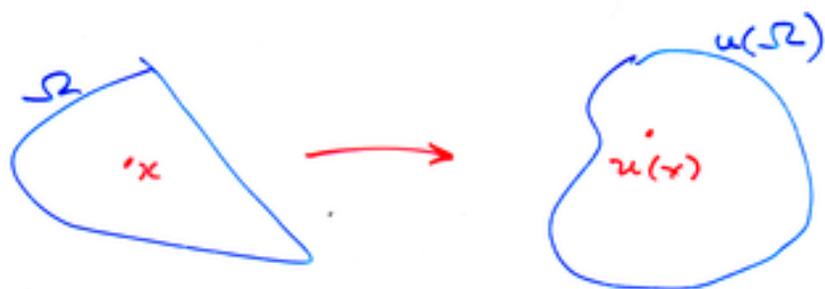


Statistical mechanics
of nonlinear elasticity
for a hard-disk system

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Principles of nonlinear elasticity



Minimize $\int_{\Omega} f(\nabla u(x)) d^3x$

↑ "deformation matrix"

↑ "stored energy function"

$$\text{Euler-Lagrange } \sum_j \frac{\partial t_{ij}}{\partial x_j} = 0$$

$$\text{Stress tensor } t_{ij} := \frac{\partial f}{\partial \left(\frac{\partial u_i}{\partial x_j} \right)}$$

Constitutive relation

$$f = f\left(\dots, \frac{\partial u_i}{\partial x_j}, \dots\right)$$

Quasi-convexity (a desirable property of f)

"if $\nabla u = A = \text{const on } \partial\Omega$
then the minimizer has $\nabla u = A$ within Ω "

Morrey's theorem (1952):

QC + continuity \Rightarrow variational problem is solvable

The "unconstrained" partition function

partition function

$$Z := \frac{1}{N!} \int \dots \int e^{-H/kT} dp_1 \dots dq_{2N}$$

← Hamiltonian
← temperature

$$= \frac{(2\pi mkT)^N}{N!} \int \dots \int e^{-W/kT} dq_1 \dots dq_{2N}$$

← potential energy

$$Q := \frac{1}{N!} \int \dots \int e^{-W/kT} dq_1 \dots dq_{2N}$$

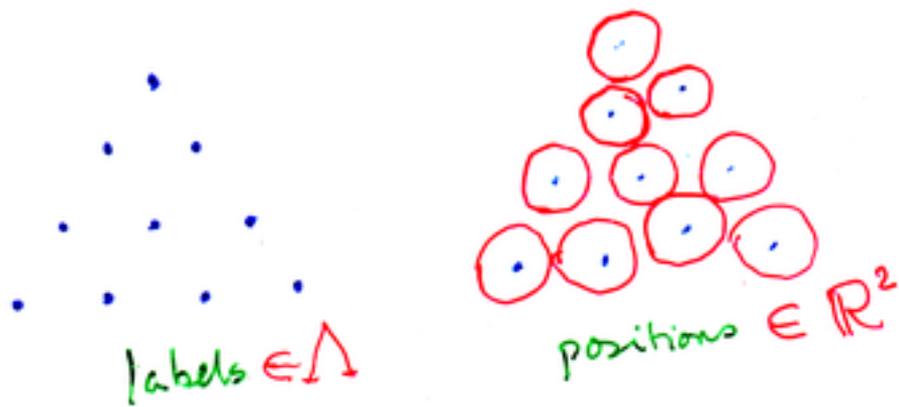
← configurational integral

$$= \frac{1}{N!} \int \dots \int \chi_{hc}(q_1 \dots q_N) \chi_{wall}(q_1 \dots q_N) dq_1 \dots dq_N$$

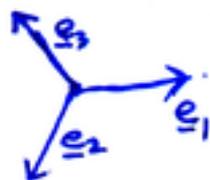
$$\chi_{hc} := \begin{cases} 1 & \text{if no disks overlap} \\ 0 & \text{otherwise} \end{cases}$$

$$\chi_{wall} := \begin{cases} 1 & \text{if all disks are inside container} \\ 0 & \text{otherwise} \end{cases}$$

The model: hard disks of diameter 1



Denote the set of possible labels
 (a triangular lattice with spacing 1)
 by $\Lambda := i\mathbf{e}_1 - j\mathbf{e}_2 \quad (i, j \in \mathbb{Z})$



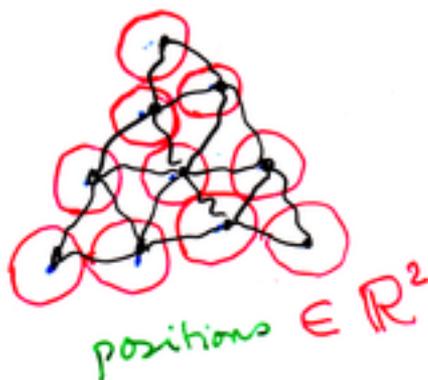
$$\mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\mathbf{e}_2 = \begin{bmatrix} -\frac{1}{2} \\ \frac{\sqrt{3}}{2} \end{bmatrix}$$

