

**Question 1 (20 Marks)**

A soap film is stretched between two rings of radius  $a$  which lie in parallel planes a distance  $2x_0$  apart—the axis of symmetry of the two rings is coincident—see Figure 1.

- (a) Explain why the surface area of the surface of revolution is given by

$$J(y) = 2\pi \int_{-x_0}^{x_0} y \sqrt{1 + (y_x)^2} dx,$$

where the radius of the surface of revolution is given by  $y = y(x)$  for  $x \in [-x_0, x_0]$ .

- (b) Show that extremizing the surface area  $J(y)$  in part (a) leads to the following ordinary differential equation for  $y = y(x)$  (*hint*: you may find the alternative form for the Euler–Lagrange equation useful here):

$$\left(\frac{dy}{dx}\right)^2 = C^{-2}y^2 - 1$$

where  $C$  is an arbitrary constant.

- (c) Use the substitution  $y = C \cosh \theta$  and the identity  $\cosh^2 \theta - \sinh^2 \theta = 1$  to show that the solution to the ordinary differential equation in part (b) is

$$y = C \cosh(C^{-1}(x + b))$$

where  $b$  is another arbitrary constant. Explain why we can deduce that  $b = 0$ .

- (d) Using the end-point conditions  $y = a$  at  $x = \pm x_0$ , discuss the existence of solutions in relation to the ratio  $a/x_0$ .

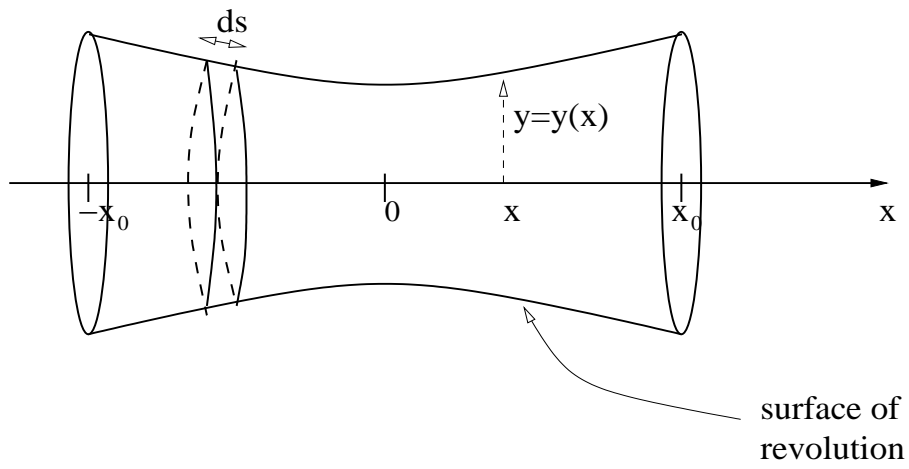


Figure 1: Soap film stretched between two concentric rings. The radius of the surface of revolution is given by  $y = y(x)$  for  $x \in [-x_0, x_0]$ .

**Question 2 (20 Marks)**

The *swinging Atwood's machine* is a mechanism that resembles a simple Atwood's machine except that one of the masses is allowed to swing in a two-dimensional plane—see Figure 2. A string of length  $\ell$ , with a mass  $M$  at one end and a mass  $m$  at the other, is stretched over two frictionless pulleys as shown in Figure 2. The mass  $M$  hangs vertically downwards; it only moves up and down. The mass  $m$  on the other hand is free to swing in a vertical plane as shown. The Lagrangian for this system has the form

$$L(r, \theta, \dot{r}, \dot{\theta}) = \frac{1}{2}(M + m)\dot{r}^2 + \frac{1}{2}mr^2\dot{\theta}^2 - gr(M - m \cos \theta),$$

where  $(r, \theta)$  are the plane polar coordinates of the mass  $m$  that can swing in the vertical plane. Here  $g$  is the acceleration due to gravity.

