Topological and ε -entropy for Large Volume Limits of Discretised Parabolic Equations

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Abstract

We consider semi-discrete and fully discrete approximations of nonlinear parabolic equations in the limit of unbounded domains, which by a scaling argument is equivalent to the limit of small viscosity. We de£ne the spatial density of ε -entropy, topological entropy and dimension for the attractors and show that these quantities are bounded. We also provide practical means of computing lower bounds on them. The proof uses the property that solutions lie in Gevrey classes of analyticity, which we de£ne in a way that does not depend on the size of the spatial domain. As a speci£c example we discuss the complex Ginzburg-Landau equation.

1 Introduction

We consider the following general parabolic equation,

$$\partial_t u = \nu \Delta u + \gamma u + F(u), \qquad x \in [-L\pi, L\pi]^d, \qquad t \ge 0, \tag{1.1}$$

for a complex valued function u = u(x,t) and bounded continuous initial condition $u(x,0) = u_0(x)$. We restrict ourselves to $L \in \mathbb{N}$ for convenience. The coefficients of (1.1) satisfy

$$\nu \in \mathbb{C}$$
, $\operatorname{Re}(\nu) > 0$, $\gamma \in \mathbb{R}$,

and we assume that Re(F) and Im(F) are real analytic functions of Re(u) and Im(u).

We are interested in the large volume limit $(L \to \infty)$ of the long time dynamics (in particular the attractor) of (1.1) and its approximation by numerical schemes. In the latter case we are interested in the limit when the mesh size of our discretisation is kept constant while taking the limit $L \to \infty$, thereby obtaining an in£nite-dimensional, but still discrete system (see Section 6 for results of upper semicontinuity of the attractors in terms of the different parameters of the problem).

We remark that by a scaling transformation, the large volume limit can be interpreted as a small viscosity limit. The rescaled function v(y,t)=u(Ly,t) with $y\in [-\pi,\pi]^d$ satisfies the following equation

$$\partial_t v = \frac{\nu}{I^2} \Delta v + \gamma v + F(v) ,$$

with periodic boundary conditions on $[-\pi,\pi]^d$. It is however easier to work with (1.1) (with periodic boundary conditions) and take $L\to\infty$. Indeed, since the problem on the full space \mathbb{R}^d is well-posed, we have a priori bounds for all $L<\infty$. In fact, we view the periodic boundary conditions on $[-L\pi,L\pi]^d$ for large L as an approximation of the in£nite volume.

For each £xed $L < \infty$, (1.1) generates a semi-¤ow Φ_L^t . We discretise this time-evolution spatially by truncating to a £nite number of (Fourier) modes. We make this truncation by multiplying by a smooth function in Fourier space (rather than a sharp indicator function), to have a better control as $L \to \infty$ (when the spectrum becomes dense). We then discretise in time by a non-stiff explicit scheme considered in [26]. This scheme is amenable to analysis and also proves to be an ef£cient numerical scheme for smooth initial conditions.

It is not the purpose of this paper to prove the existence of global attractors for (1.1) or for the discretisations, this has been considered in different setups in a large number of publications (see for example [27, 24, 3, 1, 29]). Instead, we assume the existence a semi- \mathbb{Z} ow and of a family of global attractors, $\widehat{\mathcal{A}}(L)$, for the continuous and discrete problems (see De£nition 3.2).

We compute bounds on statistical quantities that are valid both for the discrete and continuous

systems. The £rst of these statistical quantities is the (Kolmogorov) ε -entropy

$$H_{\varepsilon} := \limsup_{L \to \infty} \frac{\log \mathcal{N}(\varepsilon, \widehat{\mathcal{A}}(L))}{(2L\pi)^d},$$

where $\mathcal N$ is the minimum number of balls of radius ε in the topology of L^∞ that are needed to cover the attractor $\widehat{\mathcal A}(L)$ (see De£nition 3.3). We prove that H_ε is a £nite number in Theorem 4.3. We thereby get a bound on the upper density of dimension

$$d_{\rm up} = \limsup_{\varepsilon \to 0} \frac{H_{\varepsilon}}{\log \varepsilon^{-1}}$$
.

This is to be compared with the results of Kolmogorov and Tikhomirov [14], where they obtain a bound of the same type for the set of all entire analytic functions of exponential type. This result follows from a sampling result for such functions (Proposition D.3), namely any of these analytic functions can be reconstructed by interpolation of a discrete set of values. Although the functions on \widehat{A} are not entire functions, they are still determined by a discrete sampling.

Remark that it is appropriate to take the L^{∞} topology, since the diameter of $\widehat{\mathcal{A}}(L)$ does not depend on L in this topology, unlike the topology of Sobolev spaces of non-zero order. We remark that the L^{∞} topology is stronger than the L^2 topology, hence our results do not follow from [9, 8, 29].

We also wish to emphasise here that the order of the limits in our de£nition of $d_{\rm up}$ is important. A more 'naive' de£nition would be

$$\widehat{d}_{\rm up} = \limsup_{L \to \infty} \limsup_{\varepsilon \to 0} \frac{\log \mathcal{N}(\varepsilon, \widehat{\mathcal{A}}(L))}{(2L\pi)^d \log \varepsilon^{-1}}.$$

The two limits do not commute in general, see [5]. We believe our approach is more natural from an experimental/numerical point of view, in the sense that L is a parameter that can be varied in a series of measurements/simulations made at a £xed accuracy ε .

We also consider the density of topological entropy in Section 5. We show that the spatial densities satisfy the analogue of the following well known inequalities [13, 21]

$$V \leq h_{\text{top}} \leq \lambda d_{\text{up}}$$
,

where V is the volume expansion rate, λ is the largest Lyapunov exponent, h_{top} is the topological entropy and d_{up} is the upper Hausdorff dimension.

The paper is organised as follows: in the remainder of this section we introduce the notation for the paper. In Section 2 the semi-discrete and fully discrete approximations to (1.1) are presented. In Section 3, we de£ne the density of ε -entropy, topological entropy, of upper dimension and the volume growth rate and state our assumptions on the equation and its approximations. A key result of the paper is Lemma 4.2 (proved in Appendix A), which states that the evolution has a fast local smoothing effect, a property which allows us to establish upper bounds on the

 ε -entropy (Section 4). This is then applied in Section 5 to show that the topological entropy is £nite. We also show that it is bounded below by the volume expansion rate (Section 5.2). We discuss the upper-semicontinuity of the attractors in Section 6. Technical proofs are given at the end of the paper: Appendix B contains a proof of analyticity for the fully discrete scheme, Appendix C contains a Lemma on analytic functions and Appendix D recalls some results on Gevrey and Bernstein classes.

1.1 Notation

We use the following conventions: \overline{z} is the complex conjugate of z and $|z| = \sqrt{z\overline{z}}$ its modulus. A function $f = f_1 + if_2$ with both f_1 and f_2 real-analytic is identified with the vector-valued function $f = (f_1, f_2)$. Its analytic extension to the complex plane has the form $(f_1 + ig_1, f_2 + ig_2)$ and we write $|f| = (|f_1|^2 + |f_2|^2 + |g_1|^2 + |g_2|^2)^{1/2}$ which, on the real axis, is equal to the modulus of the complex function f. The convolution of two functions f, g is denoted $f \star g(x) := \int f(x-y)g(y)dy$.

If u is a function of t (time) and x (space), then we consider it either as a function of two variables with values in \mathbb{C} , written $u(x,t) \in \mathbb{C}$, or as a function of time with values in the functions of x, written $u(t) \in \mathcal{C}_b(\mathbb{R}^d)$ (the set of bounded continuous functions). A function in the set $\mathcal{C}_{per}([-L\pi,L\pi]^d)$ of $2L\pi$ -periodic continuous functions, will often be identified (by periodic extension) with its lift to $\mathcal{C}_b(\mathbb{R}^d)$.

