

## ■ Final exam 2004: solutions

### ■ Solution 1(a)

$$\omega = +\sqrt{9} = 3.$$

### ■ Solution 1(b)

$$y_{PI} = A \sin(2t) + B \cos(2t).$$

### ■ Solution 1(c)

This is a resonant case; the frequency of the oscillatory forcing matches the natural frequency of unforced oscillations of the system ( $\omega = 3$ ), hence try

$$y_{PI} = A t \sin(3t) + B t \cos(3t).$$

### ■ Solution 2(a)

The auxillary equation is

$$\lambda^2 + 5\lambda + 4 = 0$$

$$\Leftrightarrow \lambda = -4, \lambda = -1$$

$$\Rightarrow y_{CF} = C_1 e^{-4t} + C_2 e^{-t}.$$

The inhomogeneity in the ODE suggests we try

$$y_{PI} = A e^{2t}$$

$$\Rightarrow y_{PI}' = 2A e^{2t}$$

$$\Rightarrow y_{PI}'' = 4A e^{2t}.$$

Substituting our guess for the PI into the ODE

$$\Rightarrow 4A e^{2t} + 5(2A e^{2t}) + 4(A e^{2t}) = 2e^{2t}$$

$$\Leftrightarrow 4A + 10A + 4A = 2$$

$$\Leftrightarrow A = \frac{1}{9}.$$

Hence the general solution to the ODE is

$$y = y_{CF} + y_{PI}$$

$$\Rightarrow y = C_1 e^{-4t} + C_2 e^{-t} + \frac{1}{9} e^{2t}.$$

### ■ Solution 2(b)

The auxillary equation is

$$4\lambda^2 + 12\lambda + 25 = 0$$

$$\Leftrightarrow \lambda = -\frac{3}{2} - 2i, \lambda = -\frac{3}{2} + 2i$$

$$\Rightarrow y_{CF} = e^{-\frac{3}{2}t} (C_1 \sin(2t) + C_2 \cos(2t)).$$

The inhomogeneity in the ODE suggests we try

$$y_{PI} = A \sin(t) + B \cos(t)$$

$$\Rightarrow y_{PI}' = A \cos(t) - B \sin(t)$$

$$\Rightarrow y_{PI}'' = -A \sin(t) - B \cos(t).$$

Substituting our guess for the PI into the ODE

$$\Rightarrow 4(-A \sin(t) - B \cos(t)) + 12(A \cos(t) - B \sin(t)) + 25(A \sin(t) + B \cos(t)) = 9 \sin(t)$$

Hence equating coefficients:

$$\sin(t) : -4A - 12B + 25A = 9 \Leftrightarrow 7A - 4B = 3,$$

$$\cos(t) : -4B + 12A + 25B = 0 \Leftrightarrow 4A + 7B = 0.$$

Solving this pair of simultaneous equations

$$\Rightarrow A = \frac{21}{65}, B = -\frac{12}{65}.$$

Hence the general solution to the ODE is

$$y = y_{CF} + y_{PI}$$

$$\Rightarrow y = e^{-\frac{3}{2}t} (C_1 \sin(2t) + C_2 \cos(2t)) + \frac{21}{65} \sin(t) - \frac{12}{65} \cos(t).$$

### ■ Solution 3

The auxillary equation is

$$\lambda^2 - 8\lambda + 16 = 0$$

$$\lambda = 4, \lambda = 4$$

$$\Rightarrow y_{CF} = C_1 e^{4t} + C_2 t e^{4t}.$$

The inhomogeneity in the ODE suggests we try

$$Y_{PI} = A t^2 e^{4t}$$

$$\Rightarrow Y_{PI}' = 2 A t e^{4t} + 4 A t^2 e^{4t}$$

$$\Rightarrow Y_{PI}'' = 2 A e^{4t} + 16 A t e^{4t} + 16 A t^2 e^{4t}.$$

Substituting our guess for the PI into the ODE and dividing through by the exponential term