- (a) Show that the generalized momenta  $p_r$  and  $p_\theta$  corresponding to the coordinates  $r$  and  $\theta$ , respectively, are given by

$$p_r = (M + m)\dot{r} \quad \text{and} \quad p_\theta = mr^2\dot{\theta}.$$

- (b) Using the results from part (a), show that the Hamiltonian for this system is given by

$$H(r, \theta, p_r, p_\theta) = \frac{p_r^2}{2(M + m)} + \frac{p_\theta^2}{2mr^2} + gr(M - m \cos \theta).$$

- (c) Explain why the Hamiltonian  $H$  is a constant of the motion. Is the Hamiltonian  $H$  equal to the total energy?
- (d) By either using Lagrange's equations of motion, or, using Hamilton's equations of motion, show that the swinging Atwood's machine evolves according to a pair of second order ordinary differential equations

$$\begin{aligned} \ddot{r} &= \frac{1}{M + m}(mr\dot{\theta}^2 - g(M - m \cos \theta)), \\ r\ddot{\theta} &= -2\dot{r}\dot{\theta} - g \sin \theta. \end{aligned}$$

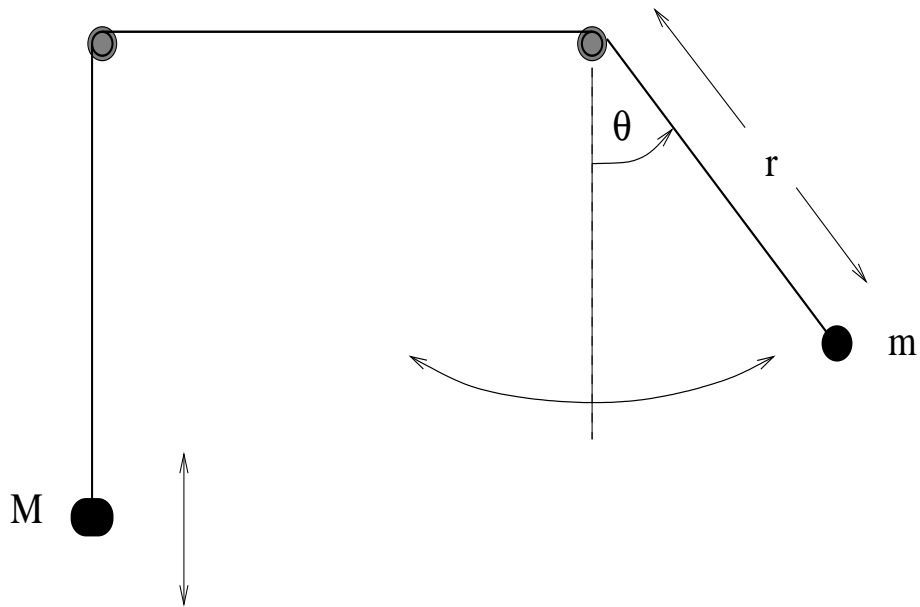


Figure 2: Swinging Atwood's machine: a string of length  $\ell$ , with a mass  $M$  at one end and a mass  $m$  at the other, is stretched over two pulleys. The mass  $M$  hangs vertically downwards; it only moves up and down. The mass  $m$  is free to swing in a vertical plane.

**Question 3 (20 Marks)**

- (a) Using the Euler equations for an ideal incompressible flow in cylindrical coordinates (see the formulae sheet at the end of the exam paper) show that at position  $(r, \theta, z)$  with  $z$  the coordinate in the vertical upward direction, for a *stationary* flow which is independent of  $\theta$  with  $u_r = u_z = 0$ , we have

$$\frac{u_\theta^2}{r} = \frac{1}{\rho} \frac{\partial p}{\partial r},$$

$$0 = \frac{1}{\rho} \frac{\partial p}{\partial z} + g,$$

where  $p = p(r, z)$  is the pressure,  $\rho$  is the constant uniform mass density and  $g$  is the acceleration due to gravity (assume this to be the body force per unit mass).