The spaces $C_b(\mathbb{R}^d)$ and $C_{per}([-L\pi, L\pi]^d)$ are Banach spaces with the sup norm $\|\cdot\|_{\infty}$ and may be viewed as subspaces of $(L^{\infty}(\mathbb{R}^d), \|\cdot\|_{\infty})$ and $(L^{\infty}([-L\pi, L\pi]^d), \|\cdot\|_{\infty})$ respectively. We also make extensive use of the Gevrey class $\mathcal{G}_{\alpha}(C)$ and the Bernstein class $\mathcal{B}_{\sigma}(C)$. These are both discussed in Appendix D. If $\operatorname{Re}(f)$ and $\operatorname{Im}(f)$ belong to the Gevrey class $\mathcal{G}_{\alpha}(C)$, we use the notation $f \in [\mathcal{G}_{\alpha}(R)]^2$ (similarly for $\mathcal{B}_{\sigma}(C)$).

We denote by \mathcal{T} the standard Fourier transform operator

$$(\mathcal{T}f)(k) := \frac{1}{(2\pi)^d} \int e^{ik\cdot x} f(x) \, dx \,, \qquad (\mathcal{T}^{-1}f)(x) := \int e^{-ik\cdot x} f(x) \, dk \,.$$

The Fourier series operator for $2L\pi$ -periodic functions is denoted with the same symbol:

$$(\mathcal{T}f)_n := \frac{1}{(2L\pi)^d} \int_{|x| \le L\pi} e^{in \cdot x/L} f(x) dx, \qquad (\mathcal{T}^{-1}f)(x) := \sum_{n \in \mathbb{Z}^d} e^{-in \cdot x/L} f_n.$$

We introduce two different smooth cutoff functions. The £rst of these, φ , acts in real space and serves as a weight in L^p norms, in order to get bounds that do not depend on L.

De£nition 1.1 Let φ be a real-space cutoff function satisfying

$$\varphi(x) > 0 \quad \forall x \in \mathbb{R}^d, \quad \varphi(-x) = \varphi(x), \quad \int \varphi(x) \, dx = 1, \quad \left\| \frac{\nabla \varphi}{\varphi} \right\|_{\infty} < \infty,$$

and, moreover, φ^{-1} is a tempered distribution ($\int \varphi^{-1} f < \infty$ for any Schwartz function f).

Examples. The function

$$\varphi(x) = \frac{1}{(1 + |C_{\varphi}x|^2)^{d/2 + 1}}$$

satis£es all of our requirements (here, C_{φ} is a normalisation constant determined by the equation $\int \varphi = 1$, similarly for C_{ψ} below). However, the function

$$\psi(x) = \frac{1}{\cosh(C_{\psi}x_1)\cdots\cosh(C_{\psi}x_d)},$$

which has a sharper decay at in£nity, cannot be used because it fails the last property: $\cosh(x)$ is not a tempered distribution. The importance of this may be seen in Lemma 4.2.

Note that for (1.1) the function ψ could be used, and would provide sharper bounds in our proofs. This does not work however with the truncation to a £nite number of modes (such as given by the semi-discrete system (2.3) or fully discrete system (2.5)).

Our second cutoff function, ξ_K , is de£ned in terms of its Fourier transform. It smoothly truncates to a £nite set of Fourier modes hence produces a £nite dimensional problem.

De£nition 1.2 Let K > 1 and let $\widehat{\xi}_K$ be a C^{∞} function taking the following values:

$$\widehat{\xi}_K(k) = \begin{cases} 1 & \text{if } |k| \le K - 1, \\ 0 & \text{if } |k| \ge K. \end{cases}$$

Its inverse Fourier transform $\xi_K = \mathcal{T}^{-1}(\widehat{\xi}_K)$ is an (entire) Schwartz function.

Note that if f is a Schwartz function, then $\xi_K \star f$ is a Schwartz function whose Fourier transform has support in $[-K, K]^d$, hence it belongs to $\mathcal{B}_K(C)$ for some C, see [23].

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2 Semi-Discrete and Fully-Discrete Approximations

In this section, we propose a spatial discretisation of (1.1) and a fully discrete scheme.

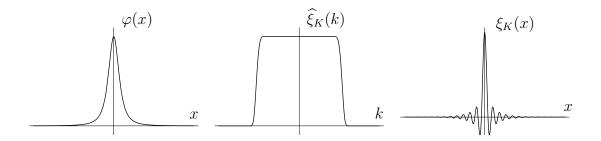


Figure 1: The cutoff functions of De£nitions 1.1-1.2

2.1 Galerkin Scheme

The semi-discretisation we describe here is a spectral method. Let $N \in \mathbb{N}$, then we use the Fourier cutoff ξ_K of De£nition 1.2 with K = N to de£ne the operators P^N and $\mathrm{Q}^N f := f - \mathrm{P}^N f$ where

$$P^{N}f := \xi_{N} \star f = \mathcal{T}^{-1}\left(\widehat{\xi}_{N}\mathcal{T}(f)\right), \qquad (2.1)$$

i.e.,

$$\mathbf{P}^{N} \sum_{n \in \mathbb{Z}^{d}} f_{n} e^{-in \cdot x/L} := \sum_{|n| \leq NL} \widehat{\xi}_{N}(n/L) f_{n} e^{-in \cdot x/L} ,$$

Notice that P^N truncates to $(2NL)^d$ modes, not $(2N)^d$. In this way $\mathcal{T}(P^Nf)$ has support contained in $[-N,N]^d$ for all L. The operator P^N is not a projector since $P^NP^N \neq P^N$.

The Galerkin approximation is de£ned as follows: the solution u(x,t) to (1.1) is replaced by a £nite Fourier series

$$u^{N}(x,t) := \sum_{|n| \le NL} u_{n}(t)e^{-in \cdot x/L}.$$
(2.2)

The evolution equation is obtained by applying P^N to the nonlinear term of (1.1) and to the initial condition u_0 :

$$\partial_t u^N = (\gamma + \nu \Delta) u^N + P^N F(u^N), \qquad u^N(x,0) = (P^N u_0)(x). \tag{2.3}$$

2.2 Fully Discrete Scheme

In this section we de£ne an explicit, non-stiff (for suf£ciently smooth data) full discretisation of (1.1) introduced in [26]. The time-discretisation is an exact exponential integrator for the linear part and a simple (order 1) quadrature for the nonlinear term appearing in the variation of constants formula. The full discretisation is obtained by applying this time-discretisation to the Galerkin scheme (2.3). We use this particular scheme because it makes it straightforward to prove that solutions are (Gevrey) analytic functions (uniformly in the parameters of the scheme, see Appendix B), a fact that we heavily rely on in the next sections.

Let $\mathcal{L} = \gamma + \nu \Delta$ and $\mathcal{K}(x,t)$ be the convolution kernel associated with the operator $\exp(t\mathcal{L})$:

$$\mathcal{K}(x,t) = \frac{1}{(2\pi)^d} \int e^{-ik\cdot x + (\gamma - \nu|k|^2)t} dk. \qquad (2.4)$$

Note that the operator P^N commutes with $\mathcal{K}\star\cdot$ since both are convolution operators. Let h>0 denote the time-step. Then the fully discrete approximation to u(x,t) is defined iteratively by

$$u^{N}((n+1)h) = \mathcal{K}(h) \star u^{N}(nh) + \left(\int_{0}^{h} P^{N} \mathcal{K}(h-s) ds\right) \star F(u^{N}(nh)). \tag{2.5}$$

In terms of the Fourier coef£cients, (2.2), we get

$$u_m^N((n+1)h) = e^{h\lambda_m} u_m^N(nh) + \left(\int_0^h e^{(h-s)\lambda_m} ds\right) P^N \mathcal{T} F \left(\mathcal{T}^{-1} u^N(nh)\right)_m$$
$$= e^{h\lambda_m} u_m^N(nh) + \left(\frac{e^{h\lambda_m} - 1}{\lambda_m}\right) \hat{\xi}_N(m/L) \mathcal{T} F \left(\mathcal{T}^{-1} u^N(nh)\right)_m,$$

where $\{\lambda_m\}_{m\in\mathbb{Z}^d}$ are the eigenvalues of \mathcal{L} , namely $\lambda_m=\gamma-\nu|m|^2/L^2$, n is the time index, m is the Fourier index, and \mathcal{T} is the Fourier transform.