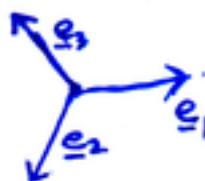
The particle whose label is $k \in \Lambda$
 has position \mathbf{x}_k

Hard-core constraint
 $|\mathbf{x}_k - \mathbf{x}_\ell| \geq 1$ if $k \neq \ell$

The model: hard disks of diameter 1



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The particle whose label is $k \in \Lambda$
has position \mathbf{x}_k

Hard-core constraint

$$|\mathbf{x}_k - \mathbf{x}_l| \geq 1 \text{ if } k \neq l$$

Network constraint

$$|\mathbf{x}_k - \mathbf{x}_l| \leq \sqrt{2} \text{ if } |k - l| = 1$$

\mathbf{x}_k
 \mathbf{x}_l

The constrained configurational integral

K any convex finite set in Δ

A any matrix in \mathcal{A}

The set of "allowed" deformation matrices is those with $1 < |A e_i| < \sqrt{2}$ ($i=1,2,3$)

δ any small positive number.

There are two types of constrained C.I.

(a) $\leftarrow a \in \{\text{loose, tight}\}$

$$Q_{\delta}^{(a)}(K, A) := \int_{\mathbb{R}^{2N}} d^{2N} \underline{x} \chi_{hc}(\underline{x}) \chi_{net}(\underline{x}) \chi_{anc}^{(a)}(\underline{x})$$

$\uparrow \underline{x} := \{x_k : k \in K\}$

$\chi_{hc} := 1$ if $|x_k - x_l| \geq 1$ whenever $k \neq l$, else 0

$\chi_{net} := 1$ if $|x_k - x_l| \leq \sqrt{2}$ whenever $|k-l|=1$, else 0

$\chi_{anc}^{(tight)} := 1$ if $|x_k - A e_k| \leq \delta$ whenever $k \in \partial K$, else 0

$\chi_{anc}^{(loose)} := 1$ if $|x_k - A e_k| \geq 1 + \delta$ whenever $k \in \partial K^c$
 AND $|x_k - A e_k| \leq \sqrt{2} - \delta$ whenever $k \in \partial K^c$ and $|k-l|=1$
 else 0