- (b) Let  $\Omega$  be the region between two concentric cylinders of radii  $R_1$  and  $R_2$ , where  $R_1 < R_2$ . Suppose the velocity field in cylindrical coordinates  $\mathbf{u} = (u_r, u_\theta, u_z)$  of the fluid flow inside  $\Omega$ , is given by

$$u_r = 0, \quad u_z = 0, \quad \text{and} \quad u_\theta = \frac{A}{r} + Br,$$

where

$$A = -\frac{R_1^2 R_2^2 (\omega_2 - \omega_1)}{R_2^2 - R_1^2} \quad \text{and} \quad B = -\frac{R_1^2 \omega_1 - R_2^2 \omega_2}{R_2^2 - R_1^2}.$$

This is known as a *Couette flow*—see Figure 3. Show that the:

- (i) velocity field  $\mathbf{u} = (u_r, u_\theta, u_z)$  is a stationary solution of Euler's equations of motion for an ideal fluid with density  $\rho \equiv 1$  (*hint*: you need to find a pressure field  $p$  that is consistent with the velocity field given);
- (ii) angular velocity of the flow (i.e. the quantity  $u_\theta/r$ ) is  $\omega_1$  on the cylinder  $r = R_1$  and  $\omega_2$  on the cylinder  $r = R_2$ .
- (iii) the vorticity field  $\boldsymbol{\omega} = \nabla \times \mathbf{u} = (0, 0, 2B)$ .

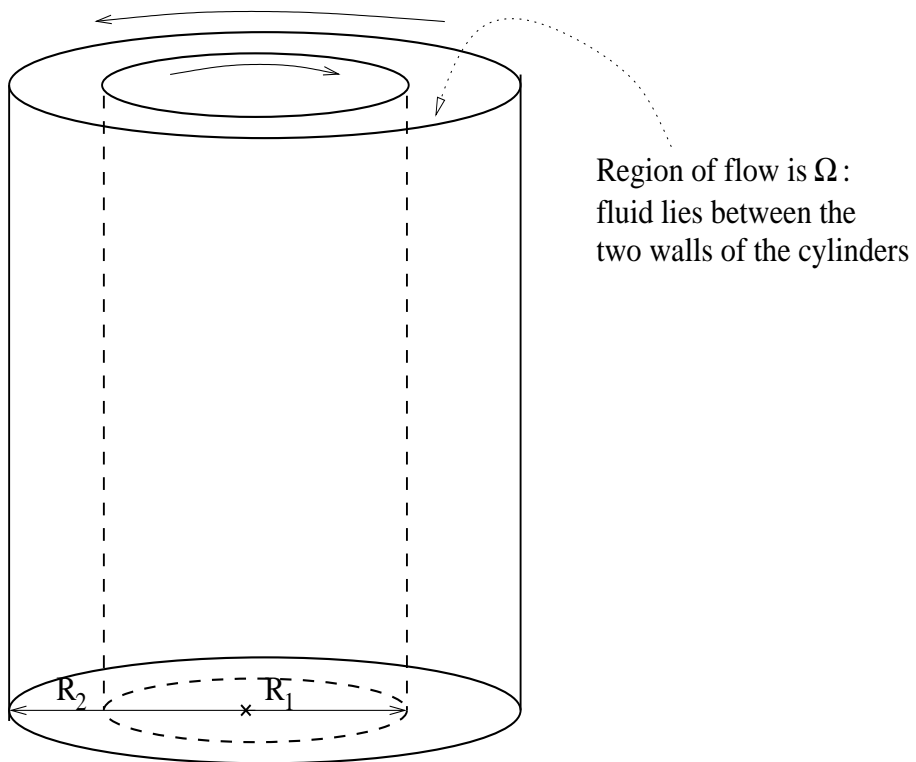


Figure 3: Couette flow between two concentric cylinders of radii  $R_1 < R_2$ .