For the purposes of analysis, it is useful to consider this scheme in terms of piece-wise solutions of a linear differential equation. Indeed, $u^N(x, (n+1)h)$ is the solution at time t = h of

$$\partial_t u(x,t) = \nu \Delta u(x,t) + \gamma u(x,t) + P^N F(u(x,nh))$$
(2.6)

with initial condition $u^N(x, nh)$ at t = 0.

Remark. We could apply our techniques to other numerical schemes. We only require the numerical approximation to belong to the Gevrey class $\mathcal{G}_{\alpha}(C)$ of bounded real analytic functions for some $\alpha > 0$, C > 0 (see Appendix D). There exists many wavelet and £nite element schemes satisfying this requirement, see [7, 17]. In particular, Propositions D.2 and D.3 provide a natural example of a different basis of analytic functions on which our problem can be decomposed and then a truncation applied: this basis consists of the functions

$$\Psi_{j,k}(x) = \frac{3e^{ik\cdot x}\sin(2x - \frac{1}{3}j\pi)\sin(6x - j\pi)}{(6x - j\pi)^2},$$

for $j, k \in \mathbb{Z}^d$. These functions have the advantage of being localised both in real space and in Fourier space although the numerical implementation is more involved.

3 De£nitions and Assumptions

Since we are interested in the large volume limit we specify this dependence in the de£nitions below.

Assumption 3.1 For initial data $u_0 \in C_{per}([-L\pi, L\pi]^d)$, we assume that

- equation (1.1) is the generator of a semi- \bowtie ow $\Phi_L^t: u_0 \mapsto u(t)$;
- for all $N > N_0$, the semi-discrete equation (2.3) is the generator of a semi-zeow $\Phi_{L,N}^t : u_0 \mapsto u(t)$;
- for all $N > N_0$ and $h < h_0$ the fully discrete equation (2.5) is the generator of a semi-wow $\Phi^t_{L,N,h}: u_0 \mapsto u(t)$ with t = nh, $n \in \mathbb{N}$.

Furthermore we assume for each of the semi-zows above that there exists constants $\alpha > 0$ and R > 0, independent L and t, such that Re(u(t)) and Im(u(t)) belong to the Gevrey class $\mathcal{G}_{\alpha}(R)$ for all t > T(u) and so $u(t) \in [\mathcal{G}_{\alpha}(R)]^2$. In other words, the following sets are absorbing balls for their corresponding semi-zows:

$$B(L) := \mathcal{C}_{per}([-L\pi, L\pi]^d) \bigcap [\mathcal{G}_{\alpha}(R)]^2,$$

$$B_N(L) := P^N \mathcal{C}_{per}([-L\pi, L\pi]^d) \bigcap [\mathcal{G}_{\alpha}(R)]^2,$$

$$B_{N,h}(L) := P^N \mathcal{C}_{per}([-L\pi, L\pi]^d) \bigcap [\mathcal{G}_{\alpha}(R)]^2.$$

Throughout the paper we use $\widehat{\Phi}^t$ to denote any of the semi-zows (with t taken appropriately) defined above and $\widehat{B}(L)$ to denote the corresponding absorbing balls.

We next de£ne the attractors of the different evolutions introduced above.

De£nition 3.2 We de£ne the following invariant attracting sets for the ¤ows de£ned in Assumption 3.1

$$\mathcal{A}(L) := \bigcap_{t>0} \Phi_L^t(B(L)),$$

$$\mathcal{A}_N(L) := \bigcap_{t>0} \Phi_{L,N}^t(B_N(L)),$$

$$\mathcal{A}_{N,h}(L) := \bigcap_{n\in\mathbb{N}} \Phi_{L,N,h}^{nh}(B_{N,h}(L)).$$

Throughout the paper we use $\widehat{\mathcal{A}}(L)$ to denote any of the above attracting sets.

Clearly £nite trigonometric sums like (2.2) are entire functions. However, the assumption that there exists a strip around the real axis where u^N is bounded by the same constant for all N is not trivial. Results of this type are know for a number of parabolic partial differential equations of the

form (1.1), under the assumptions that F is dissipative in an appropriate sense (see for example [1, 25]). For numerical approximations, existence of semi-zows and global attractors is a well considered problem (see for example [24]). Gevrey regularity of solutions for numerical schemes has not been so widely considered, two different approaches are in [16, 26]. Appendix B contains a sketch of how to obtain this result for the fully discrete scheme given by (2.5). The proof only relies on an a priori L^{∞} bound on the solutions and the assumption that the nonlinearity F is analytic.

We next introduce the notion of ε -entropy. The proof that this is a £nite quantity will be given in Section 4. From this we de£ne the upper density of dimension.

De£nition 3.3 Let Y be a subset of a metric space X. A set $\mathcal{U} = \{U_1, \dots, U_N\}$ of open sets in X is called a cover of Y if $\bigcup_{n=1}^N U_n \supset Y$. It is called an ε -cover if $\max_{n=1,\dots,N} \operatorname{diam}(U_n) \leq \varepsilon$.

Let $\widehat{\mathcal{A}}(L)$ be endowed with the metric defined by the norm $\|\cdot\|_{\infty}$. Let

$$\mathcal{N}(\varepsilon, \widehat{\mathcal{A}}(L)) := \inf \{ \operatorname{card}(\mathcal{U}) : \mathcal{U} \text{ is an } \varepsilon\text{--cover of } \widehat{\mathcal{A}}(L) \}.$$

We define the ε -entropy H_{ε} as the limit

$$H_{\varepsilon} := \limsup_{L \to \infty} \frac{\log \mathcal{N}(\varepsilon, \widehat{\mathcal{A}}(L))}{(2L\pi)^d}.$$

The upper density of dimension d_{up} is defined by

$$d_{\rm up} := \limsup_{\varepsilon \to 0} \frac{H_{\varepsilon}}{\log \varepsilon^{-1}}.$$

Remark. In [4, 5, 6, 22], H_{ε} was defined with a limit instead of a limit superior. The existence of the limit followed from a subadditivity argument which cannot be used here because of the boundary conditions. That is, the set $\widehat{\mathcal{A}}(L)$ we are considering here changes with L, whereas in the papers [4, 5, 6, 22], only the topology on \mathcal{A} depended on L, not the set itself. See also [30, 31] for similar results.

Another, more classical notion of entropy is the topological entropy. It serves to measure to complexity of a dynamical system. Similarly to the previous de£nition, we consider here the spatial density of topological entropy. See Section 5 for results on the topological entropy.

