = \left(\frac{1}{r} \frac{\partial u_z}{\partial\theta} - \frac{\partial u_\theta}{\partial z}, \frac{\partial u_r}{\partial z} - \frac{\partial u_z}{\partial r}, \frac{1}{r} \frac{\partial(r u_\theta)}{\partial r} - \frac{1}{r} \frac{\partial u_r}{\partial\theta} \right)$$

(a) Required to show that flow field given is a stationary solution of Euler's eqn's with $\rho \equiv 1$.

Using $u_r = 0$, $u_z = 0$, $u_\theta = \frac{A}{r} + Br$ (all three components also independent of θ & z) \Rightarrow

$$-\frac{u_\theta^2}{r} = -\frac{\partial p}{\partial r} \quad (\text{no body force})$$

$$0 = -\frac{1}{r} \frac{\partial p}{\partial\theta}$$

$$0 = -\frac{\partial p}{\partial z}$$

and note that the incompressibility condition is identically satisfied. Hence p indep't of θ & z

$$\Rightarrow \frac{\partial p}{\partial r} = \frac{1}{r} \left(\frac{A}{r} + Br \right)^2.$$

$$\Rightarrow \frac{\partial p}{\partial r} = \frac{A^2}{r^3} + \frac{2AB}{r} + B^2 r$$

$$\Leftrightarrow p = -\frac{1}{2} \frac{A^2}{r^2} + 2AB \log(r) + \frac{1}{2} B^2 r^2 + K$$

where K is an arbitrary constant. Hence we have shown there exists a pressure field so that (u_r, u_θ, u_z) and p satisfy Euler's equations and the incompressibility condition.

$$\begin{aligned} \text{(b)} \quad \underline{\omega} &= \nabla \times \underline{u} = \left(0, 0, \frac{1}{r} \frac{\partial}{\partial r} (r u_\theta) \right) \\ &= (0, 0, 2B) \end{aligned}$$

$$\begin{aligned} \text{(c)} \quad D &:= \frac{1}{2} \left((\nabla \underline{u}) + (\nabla \underline{u})^T \right) \\ &= \frac{1}{2} \begin{pmatrix} \frac{\partial u_r}{\partial r} & \frac{1}{r} \frac{\partial u_r}{\partial \theta} & \frac{\partial u_r}{\partial z} \\ \frac{\partial u_\theta}{\partial r} & \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} & \frac{\partial u_\theta}{\partial z} \\ \frac{\partial u_z}{\partial r} & \frac{1}{r} \frac{\partial u_z}{\partial \theta} & \frac{\partial u_z}{\partial z} \end{pmatrix} + \frac{1}{2} (\nabla \underline{u})^T \end{aligned}$$

$$\Rightarrow D = \frac{1}{2} \begin{pmatrix} 0 & 0 & 0 \\ -\frac{A}{r^2} + B & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & -\frac{A}{r^2} + B & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow D = \frac{1}{2} \left(-\frac{A}{r^2} + B \right) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \text{(ignoring the z-coord)}$$

Deformation tensor describes the expansion or contraction along characteristic directions of a fluid parcel.

(d) $u_\theta = \text{angular velocity} = u_\theta(r)$.

Two cylinders are $r = R_1$ and $r = R_2$.

$$u_\theta(R_1) = \frac{A}{R_1} + BR_1 = \frac{-R_1 R_2^2 (\omega_2 - \omega_1)}{R_2^2 - R_1^2} - R_1 \frac{(R_1^2 \omega_1 - R_2^2 \omega_2)}{R_2^2 - R_1^2}$$