**Question 4 (20 Marks)**

- (a) Consider Euler's equations of motion for an ideal homogeneous incompressible fluid—these are given on the formulae sheet at the end of the exam paper. Let  $\mathbf{u} = \mathbf{u}(\mathbf{x}, t)$  denote the fluid velocity at position  $\mathbf{x}$  and time  $t$ ,  $\rho$  the uniform constant density,  $p = p(\mathbf{x}, t)$  the pressure, and  $\mathbf{f}$  the body force per unit mass. Suppose that the flow is stationary so that

$$\frac{\partial \mathbf{u}}{\partial t} = 0,$$

and that the body force is conservative so that  $\mathbf{f} = -\nabla\phi$  for some potential function  $\phi = \phi(\mathbf{x})$ . Using the identity

$$\mathbf{u} \cdot \nabla \mathbf{u} = \frac{1}{2} \nabla(|\mathbf{u}|^2) - \mathbf{u} \times (\nabla \times \mathbf{u}),$$

show from Euler's equations of motion that the Bernoulli quantity

$$H := \frac{1}{2} |\mathbf{u}|^2 + \frac{p}{\rho} + \phi$$

is constant along streamlines.

- (b) A clepsydra has the form of a surface of revolution containing water and the level of the free surface of the water falls at a *constant* rate, as the water flows out through a small hole in the base. The basic setup is shown in Figure 4.
- (i) Apply the result in part (a) for the Bernoulli quantity  $H$  to one of the typical streamlines shown in Figure 4 to show that

$$\frac{1}{2} \left( \frac{dz}{dt} \right)^2 = \frac{1}{2} U^2 - gz$$

where  $z$  is the height of the free surface above the small hole in the base,  $U$  is the velocity of the water coming out of the small hole and  $g$  is the acceleration due to gravity.

- (ii) Assuming that the constant rate at which the level surface is falling is very slow, explain why we can deduce that

$$U \approx \sqrt{2gz}.$$

- (iii) If  $S$  is the cross-sectional area of the hole in the bottom, and  $A$  is the cross-sectional area of the free surface, explain why we must have

$$A \frac{dz}{dt} = S U.$$

- (iv) Combine the results from (ii) and (iii) above, to find the shape of the container that guarantees that the free surface of the water drops at a constant rate.

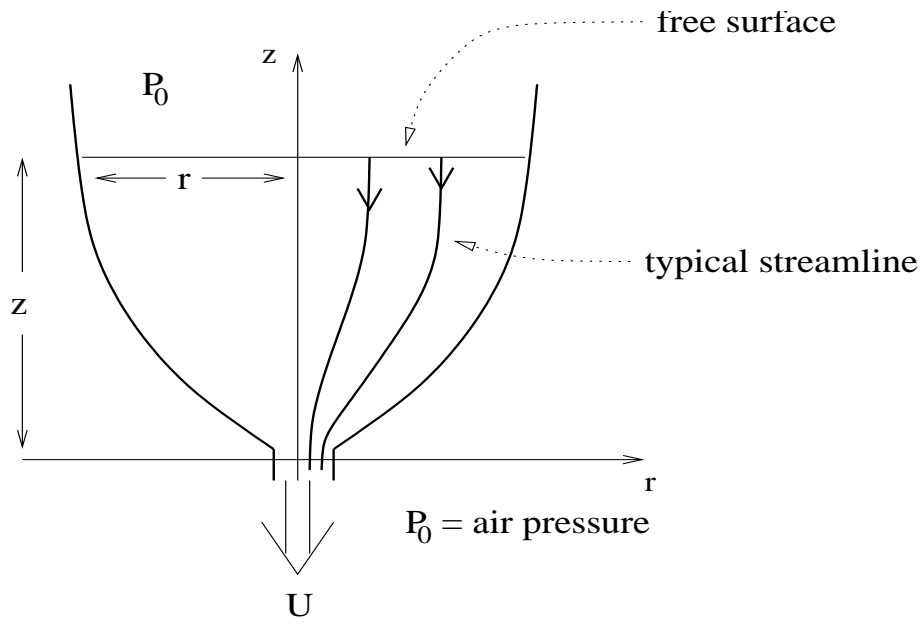


Figure 4: Clepsydra (water clock).