De£nition 3.4 For $\tau > 0$, we de£ne a pseudo-metric $d_{m,\tau}$ on $C_{per}([-L\pi, L\pi]^d)$ by

$$d_{m,\tau}(u,v) := \max_{k=0,\dots,m-1} \|\widehat{\Phi}^{k\tau}(u) - \widehat{\Phi}^{k\tau}(v)\|_{\infty}.$$

An (m, ε) -cover of $\widehat{\mathcal{A}}(L)$ is a collection of open sets whose diameter in the metric $d_{m,\tau}$ is at most ε and whose union contains $\widehat{\mathcal{A}}(L)$. Let $\mathcal{M}_{m,\tau}(\varepsilon,\widehat{\mathcal{A}}(L))$ be the cardinality of such a minimal (m, ε) -cover.

The (spatial density of) topological entropy is de£ned as follows:

$$h_{\text{top}} := \limsup_{\varepsilon \to 0} \limsup_{L \to \infty} \frac{1}{(2L\pi)^d} \lim_{m \to \infty} \frac{1}{m\tau} \log \mathcal{M}_{m,\tau}(\varepsilon, \widehat{\mathcal{A}}(L)) . \tag{3.1}$$

The existence of the £rst limit in (3.1) can be proved by a subadditivity argument, see [4, 6, 13]. A useful way of computing a lower bound on the topological entropy is by measuring the volume expansion rate (see Section 5.2).

De£nition 3.5 Let $L \mapsto \mathcal{D}(L)$ be a family of ℓ -dimensional \mathcal{C}^{∞} sub-manifolds of the absorbing ball \widehat{B} . We de£ne \mathcal{V} , the volume expansion rate, by

$$\mathcal{V} := \limsup_{L \to \infty} \frac{1}{(2L\pi)^d} \limsup_{m \to \infty} \frac{1}{m\tau} \log \operatorname{Vol}_{\ell}(\widehat{\Phi}^{m\tau}(\mathcal{D}(L))),$$

where Vol_{ℓ} is the ℓ -dimensional (Euclidean) volume.

4 Upper Bound on the ε -Entropy

We now work towards proving our main result which is a bound on the ε -entropy. First we discuss a preliminary result on the smoothing property of the semi-¤ow which is proved in Appendix A.

4.1 Smoothing Property of the Semi-Flow

We consider here differences w=u-v of two orbits u and v of the semi- $\operatorname{pow} \widehat{\Phi}^t$ of Assumption 3.1. We define functions G_1 and G_2 in such a way that w satisfies

$$\partial_t w = (\gamma + \nu \Delta) w + P^N (G_1(u, v)w + G_2(u, v)\overline{w})$$
(4.1)

for continuous time and

$$w((n+1)h) = \mathcal{K}(h) \star w(nh) + \left(\int_0^h \mathbf{P}^N \mathcal{K}(h-s) \, ds \right) \star \left(G_1(nh) w(nh) + G_2(nh) \overline{w}(nh) \right) \tag{4.2}$$

for discrete time. From now on we view G_1 and G_2 as functions of x and t (rather than of u and v) and we use the following consequence of Assumption 3.1:

Lemma 4.1 There exists $\alpha > 0$ and R > 0, both independent of N, L, and t, such that w(t), $G_1(t)$ and $G_2(t)$ all belong to $[\mathcal{G}_{\alpha}(R)]^2$ for all t > 0 (and $t/h \in \mathbb{N}$ for (4.2)).

Remark. We may assume without loss of generality that the R and the α of Assumption 3.1 and Lemma 4.1 are equal, and that they are also equal for the fully continuous, semi-discrete and fully discrete equations.

We compute bounds on the weighted L^2 -norm of w shifted in the complex plane over a £nite time interval. Instead of taking the usual (pat) L^2 norm over $[-L\pi,L\pi]^d$, which would not behave well in the limit $L\to\infty$, we take a norm over the whole of \mathbb{R}^d weighted with the function φ from De£nition 1.1. Therefore, L disappears completely from our estimates. However, in De£nition 3.3, we chose to work with the L^∞ topology. We therefore use the following bootstrap argument. From a bound in L^∞ at time t=0, we get a bound in weighted L^2 at time t=0. Using the next lemma we deduce a bound at t=1 in a weighted L^2 space on a strip of the complex plane. This is in turn combined with Lemma C.1 and provides an L^∞ bound at t=1.

Lemma 4.2 There is a constant b > 0 such that for any $\beta \in (-\alpha, \alpha)$, any N and L, the following bound holds on w a solution of (4.1) (or (4.2)) as long as $t \le 1$ (and $t/h \in \mathbb{N}$ in the case of a fully discrete scheme):

$$\sup_{|y| \le L\pi} \int \varphi(x-y) |w(x+i\beta t,t)|^2 dx \le e^{2bt} \sup_{|y| \le L\pi} \int \varphi(x-y) |w(x,0)|^2 dx. \tag{4.3}$$

The proof of Lemma 4.2 is given in Appendix A.

These L^2 norms shifted in the complex plane can be understood in terms of the classical Gevrey norms. Consider £rst $\varphi \equiv 1$. Then, using Fourier series and taking $\beta > 0$, we see that

$$\int (|f(x+2i\beta)|^2 + |f(x-2i\beta)|^2) dx = \left\| \Gamma e^{\beta(-\Delta)^{1/2}} f \right\|_2^2, \tag{4.4}$$

where Γ is the bounded invertible operator de£ned by

$$(\mathcal{T}(\Gamma f))_n = (1 + e^{-2\beta|n|/L})(\mathcal{T}f)_n.$$

This means that the left-hand side of (4.4) is equivalent to a Gevrey norm (similar norms have been used in [10, 11]). We apply a non-constant weight function φ to this norm in order to get estimates which are independent of L and take the sup over $|\beta| \le \alpha$ to be able to use Lemma C.1. Similar issues have been raised in the paper [20] but our approach is different in that we never explicitly work in Fourier space. We note also that the norms used in [20] grow with the domain size (due to the embedding constant), a problem we avoid here by using the cutoff φ .

4.2 Proof of the Upper Bound

We next show that the ε -entropy H_{ε} (De£nition 3.3) is of order $\log \varepsilon^{-1}$ at most.

Theorem 4.3 There exists a constant $C < \infty$, independent of ε such that

$$H_{\varepsilon} \leq C \log \left(\frac{R}{\varepsilon}\right) ,$$

where R is the radius of the absorbing ball $\widehat{B}(L)$ in Assumption 3.1.

The proof is based the following Lemma:

Lemma 4.4 There is a constant C > 0 such that for all $\varepsilon > 0$, the following holds:

$$H_{\varepsilon} \leq H_{2\varepsilon} + C$$
.

Proof. The proof is a consequence of the smoothness result of the previous section. We give the proof for the time continuous cases (1.1), (2.3). The time discrete case (2.5) is similar, it only requires restricting t to multiples of t.

Suppose we are given a 2ε -cover $\{U_1,\ldots,U_N\}$ of $\widehat{\mathcal{A}}(L)$. Then by invariance of $\widehat{\mathcal{A}}$ the set

$$\{\widehat{\Phi}^t(U_1),\ldots,\widehat{\Phi}^t(U_{\mathcal{N}})\}$$

is a cover of $\widehat{\mathcal{A}}(L)$ for all t>0. Moreover, if $u,v\in U_1$, by Lemma C.1 combined with Lemma 4.2, we have

$$\sup_{|x| \le L\pi, \, 2|y| \le \alpha} |(\widehat{\Phi}^1(u) - \widehat{\Phi}^1(v))(x+iy)| \le C\varepsilon.$$

That is, if we let $w = \widehat{\Phi}^1(u) - \widehat{\Phi}^1(v)$, then $w \in [\mathcal{G}_{\alpha/2}(C\varepsilon)]^2$ with C independent of L and ε .