$$\Rightarrow 2 A + 16 A t + 16 A t^2 - 8 (2 A t + 4 A t^2) + 16 (A t^2) = 2$$

$$\Leftrightarrow A = 1.$$

Hence the general solution to the ODE is

$$Y = Y_{CF} + Y_{PI}$$

$$\Rightarrow Y = C_1 e^{4t} + C_2 t e^{4t} + t^2 e^{4t}.$$

#### ■ Solution 4(a)

Since from the table

$$\mathcal{L}[\sin(2t)] = \frac{2}{s^2 + 4},$$

the shift theorem (also in the table)

$$\Rightarrow \mathcal{L}[e^{5t} \sin(2t)] = \frac{2}{(s-5)^2 + 4}.$$

#### ■ Solution 4(b)

Since the denominator factorizes

$$\frac{1}{s^2 + s - 2} = \frac{1}{(s-1)(s+2)}$$

we can use partial fractions to split this fraction into the sum of two simpler fractions, try

$$\frac{1}{(s-1)(s+2)} = \frac{A}{s-1} + \frac{B}{s+2}$$

$$\Leftrightarrow 1 = A(s+2) + B(s-1)$$

$$\Leftrightarrow 1 = (A+B)s + 2A - B.$$

Equating coefficients

$$s^0 : 1 = 2A - B, \quad \begin{cases} s^0 : 1 = 2A - B, \\ s^1 : 0 = A + B. \end{cases} \Rightarrow A = \frac{1}{3}, B = -\frac{1}{3}.$$

$$\Rightarrow \frac{1}{(s-1)(s+2)} = \frac{1/3}{(s-1)} - \frac{1/3}{(s+2)}.$$

Using the table of Laplace transforms

$$\mathbb{L}\left[\frac{1}{3}e^t - \frac{1}{3}e^{-2t}\right] = \frac{1/3}{(s-1)} - \frac{1/3}{(s+2)}.$$

Hence

$$\mathbb{L}^{-1}\left[\frac{1}{s^2 + s - 2}\right] = \frac{1}{3}e^t - \frac{1}{3}e^{-2t}.$$

## ■ Solution 5

Taking the Laplace transform of both sides of the ODE

$$\Rightarrow \mathbb{L}[y''(t) + 7y'(t) + 6y(t)] = \mathbb{L}[\delta(t - 2\pi)]$$

$$\Leftrightarrow s^2 \bar{y}(s) - sy(0) - y'(0) + 7(s\bar{y}(s) - y(0)) + 6\bar{y}(s) = e^{-2\pi s}$$

$$\Leftrightarrow (s^2 + 7s + 6)\bar{y}(s) = e^{-2\pi s}$$

$$\Leftrightarrow \bar{y}(s) = \frac{e^{-2\pi s}}{s^2 + 7s + 6}$$

$$\Leftrightarrow \bar{y}(s) = \frac{e^{-2\pi s}}{(s+1)(s+6)}.$$

Using partial fractions, we can expand

$$\frac{1}{(s+1)(s+6)} = \frac{A}{(s+1)} + \frac{B}{(s+6)}$$

$$\Leftrightarrow 1 = A(s+6) + B(s+1)$$

$$\Leftrightarrow 1 = (A+B)s + 6A + B.$$

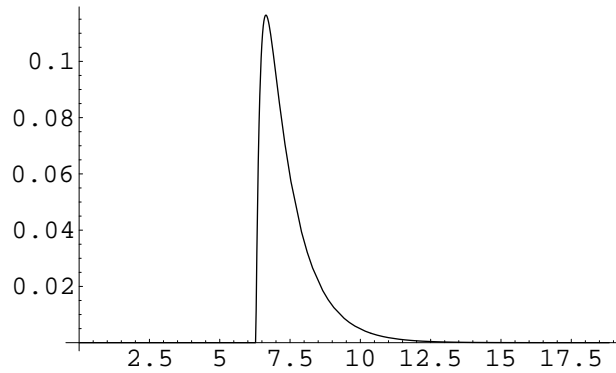
Equating coefficients

$$\begin{cases} s^0 : 1 = 6A + B, \\ s^1 : 0 = A + B. \end{cases} \Rightarrow A = \frac{1}{5}, B = -\frac{1}{5}.$$

$$\Rightarrow \bar{y}(s) = \frac{1}{5} \frac{e^{-2\pi s}}{(s+1)} - \frac{1}{5} \frac{e^{-2\pi s}}{(s+6)}$$

$$\Leftrightarrow y(t) = \begin{cases} \frac{1}{5}e^{-(t-2\pi)} - \frac{1}{5}e^{-6(t-2\pi)}, & t > 2\pi, \\ 0, & t \leq 2\pi. \end{cases}$$