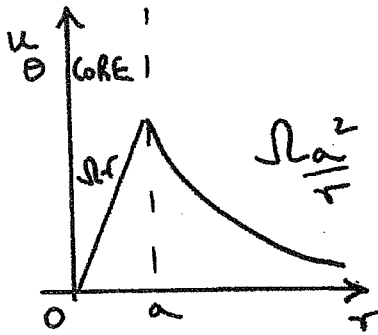
$$= \frac{+R_1 R_2^2 \omega_1 - R_1^3 \omega_1}{R_2^2 - R_1^2} = R_1 \omega_1$$

$$u_\theta(R_2) = \frac{A}{R_2} + BR_2 = \frac{-R_1^2 R_2 (\omega_2 - \omega_1)}{R_2^2 - R_1^2} - R_2 \frac{(R_1^2 \omega_1 - R_2^2 \omega_2)}{R_2^2 - R_1^2}$$

$$= \frac{-R_1^2 R_2 \omega_2 + R_2^3 \omega_2}{R_2^2 - R_1^2} = R_2 \omega_2$$

4.

(*)



(i) acceleration

$$\underline{a_c} = -\frac{u_\theta^2}{r} \hat{r} = -\frac{1}{\rho} \frac{\partial p}{\partial r} \hat{r} - \frac{1}{\rho} \frac{\partial p}{\partial z} \hat{k} - g \hat{k}$$

Euler.

per unit mass

$$\text{so } \frac{\partial p}{\partial z} = -g\rho$$

2

$$\frac{\partial p}{\partial r} = \begin{cases} \rho \Omega^2 r & (r \leq a) \\ \rho \Omega^2 \frac{a^4}{r^3} & (r > a) \end{cases}$$

$$\Rightarrow p = \begin{cases} p_0 - g\rho z + \frac{1}{2} \rho \Omega^2 r^2 & (r \leq a) \\ p_0 - g\rho z - \frac{1}{2} \rho \Omega^2 \frac{a^4}{r^2} + \rho \Omega^2 a^2 & (r > a) \end{cases}$$

2

2

p continuous at $r=a$ $r=0, z=0$ on axis at free surface

$$\text{Hence } p=p_0 \Rightarrow z = \begin{cases} \frac{\Omega^2}{2g} r^2 & (r \leq a) \\ \frac{\Omega^2 a^2}{g} - \frac{\Omega^2 a^4}{2g r^2} & (r > a) \end{cases}$$

$$\text{i.e. } \alpha = \frac{\Omega^2}{2g} \text{ and } F(r) = \frac{\Omega^2 a^2}{g} - \frac{\Omega^2 a^4}{2g r^2}$$

$$(ii) H = \frac{p}{\rho} + \frac{1}{2} u^2 + gz$$

$$= \begin{cases} \frac{p_0}{\rho} + \Omega^2 r^2 & (r \leq a) \\ \frac{p_0}{\rho} + \Omega^2 a^2 & (r > a) \end{cases}$$

2

Bernoulli theorem: H constant along streamlines and along vortex lines since flow is steady and ρ is uniform. Furthermore H is constant throughout a region where $\underline{\omega} = \nabla \times \underline{u} = \underline{0}$. (irrotational). 3

For this example: streamlines are horizontal circles

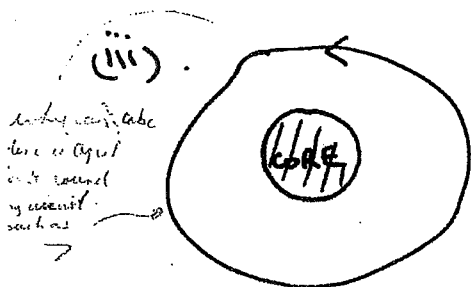
$$\begin{aligned} r &= \text{const} \\ z &= \text{const} \end{aligned}$$

for $r \leq a$ vortex lines are vertical straight lines

$$\begin{aligned} r &= \text{const} \\ \theta &= \text{const} \end{aligned} \quad 3$$

$$\text{for } r > a \quad \nabla \times \underline{u} \equiv \underline{0}.$$

So we expect H to be a function of r (only) when $r \leq a$ and constant for $r > a$.



$$\begin{aligned} K &= \oint_C \underline{u} \cdot d\underline{s} = 2\pi \int_0^a \Omega r^2 \frac{dr}{r} = 2\pi (\Omega a^2) \\ &= \int_S \underline{\omega} \cdot d\underline{S} = \int_{\text{CIRCULAR CORE}} (2\Omega \underline{k}) \cdot d\underline{S} \\ &= (2\Omega)(\pi a^2) \end{aligned} \quad 2$$