We now use an argument due to Tikhomirov [28], discussed in [14], $\S 8$, Theorem XXII. By Proposition D.2 w can be written as

$$w(z) = \sum_{n \in \mathbb{Z}^d} e^{-\alpha |n|/2} e^{in \cdot z} w_n(z) , \qquad (4.5)$$

with w_n in the Bernstein class $[\mathcal{B}_2(C'\varepsilon)]^2$ (see Appendix D for the de£nition of \mathcal{B}_2). Thus, splitting the sum in (4.5) in two, we can £nd a K independent of ε and K and a K independent of K and K independent of K independent of K and K independent of K

$$||w - \widetilde{w}||_{\infty} \le \frac{\varepsilon}{2}$$
.

If $\widetilde{w} \in [\mathcal{B}_K(C\varepsilon)]^2$, then by Proposition D.3,

$$\widetilde{w}(x) = \sum_{n \in \mathbb{Z}^d} \widetilde{w}(x_K(n)) \mathcal{F}_K(x - x_K(n)),$$

hence there is a $\delta>0$ depending only on K such that $\|\widetilde{w}\|_{\infty}\leq \varepsilon/2$ if $|\widetilde{w}(x_K(n))|\leq \delta\varepsilon$ for all $n\in\mathbb{Z}^d$ for which $x_K(n)=(n\pi)/(3K)\in [-L\pi,L\pi]^d$. There are $c(K)(2L\pi)^d$ such points, hence at most

$$\left(\frac{C\varepsilon}{\delta\varepsilon}\right)^{c(K)(2L\pi)^d} =: C_*^{(2L\pi)^d}$$

balls of radius $\varepsilon/2$ will be needed to cover $[\mathcal{B}_K(C\varepsilon)]^2$. This covers all the functions \widetilde{w} obtained from the set $\widehat{\Phi}^1(U_1)$ by the above construction. Consequently, $\widehat{\Phi}^1(U_1)$ can be covered with the same number of balls of diameter ε .

Repeating the operation with each one of the $\mathcal{N}(2\varepsilon, \widehat{\mathcal{A}}(L))$ sets of diameter 2ε of the original cover $\{U_1, \ldots, U_{\mathcal{N}}\}$, we obtain a cover with at most

$$\mathcal{N}(\varepsilon, \widehat{\mathcal{A}}(L)) \leq \mathcal{N}(2\varepsilon, \widehat{\mathcal{A}}(L)) C_*^{(2L\pi)^d}$$

elements. Taking the logarithm, dividing by $(2L\pi)^d$ and passing to the limit $L \to \infty$, we obtain Lemma 4.4.

Proof of Theorem 4.3. It trivially holds that $H_R = 0$, because $\mathcal{N}(R, \widehat{\mathcal{A}}(L)) = 1$ by Assumption 3.1. Let k be the smallest integer larger than $\log(R/\varepsilon)/\log 2$, then by Lemma 4.4 we have

$$H_{\varepsilon} \leq H_{2\varepsilon} + C \leq \cdots \leq H_{2^k \varepsilon} + Ck \leq C' \log R/\varepsilon$$
.

This proves Theorem 4.3

5 The Topological Entropy

5.1 Upper Bound by the Dimension

In this section, we prove that the topological entropy of the attractors \widehat{A} is bounded by a multiple of the upper density of dimension, a quantity related to the ε -entropy. The corresponding inequality for £nite dimensional dynamical systems is well-known, see [13].

Theorem 5.1 *There is a* $b < \infty$ *such that*

$$h_{\rm top} \le b d_{\rm up} < \infty$$
 (5.1)

Proof. The right-hand inequality is a direct consequence of Theorem 4.3. The left-hand inequality follows from the arguments in [4, 13] that we summarise here. Let $\rho > 0$ be such that $H_{\varepsilon} \leq (d_{\rm up} + \rho) \log 1/\varepsilon$ for all $\varepsilon < \varepsilon_0$ and then let $L_0 = L_0(\varepsilon, \rho)$ be such that for all $L > L_0$,

$$\frac{\log \mathcal{N}(\varepsilon, \widehat{\mathcal{A}}(L))}{(2L\pi)^d} \le H_{\varepsilon} + \rho \le (d_{\rm up} + \rho) \log \frac{1}{\varepsilon} + \rho.$$

By iterating Lemma C.1 and Lemma 4.2, there is a b>0 such that for all L and all (sufficiently small) $\varepsilon>0$, if $||u-v||_{\infty}\leq \varepsilon$ then for t>0,

$$\|\widehat{\Phi}^t(u) - \widehat{\Phi}^t(v)\|_{\infty} \le e^{bt}\varepsilon$$
.

Let $\varepsilon' = \exp(-bT)\varepsilon$. Let an ε' -cover of $\widehat{\mathcal{A}}(L)$ (in the sense of De£nition 3.3) be given. Then it is also a $(T/\tau, \varepsilon)$ -cover (in the sense of De£nition 3.4), hence

$$\mathcal{M}_{T/\tau,\tau}(\varepsilon,\widehat{\mathcal{A}}(L)) \leq \mathcal{N}(\varepsilon',\widehat{\mathcal{A}}(L))$$
.

It follows that

$$h_{\text{top}} = \limsup_{\varepsilon \to 0} \limsup_{L \to \infty} \frac{1}{(2L\pi)^d} \lim_{T \to \infty} \frac{1}{T} \log \mathcal{M}_{T/\tau,\tau}(\varepsilon, \widehat{\mathcal{A}}(L))$$

$$= \limsup_{\varepsilon \to 0} \limsup_{L \to \infty} \frac{1}{(2L\pi)^d} \inf_{T} \frac{1}{T} \log \mathcal{M}_{T/\tau,\tau}(\varepsilon, \widehat{\mathcal{A}}(L))$$

$$\leq \limsup_{\varepsilon \to 0} \limsup_{L \to \infty} \frac{1}{T} \frac{\log \mathcal{N}(\varepsilon', \widehat{\mathcal{A}}(L))}{(2L\pi)^d}$$

$$\leq \limsup_{\varepsilon \to 0} \limsup_{L \to \infty} \frac{1}{T} \left((d_{\text{up}} + \rho) \log \frac{1}{\varepsilon'} + \rho \right).$$

Since $\log 1/\varepsilon' = bT + \log 1/\varepsilon$, the limit $T \to \infty$ and $\rho \to 0$ leaves only $bd_{\rm up}$ on the r.h.s. above.

5.2 Lower Bound by the Expansion Rate

We provide here a way of computing a lower bound on the topological entropy (hence on the upper dimension $d_{\rm up}$ by Theorem 5.1), based on Yomdin's Theorem, an account of which may be found in [21].

Theorem 5.2 Let h_{top} be as in De£nition 3.4. Then for all choices of $\mathcal{D}(L)$ in De£nition 3.5,

$$V \leq h_{\text{top}}$$
.

Remark. The lower bound in [5] is in the same spirit. An adequate sequence of sub-manifolds is chosen (small balls around the trivial solution). The volume expansion rate of that sequence can be controlled, yielding a lower bound on the $(\varepsilon$ -)entropy.

Proof. The proof follows from the argument by Yomdin and Gromov. By a Lemma of Gromov, there exists a C>0 such that if $\widehat{\Phi}^{\tau}$ is \mathcal{C}^{r} , then

$$\operatorname{Vol}_{\ell}(\widehat{\Phi}^{m\tau}(\mathcal{D}(L))) \leq \mathcal{M}_{m,\tau}(\varepsilon,\widehat{\mathcal{A}}(L))(C||D\widehat{\Phi}^{\tau}||_{\infty})^{m\ell/r},$$

hence

$$\limsup_{L \to \infty} \frac{1}{(2L\pi)^d} \limsup_{m \to \infty} \frac{1}{m\tau} \log \operatorname{Vol}_{\ell}(\widehat{\Phi}^{m\tau}(\mathcal{D}(L)))$$

$$\leq \limsup_{L \to \infty} \frac{1}{(2L\pi)^d} \limsup_{m \to \infty} \frac{1}{m\tau} \log \mathcal{M}_{m,\tau}(\varepsilon, \widehat{\mathcal{A}}(L)) + \limsup_{L \to \infty} \frac{\ell/r}{(2L\pi)^d} \log \left(C^{1/\tau} \|D\widehat{\Phi}^{\tau}\|_{\infty}^{1/\tau}\right).$$

Since τ can be arbitrarily large, the constant C drops out, and since $\widehat{\Phi}^{\tau}$ is \mathcal{C}^{∞} , the second term is arbitrarily small by letting $r \to \infty$. The £rst term tends to h_{top} upon letting $\varepsilon \to 0$.