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Plot[UnitStep[t - 2 π] (1/5 e-(t-2π) - 1/5 e-6(t-2π)), {t, 0, 6 π}]
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- Graphics -

## ■ Solution 6

The augmented matrix is

$$\mathbf{H} := \begin{pmatrix} 2 & 0 & 3 & 8 \\ 0 & 2 & 3 & 16 \\ 1 & 1 & -1 & 0 \end{pmatrix}$$

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H = H /. H[[3]] -> 2 H[[3]] - H[[1]];
H // MatrixForm
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$$\begin{pmatrix} 2 & 0 & 3 & 8 \\ 0 & 2 & 3 & 16 \\ 0 & 2 & -5 & -8 \end{pmatrix}$$

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H = H /. H[[3]] -> H[[3]] - H[[2]];
H // MatrixForm
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$$\begin{pmatrix} 2 & 0 & 3 & 8 \\ 0 & 2 & 3 & 16 \\ 0 & 0 & -8 & -24 \end{pmatrix}$$

Hence using back-substitution, the solution is

$$I_1 = -\frac{1}{2}, I_2 = \frac{7}{2}, I_3 = 3.$$

That  $I_1$  is negative simply means that the current actually flows in the direction opposite to that assumed in the figure.

## ■ Solution 7

The eigenvalues are the solutions to the characteristic equation

$$\det \begin{pmatrix} -1-\lambda & 6 & 0 \\ 2 & 1-\lambda & 1 \\ -2 & -1 & -1-\lambda \end{pmatrix} = 0$$

$$\Leftrightarrow -(1+\lambda)(-(1-\lambda)(1+\lambda)+1)-6(-2(1+\lambda)+2)=0$$

$$\Leftrightarrow -(1+\lambda)(\lambda^2)-6(-2\lambda)=0$$

$$\Leftrightarrow \lambda(\lambda^2+\lambda-12)=0.$$

Hence the eigenvalues are

$$\lambda = 0, \lambda = 3, \lambda = -4.$$

For  $\lambda=3$ , the eigenvector solves

$$(\mathbf{A} - \lambda \mathbf{I}) \mathbf{x} = \mathbf{0}$$

$$\Leftrightarrow \begin{pmatrix} -1-3 & 6 & 0 \\ 2 & 1-3 & 1 \\ -2 & -1 & -1-3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

The augmented matrix is

$$\mathbf{H} := \begin{pmatrix} -4 & 6 & 0 & 0 \\ 2 & -2 & 1 & 0 \\ -2 & -1 & -4 & 0 \end{pmatrix}$$

$$\mathbf{H} = \mathbf{H} /. \mathbf{H}[[2]] \rightarrow 2\mathbf{H}[[2]] + \mathbf{H}[[1]];$$

$$\mathbf{H} = \mathbf{H} /. \mathbf{H}[[3]] \rightarrow 2\mathbf{H}[[3]] - \mathbf{H}[[1]];$$

$\mathbf{H} // \text{MatrixForm}$

$$\begin{pmatrix} -4 & 6 & 0 & 0 \\ 0 & 2 & 2 & 0 \\ 0 & -8 & -8 & 0 \end{pmatrix}$$

$$\mathbf{H} = \mathbf{H} /. \mathbf{H}[[3]] \rightarrow \mathbf{H}[[3]] + 4\mathbf{H}[[2]];$$