So K constant

$$\Rightarrow \Omega a^2 \text{ constant}$$

From part (i) $\mathcal{D} = \frac{\Omega^2 a^2}{g}$ i.e. $z(\infty) - z(=0)$
(Using this in part (i) to get \mathcal{D})

so that $\mathcal{D} = \left(\frac{K^2}{4\pi^2 g} \right) \frac{1}{a^2}$ i.e. $\mathcal{D} \propto \frac{1}{a^2}$ 2

5) $u_t = u_{xx} \quad 0 < x < 1, t > 0$

We seek solutions of the form $u(x,t) = X(x)T(t)$

Since ends are fixed at same horizontal level we require $X(0) = 0 = X(1)$

Substituting into the equation we require

$$T''(t)X(x) = T(t)X''(x)$$

Thus it suffices to find X and T such that

$$\frac{T''}{T} = \frac{X''}{X} = -k \quad \text{where } k \text{ is a constant}$$

$$-X' = kX \quad X(0) = 0 = X(1) \quad (1)$$

$$-T'' = kT \quad (2)$$

(1) has non-zero solutions iff $k = n^2\pi^2$ with corresponding solutions

1. $\sin n\pi x$ for $n = 1, 2, \dots$

1. If $k = n^2\pi^2$, (2) has general solution $T(t) = A_n \cos n\pi t + B_n \sin n\pi t$

Hence any function of the form

$$u(x,t) = \sum_{n=1}^{\infty} (A_n \cos n\pi t + B_n \sin n\pi t) \sin n\pi x$$

3. In order to satisfy boundary conditions,

1. If $u(x,0) = \sin 2\pi x$ we require $\sin 2\pi x = \sum_{n=1}^{\infty} A_n \sin n\pi x$

2. This requires $A_2 = 1$ and $A_n = 0$ for $n \neq 2$.

Now

$$u_t(x,t) = \sum_{n=1}^{\infty} (-n\pi A_n \sin n\pi t + n\pi B_n \cos n\pi t) \sin n\pi x$$

Since $u_t(x,0) = x$ we require

$$x = \sum_{n=1}^{\infty} n\pi B_n \sin n\pi x$$

$$n\pi B_n = \frac{2}{1} \int_0^1 x \sin n\pi x \, dx$$

$$= 2 \left[-\frac{1}{n\pi} x \cos n\pi x \right]_0^1 + \frac{1}{n\pi} \int_0^1 \cos n\pi x \, dx$$

$$= -\frac{2}{n\pi} \cos n\pi = (-1)^{n+1} \frac{2}{n\pi}$$

4. $B_n = (-1)^{n+1} \frac{2}{n^2\pi^2}$

(b) $E(t) = \frac{1}{2} \int_0^1 [u_x^2(x,t) + u_t^2(x,t)] \, dx$

Therefore Hence $\frac{dE}{dt} = \int_0^1 [u_x(x,t)u_{xt}(x,t) + u_t(x,t)u_{tt}(x,t)] \, dx$

$$B \text{ total} = u_x(x,t) u_t(x,t) \Big|_{x=0}^{x=1} - \int_0^1 u_{xx}(x,t) u_t(x,t) dx + \int_0^1 u_x(x,t) u_{tt}(x,t) dx$$

Since $u(0,t) \equiv 0$, $u_t(0,t) = 0$; similarly $u_t(1,t) \equiv 0$.

$$\text{Hence } \frac{dE}{dt} = \int_0^1 [u_{tt}(x,t) - u_{xx}(x,t)] u_t(x,t) dx = 0 \text{ as } u_{tt} \equiv u_{xx}$$

Thus $E(t) \equiv E(0) = 0$ as $u(x,0) \equiv u_t(x,0) \equiv 0$.