6 Upper Semicontinuity of the In£nite Volume Attractors

In this section we discuss four different invariant sets and their mutual relationship. The £rst two invariant sets are $A_{N,h}(L)$ and A(L) from De£nition 3.2. Then we also introduce two large volume limits:

$$\mathcal{A}_{N,h}(\infty) \,:=\, \overline{igcup_{L\in\mathbb{N}} \mathcal{A}_{N,h}(L)}\,, \qquad \mathcal{A}(\infty) \,:=\, \overline{igcup_{L\in\mathbb{N}} \mathcal{A}(L)}\,,$$

where the closure is taken in the uniformly local topology of [18]. We de£ne the distance between a point and a set and between two sets in the standard way

$$\operatorname{dist}(U, \mathcal{V}) := \inf_{V \in \mathcal{V}} \|U - V\|_{L^{\infty}([-L\pi, L\pi]^d)},$$

$$\operatorname{dist}(\mathcal{U}, \mathcal{V}) := \sup_{U \in \mathcal{U}} \operatorname{dist}(U, \mathcal{V}).$$

We claim that

$$\lim_{N \to \infty, h \to 0} \operatorname{dist}(\mathcal{A}_{N,h}(L), \mathcal{A}(L)) = 0, \lim_{N \to \infty, h \to 0} \operatorname{dist}(\mathcal{A}_{N,h}(\infty), \mathcal{A}(\infty)) = 0, \tag{6.1}$$

and the following relations are straightforward

$$\lim_{L \to \infty} \operatorname{dist} (\mathcal{A}_{N,h}(L), \mathcal{A}_{N,h}(\infty)) = 0,$$

$$\lim_{L \to \infty} \operatorname{dist} (\mathcal{A}(L), \mathcal{A}(\infty)) = 0.$$

Hence we obtain the following diagram, in which each arrow represents a relation of upper semi-continuity:

$$\begin{array}{c|c}
\mathcal{A}_{N,h}(L) \xrightarrow{N \to \infty} \mathcal{A}(L) \\
\downarrow_{L \to \infty} & \downarrow_{L \to \infty} \\
\mathcal{A}_{N,h}(\infty) \xrightarrow[h \to 0]{N \to \infty} \mathcal{A}(\infty) .
\end{array}$$

The relation (6.1) is a consequence of the following (see e.g. [12, 16, 18, 19]).

Theorem 6.1 For all $\varepsilon > 0$, there is a T_1 , an h_1 and an N_1 such that if $h < h_1$ and $N > N_1$, then for all $L \in \mathbb{N}$

$$\Phi_{L,N,h}^T(B_{N,h}(L)) \subset \mathcal{U}_{\varepsilon}(\mathcal{A}(L)) \qquad \forall T > T_1 ,$$

where $\mathcal{U}_{\varepsilon}(\mathcal{A}(L))$ is the ε -neighbourhood of $\mathcal{A}(L)$ in L^{∞} .

Proof. The proof is by induction using the attracting property of the attractor and a £nite time error estimate.

By the attraction property of A(L), there exists a T such that $\forall T > T_1$

$$\Phi_L^T(B(L) \cup B_{N,h}(L)) \subset \mathcal{U}_{\varepsilon/2}(\mathcal{A}(L))$$
,

for all $L \in \mathbb{N}$. Hence for any $u_0 \in B_{N,h}(L)$ we have

$$\operatorname{dist}(\Phi_{L,N,h}^{nh}(u_{0}),\mathcal{A}(L)) = \inf_{u \in \mathcal{A}(L)} \|\Phi_{L,N,h}^{nh}(u_{0}) - u\|_{\infty}$$

$$\leq \inf_{u \in \mathcal{A}(L)} \|\Phi_{L}^{nh}(u_{0}) - u\|_{\infty} + \|\Phi_{L,N,h}^{nh}(u_{0}) - \Phi_{L}^{nh}(u_{0})\|_{\infty}$$

$$\leq \frac{\varepsilon}{2} + \|\Phi_{L,N,h}^{nh}(u_{0}) - \Phi_{L}^{nh}(u_{0})\|_{\infty}, \qquad (6.2)$$

provided nh > T.

We next show that N, h can be chosen in such a way that the second term above is smaller than $\varepsilon/2$ for $T \in (0, 2T_1]$.

Let $v(t) = \Phi_L^t(u_0)$ and $w(nh+s) = \Phi_{\text{Lin}}^s \Phi_{L,N,h}^{nh}(u_0)$ where Φ_{Lin}^s is the solution semi- π ow of (2.6). We thus have for s < h

$$\partial_t \big(v(nh+s) - w(nh+s) \big) =$$

$$\big(\gamma + \nu \Delta \big) \big(v(nh+s) - w(nh+s) \big) + \mathcal{P}^N \Big(F \big(v(nh+s) \big) - F \big(w(nh+s) \big) \Big)$$

$$+ \mathcal{P}^N \Big(F \big(w(nh+s) \big) - F \big(w(nh) \big) \Big) + \mathcal{Q}^N F \big(v(nh+s) \big) .$$

Using Proposition D.2 we see that

$$\sup_{s < h} \| \mathcal{Q}^N F(v(nh+s)) \|_{\infty} \le C(R)e^{-N} ,$$

and similarly (see [26]) that

$$\sup_{s \le h} \left\| P^N \left(F \big(w(nh+s) \big) - F \big(w(nh) \big) \right) \right\|_{\infty} \le C(R) \sqrt{h} ,$$

where R is the radius of the absorbing ball. Hence, using the same analysis as in the proof of Lemma 4.2, we obtain

$$||v((n+1)h) - w((n+1)h)||_{\infty} \le e^{ch}||v(nh) - w(nh)||_{\infty} + C(R)(h^{3/2} + e^{-N}h).$$

By iteration, this gives

$$||v(nh) - w(nh)||_{\infty} \le e^{cnh} ||v(0) - w(0)||_{\infty} + C(R)e^{cnh} (h^{3/2} + e^{-N}h). \tag{6.3}$$

Taking N large enough and h small enough, we can make the second term of (6.2) smaller than $\varepsilon/2$ for $T \in (0, 2T_1]$.

To complete the induction we note that the absorbing ball is positively invariant and so we can repeat the argument for $T > 2T_1$.

7 Discussion: The Complex Ginzburg-Landau Equation

An interesting example to which our results apply is the (cubic) complex Ginzburg-Landau equation in d=1 space dimension

$$\partial_t u(x,t) = (1+ia)\partial_x^2 u(x,t) + u(x,t) - (1+ib)|u(x,t)|^2 u(x,t)$$
.

In terms of the notations of (1.1), this means:

$$d = 1$$
, $\nu = 1 + ia$, $\gamma = 1$, $F(u) = -(1 + ib)|u|^2u$.