$\mathbf{H} // \text{MatrixForm}$

$$\begin{pmatrix} -4 & 6 & 0 & 0 \\ 0 & 2 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Hence

$$\mathbf{x}_3 = -\mathbf{x}_2, \quad \mathbf{x}_1 = \frac{3}{2} \mathbf{x}_2$$

and the eigenvector corresponding to  $\lambda=3$  is, for any  $\alpha \neq 0$ :

$$\mathbf{x} = \alpha \begin{pmatrix} \frac{3}{2} \\ 1 \\ -1 \end{pmatrix}.$$

### ■ Solution 8(a)

Look for a solution of the form

$$\mathbf{Y}(t) = \mathbf{C} e^{i\omega t}$$

$$\Rightarrow (i\omega)^2 \mathbf{C} e^{i\omega t} = \mathbf{A} \mathbf{C} e^{i\omega t}$$

$$\Leftrightarrow (\mathbf{A} + \omega^2 \mathbf{I}) \mathbf{C} = \mathbf{0}.$$

### ■ Solution 8(b)

The eigenvalues are the solutions to the characteristic equation

$$\det(\mathbf{A} + \omega^2 \mathbf{I}) = 0$$

$$\Leftrightarrow \det \begin{pmatrix} -5 + \omega^2 & 3 \\ 3 & -5 + \omega^2 \end{pmatrix} = 0$$

$$\Leftrightarrow (\omega^2 - 5)^2 - 9 = 0$$

$$\Leftrightarrow (\omega^2)^2 - 10\omega^2 + 16 = 0$$

$$\Leftrightarrow (\omega^2 - 2)(\omega^2 - 8) = 0$$

$$\Leftrightarrow \omega^2 = 2, \omega^2 = 8$$

$$\Leftrightarrow \omega = \pm 2\sqrt{2}, \omega = \pm \sqrt{2}.$$

Hence  $\omega = 2\sqrt{2}$  and  $\omega = \sqrt{2}$  are the fundamental frequencies of vibration.

### ■ Solution 8(c)

For  $\omega^2 = 2$ , the eigenvector solves

$$\begin{pmatrix} -5 + 2 & 3 \\ 3 & -5 + 2 \end{pmatrix} \begin{pmatrix} \mathbf{C}_1 \\ \mathbf{C}_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} -3 & 3 \\ 3 & -3 \end{pmatrix} \begin{pmatrix} \mathbf{C}_1 \\ \mathbf{C}_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \mathbf{C}_2 = \mathbf{C}_1.$$

Hence the eigenvector corresponding to  $\omega^2 = 2$  is, for any  $\alpha \neq 0$ :

$$\mathbf{C}^{(1)} = \alpha \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

and the corresponding mode of oscillation is

$$\mathbf{y}^{(1)}(\mathbf{t}) = \alpha \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{i\sqrt{2}t},$$

i.e. they oscillate exactly in phase.

For  $\omega^2 = 8$ , the eigenvector solves

$$\begin{pmatrix} -5 + 8 & 3 \\ 3 & -5 + 8 \end{pmatrix} \begin{pmatrix} \mathbf{C}_1 \\ \mathbf{C}_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} 3 & 3 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} \mathbf{C}_1 \\ \mathbf{C}_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \mathbf{c}_2 = -\mathbf{c}_1.$$

Hence the eigenvector corresponding to  $\omega^2 = 2$  is, for any  $\beta \neq 0$ :

$$\mathbf{c}^{(2)} = \beta \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

and the corresponding mode of oscillation is

$$\mathbf{y}^{(2)}(t) = \beta \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{i 2 \sqrt{2} t},$$

i.e. they oscillate exactly out of phase with each other.

### ■ Solution 8(d)

The general solution is

$$\begin{aligned} \mathbf{Y}(t) &= \operatorname{Re}[\mathbf{K}_1 \mathbf{Y}^{(1)}(t) + \mathbf{K}_2 \mathbf{Y}^{(2)}(t)] \\ \Rightarrow \mathbf{Y}(t) &= \operatorname{Re}\left[\tilde{\mathbf{K}}_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{i \sqrt{2} t} + \tilde{\mathbf{K}}_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{i 2 \sqrt{2} t}\right], \end{aligned}$$

where  $\tilde{\mathbf{K}}_1$  and  $\tilde{\mathbf{K}}_2$  are arbitrary complex constants (fixed by the initial data).