$$\text{Hence } \int_0^1 [u_x^2(x,t) + u_t^2(x,t)] dx = 0$$

Thus $u_x(x,t) \equiv u_t(x,t) \equiv 0$ and so $u(x,t) \equiv \text{constant}$

6 Hence as $u(x,0) \equiv 0$, $u(x,t) \equiv 0$

(a) $u_t = u_{xx} \quad 0 < x < \pi \quad t > 0; \quad u(0,t) = u(\pi,t) = 0$

We seek solutions of the form $u(x,t) = X(x)T(t)$

To ensure that $u(0,t) = u(\pi,t) = 0$ we require $X(0) = 0 = X(\pi)$.

$u_t = u_{xx} \Rightarrow X(x)T'(t) = X''(x)T(t)$

$\Rightarrow \frac{X''(x)}{X(x)} = \frac{T'(t)}{T(t)} = -k$ where k is a constant.

(1) $-X'' = kX \quad X(0) = 0 = X(\pi)$

(2) $T' = -kT$

(1) has non-zero solutions iff $k = m^2$ for $m = 1, 2, \dots$ with solutions

$\sin m\pi x$.

(2) has general solution $T(t) = A_m e^{-m^2 t}$

Hence any function of the form

$u(x,t) = \sum_{m=1}^{\infty} A_m \sin m\pi x e^{-m^2 t}$

is a solution of the PDE satisfying the boundary conditions

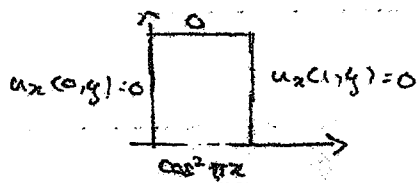
Since $u(x,0) = \sin x \cos x = \frac{1}{2} \sin 2x$ we require

$\frac{1}{2} \sin 2x = \sum_{m=1}^{\infty} A_m \sin m\pi x$

and so we choose $A_2 = \frac{1}{2}$ and $A_m = 0$ for $m \neq 2$

Hence solution is $u(x,t) = \frac{1}{2} e^{-4t} \sin 2x$

(b)



$u_{xx} + u_{yy} = 0$

We seek solutions of the form $u(x,y) = X(x)Y(y)$.

Since $u_x(0,y) = 0 = u_x(1,y)$, we require $X'(0) = 0 = X'(1)$.

Since $u(x,2) = 0$ we require $Y(2) = 0$

$u_{xx} + u_{yy} = 0 \Leftrightarrow X''(x)Y(y) + X(x)Y''(y) = 0$

$\Rightarrow \frac{X''}{X} = -\frac{Y''}{Y} = -k$ where k is a constant.

(1) $X'' = -kX \quad X'(0) = 0 = X'(1)$

(2) $Y' = kY \quad Y(0) = 0$

Q. 10

① has non zero solutions iff $k = 0, \pi^2, 4\pi^2, \dots$ and the corresponding solutions are $1, \cos \pi x, \cos 2\pi x, \dots$

If $k = 0$, ② has general solution $Y(y) = A(2-y)$

If $k = n^2\pi^2$, ② has general solution $Y(y) = A \sinh n\pi(2-y)$

Thus we have the general solution

$$u(x, y) = A_0(2-y) + \sum_{n=1}^{\infty} A_n \cos n\pi x \sinh n\pi(2-y)$$

1)

If $u(x, 0) = \cos^2 \pi x = \frac{1}{2}(\cos 2\pi x + 1)$ we require

$$\frac{1}{2}(\cos 2\pi x + 1) = A_0 \cdot 2 + \sum_{n=1}^{\infty} A_n \sinh 2n\pi \cos n\pi x$$

Thus we choose $A_0 = \frac{1}{4}$, $A_2 = \frac{1}{2 \sinh 4\pi}$, $A_n = 0$, $n \neq 0, 2$

Thus we have solution

$$u(x, y) = \frac{1}{4}(2-y) + \frac{1}{2 \sinh 4\pi} \cos 2\pi x \sinh 2\pi(2-y)$$