The equation for the difference w = u - v of two solutions u and v that we use in Section 4.1 admits a simple expression:

$$\partial_t w(x,t) = (1+ia)\partial_x^2 w(x,t) + w(x,t) + \int \xi_N(x-y) \Big(G_1(y,t)w(y,t) + G_2(y,t)\overline{w}(y,t) \Big) dy ,$$

where

$$G_1(x,t) = -(1+ib)(|u(x,t)|^2 + |v(x,t|^2), \qquad G_2(x,t) = -(1+ib)u(x,t)v(x,t).$$

Assumption 3.1 for the continuous case follows from the works [2, 1, 25]. Remark that these papers deal with the equation on the whole space without boundary conditions, but their results obviously remain true on the set of spatially periodic solutions, which is invariant under the time evolution.

The time discretisation of the scheme was considered in [26] on a £xed length interval. Although there is no formal proof of existence of a semi-¤ow and global attractor for the modi£ed Galerkin scheme considered here, this can be seen to be true. By iterating the error bound 6.3 and the uniform bounds proved in [2] for £nite time intervals, we obtain existence of a global semi-¤ow. The existence of the absorbing balls of Assumption 3.1 follows from Appendix B.

A Proof of Lemma 4.2

We £rst consider the time-continuous case (4.1). We write the analytic extension of w as a vector valued function with components w_r and w_i (each of which is complex-valued) and its complex argument x + iy is also written as a vector of reals. Namely

$$w(x+iy,t) = (w_{\mathbf{r}}(x,y;t), w_{\mathbf{i}}(x,y;t)).$$

As a preparation for the proof, we estimate the following expression:

$$\operatorname{Re} \nu \int \varphi(x) \Big(\overline{w}_{r}(x, y; t) \Delta_{x} w_{r}(x, y; t) + \overline{w}_{i}(x, y; t) \Delta_{x} w_{i}(x, y; t) \Big) dx$$

$$+ \operatorname{Re} i\beta \int \varphi(x) \Big(\overline{w}_{r}(x, y; t) \nabla_{y} w_{r}(x, y; t) + \overline{w}_{i}(x, y; t) \nabla_{y} w_{i}(x, y; t) \Big) dx$$
(A.1)

By using the Cauchy–Riemann equations ($|\nabla_y u_{\mathrm{r,i}}| = |\nabla_x u_{\mathrm{r,i}}|$), we obtain:

$$\operatorname{Re} \nu \int \varphi \left(\overline{w}_{r} \Delta_{x} w_{r} + \overline{w}_{i} \Delta_{x} w_{i} \right) dx + \operatorname{Re} i\beta \int \varphi \left(\overline{w}_{r} \nabla_{y} w_{r} + \overline{w}_{i} \nabla_{y} w_{i} \right) dx$$

$$= -\operatorname{Re} \nu \int \varphi \left(|\nabla_{x} w_{r}|^{2} + |\nabla_{x} w_{i}|^{2} \right) dx - \operatorname{Re} \nu \int \nabla_{x} \varphi \left(\overline{w}_{r} \nabla_{x} w_{r} + \overline{w}_{i} \nabla_{x} w_{i} \right) dx$$

$$+ \operatorname{Re} i\beta \int \varphi \left(\overline{w}_{r} \nabla_{y} w_{r} + \overline{w}_{i} \nabla_{y} w_{i} \right) dx$$

$$\leq -\operatorname{Re} \nu \int \varphi \left(|\nabla_{x} w_{r}|^{2} + |\nabla_{x} w_{i}|^{2} \right) dx + |\nu| \left\| \frac{\nabla \varphi}{\varphi} \right\|_{\infty} \int \varphi \left(|w_{r}| |\nabla_{x} w_{r}| + |w_{i}| |\nabla_{x} w_{i}| \right) dx$$

$$+ |\beta| \int \varphi \left(|w_{r}| |\nabla_{x} w_{r}| + |w_{i}| |\nabla_{x} w_{i}| \right) dx$$

$$\leq \frac{|\beta|^{2} + |\nu|^{2} ||\nabla \varphi / \varphi||_{\infty}^{2}}{2\operatorname{Re} \nu} \int \varphi \left(|w_{r}|^{2} + |w_{i}|^{2} \right) dx$$

$$=: b_{0} \int \varphi \left(|w_{r}|^{2} + |w_{i}|^{2} \right) dx . \tag{A.2}$$

De£ne

$$\varphi_y(x) := \varphi(x-y), \qquad \xi_y^*(x) := \xi_N(x-y),$$

where φ and ξ_N are as in De£nitions 1.1–1.2. We next compute the time-derivative of the left-hand side of (4.3). The expression (A.1) is the linear part of the time-derivative, hence we simply insert the bound (A.2) and compute the non-linear part:

$$\frac{1}{2}\partial_t \sup_y \int \varphi_y(x)|w(x+i\beta t,t)|^2 dx \leq \frac{1}{2}\sup_y \partial_t \int \varphi_y(x)|w(x+i\beta t,t)|^2 dx$$

$$\leq (\gamma + b_0) \sup_y \int \varphi_y(x)|w(x+i\beta t,t)|^2 dx$$

$$+\operatorname{Re}\sup_{y} \left| \int \varphi_{y}(x)\overline{w}(x+i\beta t,t) \right|$$

$$\times \left(\int \xi_{x}^{*}(z) \left(G_{1}(z+i\beta t,t)\overline{w}(z+i\beta t,t) + G_{2}(z+i\beta t,t)w(z+i\beta t,t) \right) dz \right) dx \right|$$

$$\leq \left(\gamma + b_{0} \right) \sup_{y} \int \varphi_{y}(x) |w(x+i\beta t,t)|^{2} dx$$

$$+ \sup_{y} \int \varphi_{y}(x) |w(x+i\beta t,t)|$$

$$\times \left(\int \frac{|\xi_{x}^{*}(z)|}{\sqrt{\varphi_{x}(z)}} \sqrt{\varphi_{x}(z)} \left(|G_{1}(z+i\beta t,t)| + |G_{2}(z+i\beta t,t)| \right) |w(z+i\beta t,t)| dz \right) dx .$$

At this point, we apply the Cauchy–Schwarz Inequality to each of the two integrals on the right-hand side. Using Lemma 4.1 we know that

$$\sup_{|\beta| \le \alpha} \sup_{x \le \mathbb{R}^d} \left(|G_1(x+i\beta,t)| + |G_2(x+i\beta,t)| \right) \le 2R.$$

This gives

$$\frac{1}{2}\partial_{t}\sup_{y}\int\varphi_{y}(x)|w(x+i\beta t,t)|^{2}dx \leq (\gamma+b_{0})\sup_{y}\int\varphi_{y}(x)|w(x+i\beta t,t)|^{2}dx
+\sup_{y}\left(\int\varphi_{y}(x)|w(x+i\beta t,t)|^{2}dx\right)^{1/2}\left(\int\varphi(x)dx\int\frac{\xi_{N}^{2}(z)}{\varphi(z)}dz\right)^{1/2}
\times 2R\left(\sup_{x}\int\varphi_{x}(z)|w(z+i\beta t,t)|^{2}dz\right)^{1/2}
\leq \left(\gamma+b_{0}+2R\left(\int\frac{\xi_{N}^{2}}{\varphi}\right)^{1/2}\right)\sup_{y}\int\varphi_{y}(x)|w(x+i\beta t,t)|^{2}dx
=: b\sup_{y}\int\varphi_{y}(x)|w(x+i\beta t,t)|^{2}dx,$$

where we used that by De£nition 1.1, $\int \xi_N^2/\varphi < \infty$ because ξ_N^2 is a Schwartz function and $1/\varphi$ a Schwartz distribution. Equation (4.3) now follows from Gronwall's Lemma.