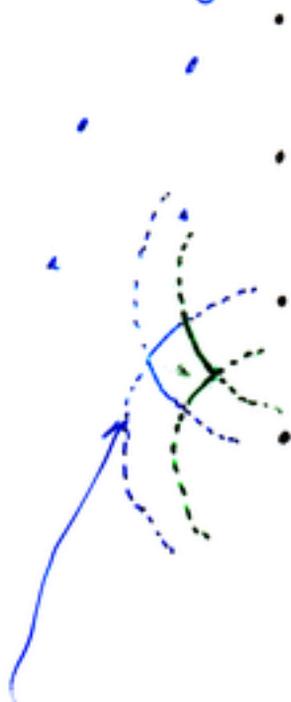
Tight Anchoring



The anchored particles
stay inside circles of
radius δ

anchor points
 $A_k: k \in J_K$

Loose Anchoring



The anchored particles

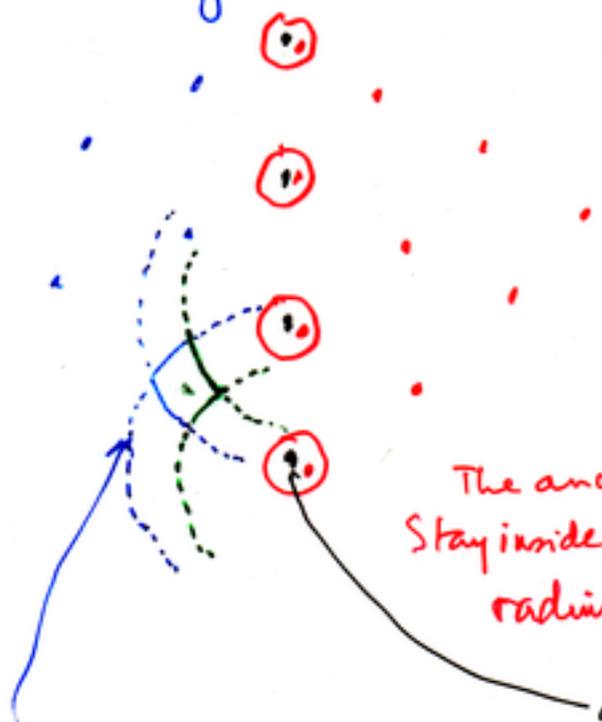
stay inside
circles of radius

$$\sqrt{2} - \delta$$

and outside
circles of
radius $1 + \delta$

Loose Anchoring

Tight Anchoring



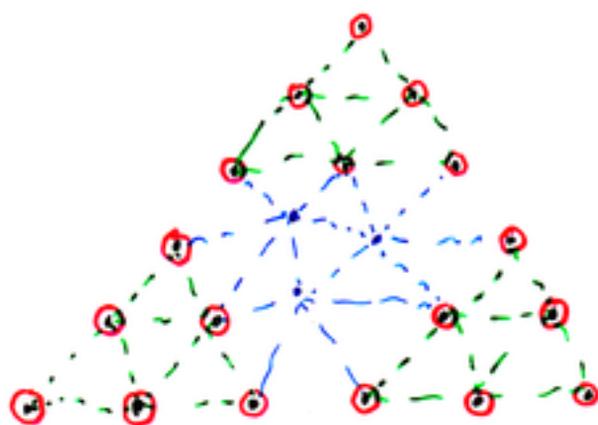
The anchored particles stay inside circles of radius δ

anchor points
 $A_k: k \in J$

The anchored particles stay inside circles of radius $\sqrt{2} - \delta$

and outside circles of radius $1 + \delta$

Idea behind proof of Theorem 2



$$[Q_\delta^t(\Delta_2)]^3 Q_\delta^l(\Delta_1) \leq Q_\delta^t(\Delta_5)$$

$$3 \log Q_\delta^t(\Delta_{2^{p-1}}) + \log Q_\delta^l(\Delta_{2^{p-2}}) \leq \log Q_\delta^t(\Delta_{2^{p+1}})$$

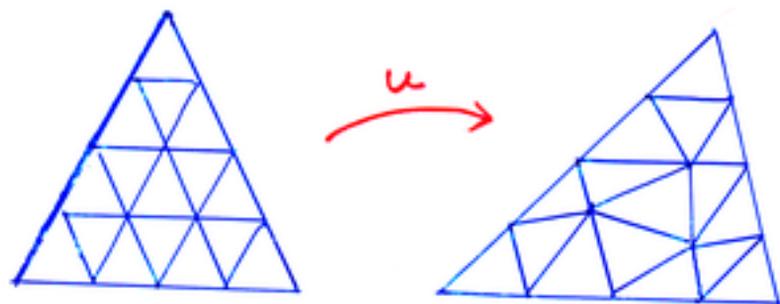
$$\frac{3}{4} \psi_\delta^t(p) + \frac{1}{4} \psi_\delta^l(p) \leq \psi_\delta^t(p+1)$$

$$\begin{array}{ccc} \uparrow & & \uparrow \\ 2^{-2p} \log Q^t(\Delta_{2^{p-1}}) & & 2^{-2p} \log Q^l(\Delta_{2^{p-2}}) \end{array}$$

$$\text{Also } \frac{3}{4} \psi_\delta^l(p) + \frac{1}{4} \psi_\delta^t(p) \leq \psi_\delta^l(p+1)$$

This sequence $\psi_\delta^l(p) + \psi_\delta^t(p)$ $p=1, 2, \dots$
is bounded & increasing $\therefore \rightarrow$ limit.

Theorem 3 (Triangulation inequality)



If A a matrix in \mathcal{A}

n a positive integer

$u(\cdot)$ a homeomorphism (continuous & invertible)

$\nabla u(x) = A$ for $x \in \Delta$

$\nabla u = \text{const}$ on each sub-triangle

Then

$$\sum_{\text{Sub-triangles } \mathbb{k}} \Psi(\nabla u(\mathbb{k})) \leq n^2 \Psi(A)$$

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Theorem 4 The function $\psi(\cdot)$
is Lipschitz continuous on any
compact convex subset of \mathcal{A}

ie. if \mathcal{B} is the subset & $A_1, A_2 \in \mathcal{B}$
then

$$|\psi(A_1) - \psi(A_2)| \leq K(\mathcal{B}) \|A_1 - A_2\|$$

Theorem 5: "Quasi Convexity" of $-\psi$



A is an allowed 2×2 matrix

$$\underline{u}(x) = Ax \quad \text{for } x \notin \Omega$$

$$\nabla \underline{u}(x) \in \mathcal{A} \quad \text{for } x \in \Omega$$

$\underline{u}(\cdot)$ is Lipschitz continuous
& so is its inverse

$$\text{i.e. } (1+\delta)|x-x'| < |u(x) - u(x')| < (\sqrt{2}-\delta)|x-x'|$$

$$\int_{\Omega} \bar{\Psi}(\nabla \underline{u}(x)) d^2x \geq \bar{\Psi}(A) \int_{\Omega} d^2x$$

where $\bar{\Psi} := -\psi = \frac{1}{kT} \times$ free energy
per particle
+ k.e. term