**Question 5 (20 Marks)**

(a) Find the solution of the heat equation

$$u_t = ku_{xx}$$

where  $k$  is a known diffusion parameter, for  $0 < x < L$ ,  $t > 0$  subject to the boundary conditions

$$u(0, t) = 0 \quad \text{and} \quad u(L, t) = 0$$

for  $t > 0$  and an initial condition

$$u(x, 0) = T_0 \sin\left(\frac{2\pi x}{L}\right),$$

for  $0 \leq x \leq L$ , where  $T_0$  is a constant. Explain briefly the physical situation represented by the equation above.

(b) Suppose  $u = u(x, t)$  satisfies the heat equation

$$u_t = u_{xx}$$

for  $0 \leq x \leq L$  and  $t > 0$ , the initial condition

$$u(x, 0) = 0$$

for  $0 \leq x \leq L$ , and the boundary conditions

$$u(0, t) = u(L, t) = 0$$

for  $t > 0$ . Show, by considering the function

$$E(t) := \int_0^L u^2(x, t) dx,$$

that  $u(x, t) \equiv 0$ .

## Formulae

(I) Euler's equations of motion for an ideal homogeneous incompressible fluid are

$$\begin{aligned}\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} &= -\frac{1}{\rho} \nabla p + \mathbf{f}, \\ \nabla \cdot \mathbf{u} &= 0,\end{aligned}$$

where  $\mathbf{u} = \mathbf{u}(\mathbf{x}, t)$  is the fluid velocity at position  $\mathbf{x}$  and time  $t$ ,  $\rho$  is the uniform constant density,  $p = p(\mathbf{x}, t)$  is the pressure, and  $\mathbf{f}$  is the body force per unit mass.

(II) Euler's equations for an ideal homogeneous incompressible fluid in cylindrical coordinates  $(r, \theta, z)$  with the velocity field expressed as  $\mathbf{u} = (u_r, u_\theta, u_z)$  are

$$\begin{aligned}\frac{\partial u_r}{\partial t} + (\mathbf{u} \cdot \nabla) u_r - \frac{u_\theta^2}{r} &= -\frac{1}{\rho} \frac{\partial p}{\partial r} + f_r, \\ \frac{\partial u_\theta}{\partial t} + (\mathbf{u} \cdot \nabla) u_\theta + \frac{u_r u_\theta}{r} &= -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + f_\theta, \\ \frac{\partial u_z}{\partial t} + (\mathbf{u} \cdot \nabla) u_z &= -\frac{1}{\rho} \frac{\partial p}{\partial z} + f_z,\end{aligned}$$

where  $p = p(r, \theta, z, t)$  is the pressure,  $\rho$  is the uniform constant density and  $\mathbf{f} = (f_r, f_\theta, f_z)$  is the body force per unit mass. Here we also have

$$\mathbf{u} \cdot \nabla = u_r \frac{\partial}{\partial r} + \frac{u_\theta}{r} \frac{\partial}{\partial \theta} + u_z \frac{\partial}{\partial z}.$$

Further the incompressibility condition  $\nabla \cdot \mathbf{u} = 0$  is given in cylindrical coordinates by

$$\frac{1}{r} \frac{\partial (r u_r)}{\partial r} + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial u_z}{\partial z} = 0.$$

Lastly in cylindrical coordinates the vorticity  $\boldsymbol{\omega} = \nabla \times \mathbf{u}$  is given by

$$\boldsymbol{\omega} = \begin{pmatrix} \omega_r \\ \omega_\theta \\ \omega_z \end{pmatrix} = \nabla \times \mathbf{u} = \begin{pmatrix} \frac{1}{r} \frac{\partial u_z}{\partial \theta} - \frac{\partial u_\theta}{\partial z} \\ \frac{\partial u_r}{\partial z} - \frac{\partial u_z}{\partial r} \\ \frac{1}{r} \frac{\partial (r u_\theta)}{\partial r} - \frac{1}{r} \frac{\partial u_r}{\partial \theta} \end{pmatrix}.$$