In the discrete case, we solve the linear differential equation (see (2.6))

$$\partial_t w(nh+t) = (\gamma + \nu \Delta) w(nh+t) + \xi_N \star (G_1(nh)w(nh) + G_2(nh)\overline{w}(nh))$$

for $t \in [0, h)$, and then we iterate for n = 0 to n = [1/h] + 1. Over one time-step, the same calculations as in the continuous case give

$$\sup_{|y| \le L\pi} \int \varphi(x-y) |w(x+i\beta(n+1)h, (n+1)h)|^2 dx$$

$$\le e^{2bh} \sup_{|y| \le L\pi} \int \varphi(x-y) |w(x+i\beta nh, nh)|^2 dx,$$

hence by iteration

$$\sup_{|y| \le L\pi} \int \varphi(x-y) |w(x+i\beta nh, nh)|^2 dx \le e^{2bnh} \sup_{|y| \le L\pi} \int \varphi(x-y) |w(x,0)|^2 dx.$$

This completes the proof of Lemma 4.2.

B Analyticity for the Fully Discrete Scheme

The full discretisation discussed in Section 2.2 was introduced in [26] where Gevrey regularity is proved. We give here another simple and direct proof that the semi-group generated by (2.5) maps into $\mathcal{G}_{\alpha}(C)$ (see Appendix D) for some α and C independent of N and L. Our proof is in the spirit of Collet [1] or Taká \hat{e} et al. [25]. We assume that the solution u(x, nh) of (2.5) has reached an absorbing ball in L^{∞} , hence there is an R > 0 such that $||u(nh)||_{\infty} \leq R$ irrespective of u_0 and n. We then use a contraction argument to show that for small T, for $nh \in [0, T]$, there is a unique solution to (2.5) in the metric space of functions satisfying $|||u||| \leq R$, where

$$|||f||| = \max_{nh \in [0,T]} \sup_{|x| \le L\pi} |f(x + i\sqrt{nh}, nh)|.$$

Remark that if T < h, there is nothing to prove (the solutions are entire functions anyway). The purpose of this section is to provide bounds on the radius of analyticity which are independent of h and N, hence we may assume h to be small.

We seek a solution to the equation $u(nh) = \mathcal{Y}(u, u_0)(nh)$ with \mathcal{Y} de£ned by

$$\mathcal{Y}(f, f_0)(nh) = \mathcal{K}(nh) \star f_0 - \sum_{j=0}^{n-1} \left(\int_0^1 h \mathcal{P}^N \mathcal{K}(h(n-j-s)) ds \right) \star F(f(jh)) \right),$$

where K is given by (2.4).

It is easy to see that for small T > 0, $\mathcal{Y}(\cdot, f_0)$ is a contraction:

$$\begin{aligned} & \left| \mathcal{Y}(f, f_0)(x + i\sqrt{nh}, nh) - \mathcal{Y}(g, f_0)(x + i\sqrt{nh}, nh) \right| \\ & \leq \sum_{j=0}^{n-1} \int_0^1 \int h |\mathcal{P}^N \mathcal{K}(y - z + i(\sqrt{nh} - \sqrt{jh}), h(n - j - s))| \, ds \\ & \times \left| F(f(z + i\sqrt{jh}, jh)) - F(g(z + i\sqrt{jh}, jh)) \right| dz \\ & \leq \operatorname{Lip}(F, R) \left\| \left\| f - g \right\| \sum_{j=0}^{[T/h]+1} \int_0^1 \int h |\mathcal{P}^N \mathcal{K}(x + i(\sqrt{nh} - \sqrt{jh}), h(n - j - s))| \, ds \, dx \end{aligned}$$

(here $\operatorname{Lip}(F,R)$ is the Lipschitz constant of F in the ball of radius R) hence by taking T small enough (depending on $\operatorname{Lip}(F,R)$ only) the solution to the £xed point problem exists and is unique. Since u belongs to an absorbing ball of L^{∞} , the argument can be iterated inde£nitely, hence u is analytic for all times thereafter.

C Uniform Bounds on Complex Analytic Functions

In this section we show that an L^p bound in a strip of the complex plane provides an L^{∞} bound in a smaller strip.

Lemma C.1 Let $p \ge 1$. There is a constant $C = C(\varphi, \delta)$ such that any function f analytic in $|\operatorname{Im}(x)| \le \delta$ satisfies:

$$|f(y+iz)|^p \le C \sup_{|\gamma| \le \delta} \int \varphi(x-y) |f(x+i\gamma)|^p dx$$

for all $y \in \mathbb{R}^d$ and $|z| \leq \delta/2$.

Proof. We take y=0 and $\delta=1$ for simplicity. The general case is obtained by translation and scaling. Since analytic functions are harmonic the following Mean Value Property holds (see [15]). Let \mathcal{D} be the unit ball centred at 0 in the n-dimensional complex space, then

$$f(0) = \frac{1}{\operatorname{Vol}(\mathcal{D})} \int_{\mathcal{D}} f(x+i\gamma) \, dx \, d\gamma$$
.

We apply Jensen's inequality and use that there is a C for which

$$\inf_{|x| \le 1} C\varphi(x) \ge 1$$

(see De£nition 1.1), to obtain

$$|f(0)|^{p} \leq \frac{1}{\operatorname{Vol}(\mathcal{D})} \int_{\mathcal{D}} |f(x+i\gamma)|^{p} dx d\gamma$$

$$\leq \frac{1}{\operatorname{Vol}(\mathcal{D})} \sup_{|\gamma| \leq 1} \int_{|x| \leq 1} |f(x+i\gamma)|^{p} dx$$

$$\leq \frac{C}{\operatorname{Vol}(\mathcal{D})} \sup_{|\gamma| \leq 1} \int \varphi(x) |f(x+i\gamma)|^{p} dx.$$

D Gevrey and Bernstein Classes of Analytic Functions

We introduce here the metric spaces $\mathcal{B}_{\sigma}(C)$ (the Bernstein class) and $\mathcal{G}_{\alpha}(C)$ (the Gevrey class) and recall two properties of functions belonging to these spaces (see [7, 14, 17] for details).

De£nition D.1 The Bernstein class $\mathcal{B}_{\sigma}(C)$ is the set of all functions f having an analytic extension to the whole of \mathbb{C}^d with exponential growth along the imaginary directions:

$$|f(x+iy)| \le Ce^{\sigma|y|}, \forall (x,y) \in \mathbb{R}^d \times \mathbb{R}^d.$$

The Gevrey class $\mathcal{G}_{\alpha}(C)$ is the set of all functions f admitting an analytic extension to a strip of width 2α around the real axes and which are uniformly bounded in this strip:

$$|f(x+iy)| \le C, \forall (x,y) \in \mathbb{R}^d \times [-\alpha, \alpha]^d.$$

The £rst result states that any function in $\mathcal{G}_{\alpha}(C)$ can be written as a sum of entire functions:

Proposition D.2 Let $f \in \mathcal{G}_{\alpha}(C)$. Then there exists a C' depending on C only such that

$$f(z) = \sum_{n \in \mathbb{Z}^d} e^{-\alpha|n|} e^{in \cdot z} f_n(z) ,$$

with $f_n \in \mathcal{B}_2(C')$.

The second result is a classical sampling formula (see [7] or [14] where it is called the Cartwright formula).

Proposition D.3 For all $f \in \mathcal{B}_{\sigma}(C)$, the following identity holds:

$$f(z) = \sum_{n \in \mathbb{Z}^d} f(x_{\sigma}(n)) \mathcal{F}_{\sigma}(z - x_{\sigma}(n)),$$

where

$$x_{\sigma}(n) = \frac{n\pi}{3\sigma}, \qquad \mathcal{F}_{\sigma}(x) = \frac{\sin(3\sigma x)\sin(\sigma x)}{3\sigma^2 x^2}.$$

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